

Principles of Optical Interferometry

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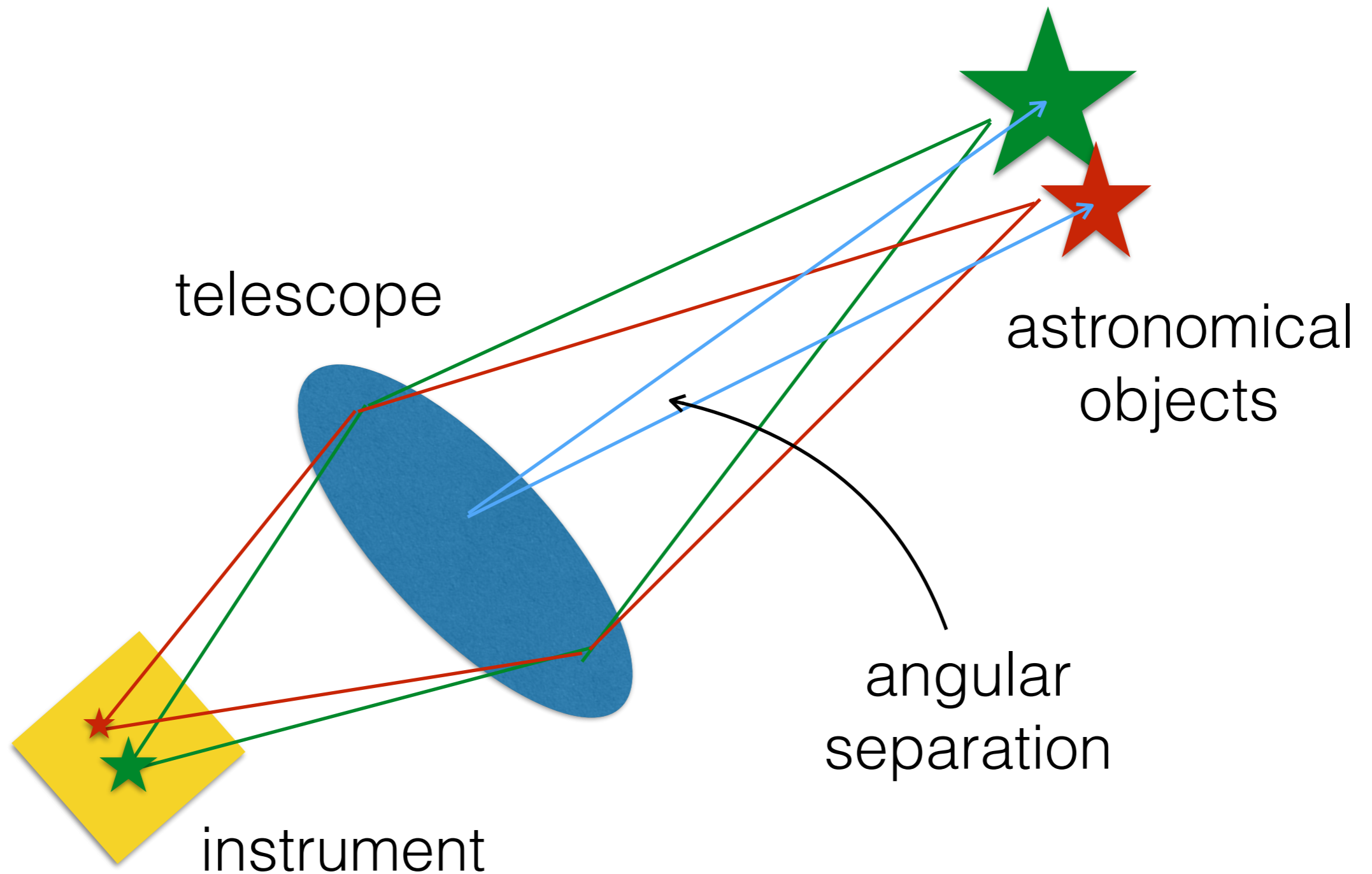
Garching - March 6th, 2017



The Need for Angular Resolution



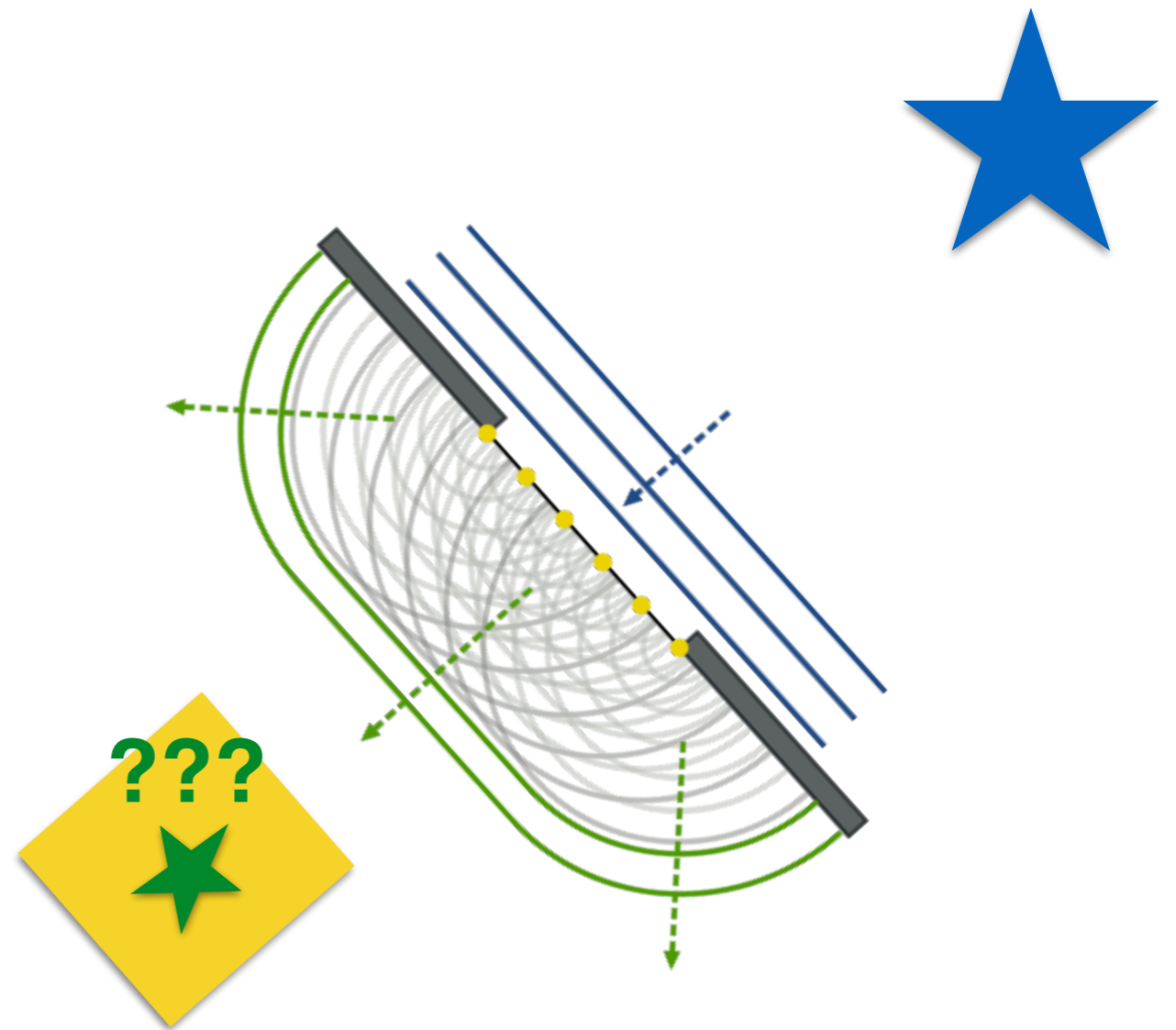
Angular resolution





Diffraction

- light as a wavefront
- each points of the aperture emits an hemispherical wave



illustrations from http://en.wikipedia.org/wiki/Huygens%E2%80%93Fresnel_principle





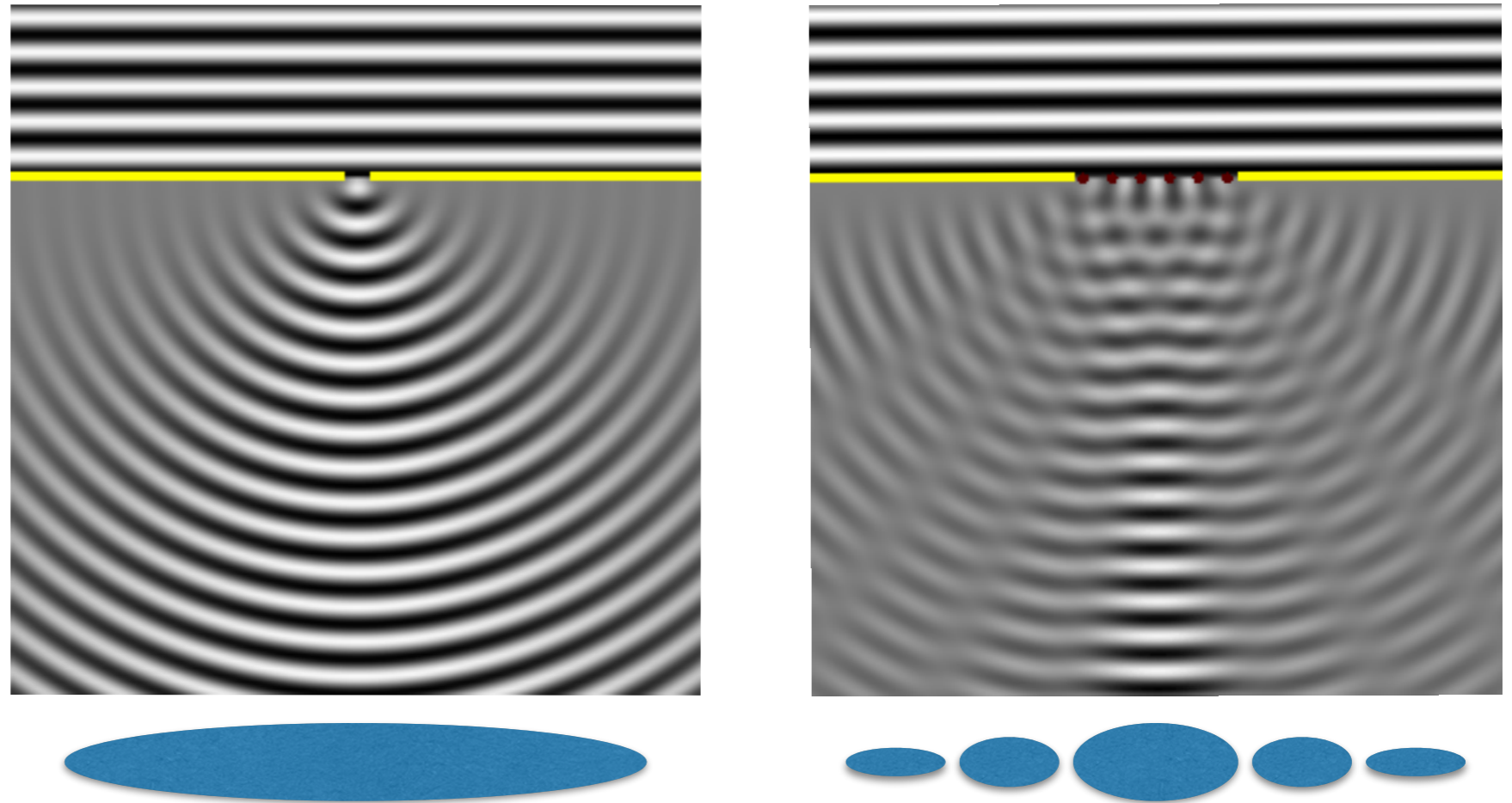
Larger apertures produce finer images

incoming wave

aperture

diffracted wave

image

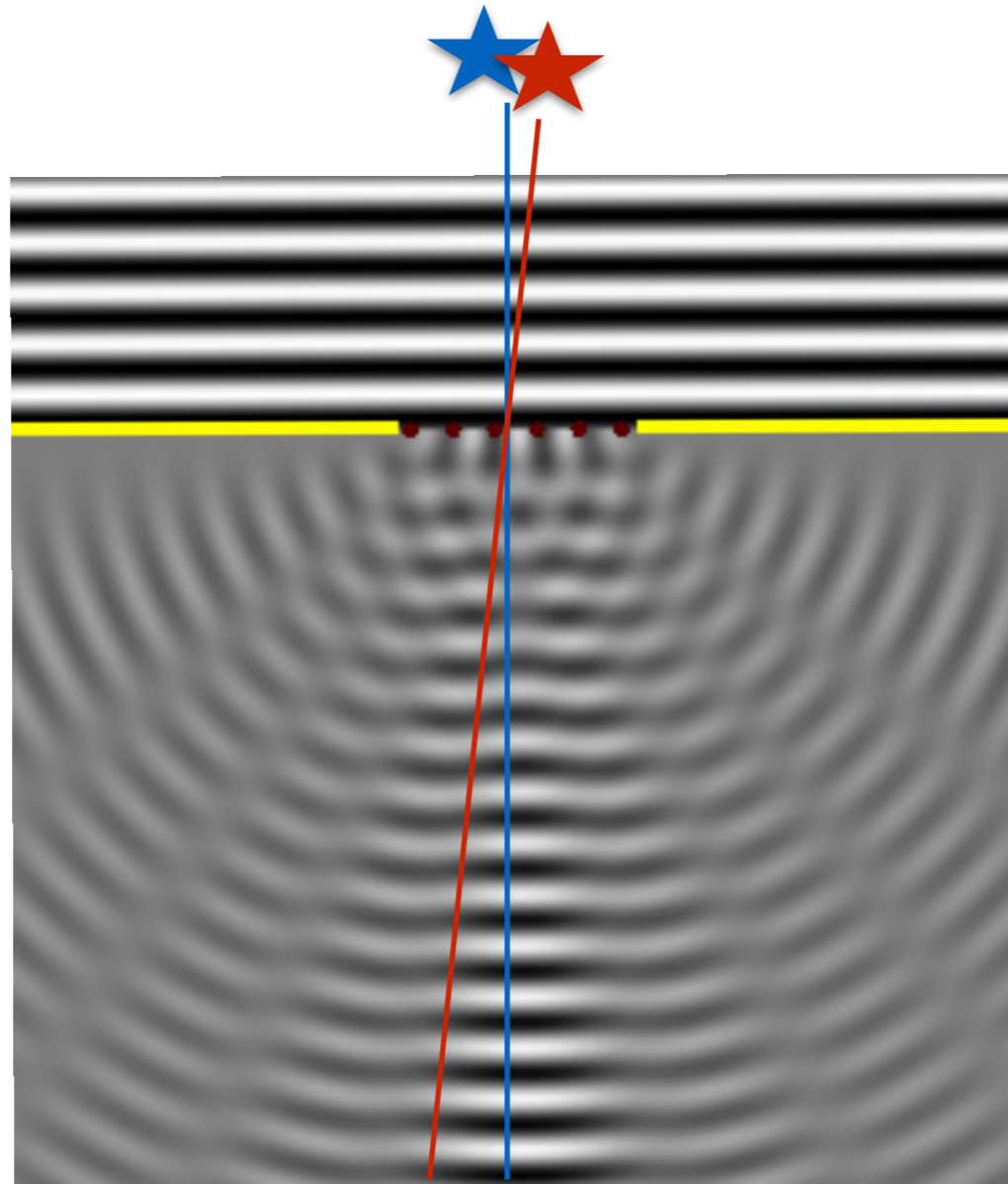


illustrations from http://en.wikipedia.org/wiki/Huygens%E2%80%93Fresnel_principle





Diffraction limits the angular resolution



Confusion!

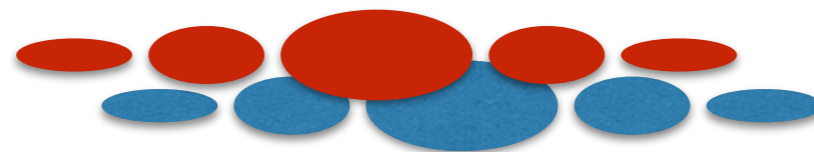




Image formation

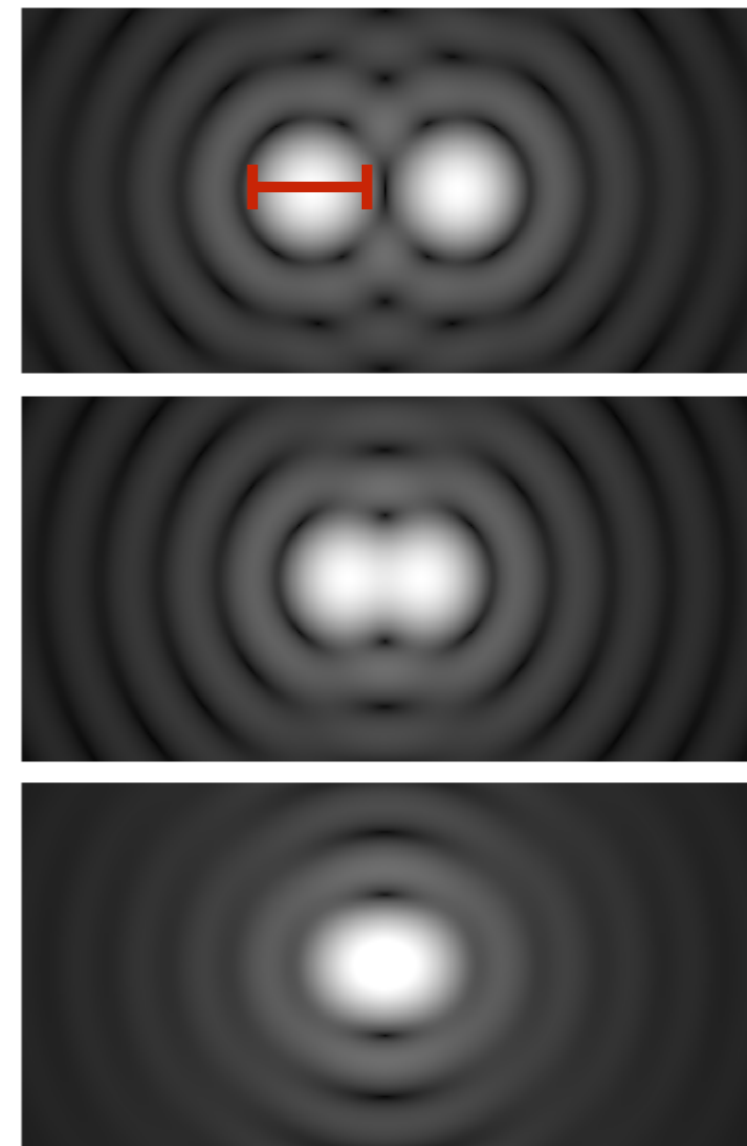
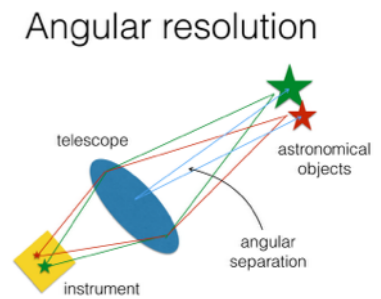
- For an incoming **plane wavefront** (point like object)
- Each point of the **entrance pupil** generates a small wave
- $I \sim \iint \text{pupil}(x,y) e^{i(xa+by)} dx dy$
- The image of a point like object is the Fourier Transform of the pupil: **Point Spread Function**
- The observed image is the convolution of the true image by the PSF



Angular resolution

- The PSF of a **circular aperture** in an **Airy pattern**
- For diameter D and wavelength λ :
 - **First null occurs at angle $1.22\lambda/D$** (radians)
 - The input aperture act as a **low pass filter with cutoff frequency λ/B**

$$2.44\lambda/D$$





The need for angular resolution



Galactic Centre seen without and with Adaptive Optics



Limitations to angular resolution

- **Diffraction: $\sim \lambda/D$**

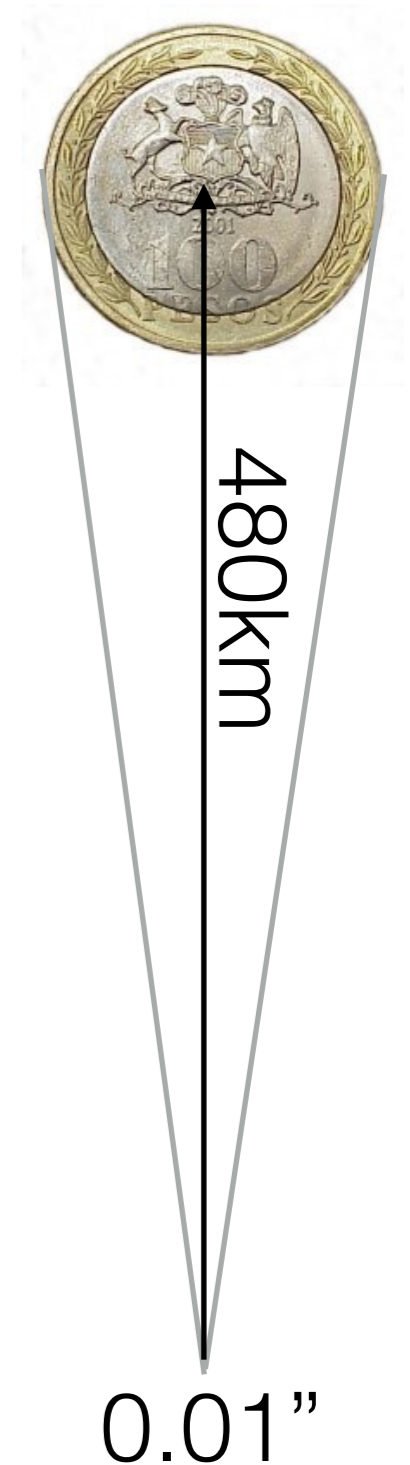
- $D=10\text{m}, \lambda=500\text{nm} \rightarrow 3\text{e-}6^\circ \sim 0.01''$

- **Atmospheric turbulence**

- typically limits to $\sim 1''$ (in the visible)

- best sites down to $\sim 0.5''$ or less

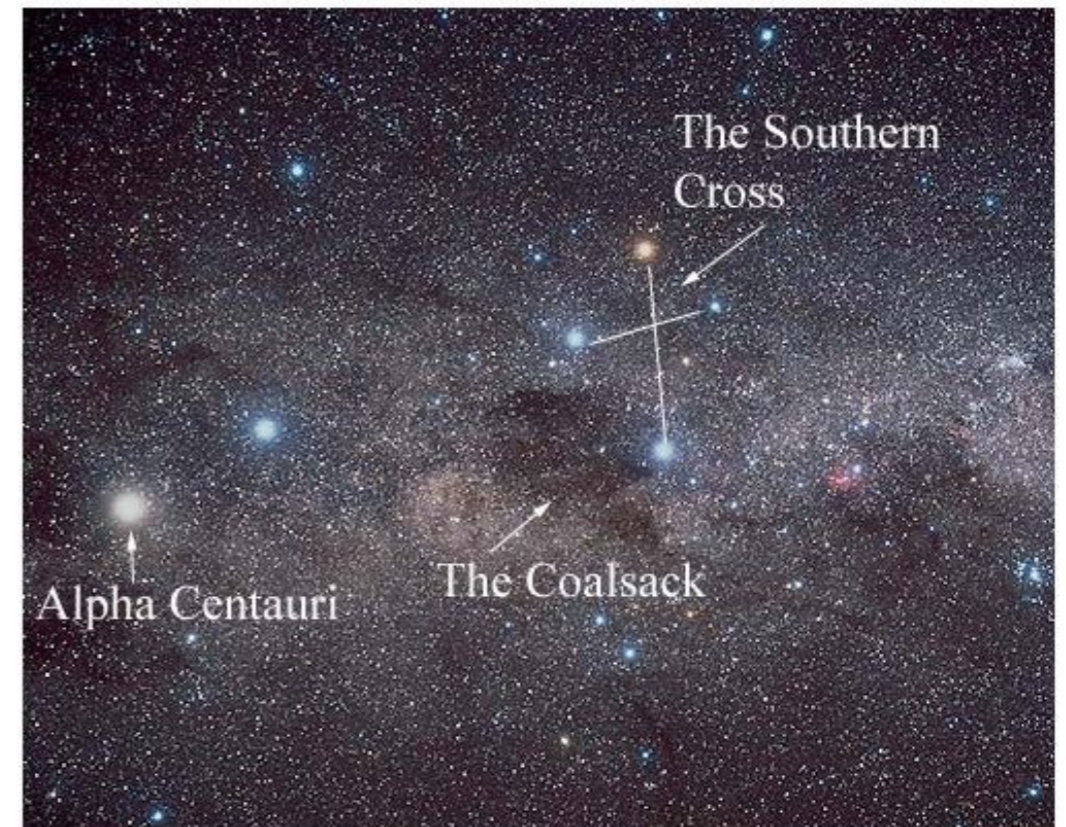
- adaptive optics bring diff limit for $\lambda \sim 1\mu\text{m}$





What is the angular size of stars?

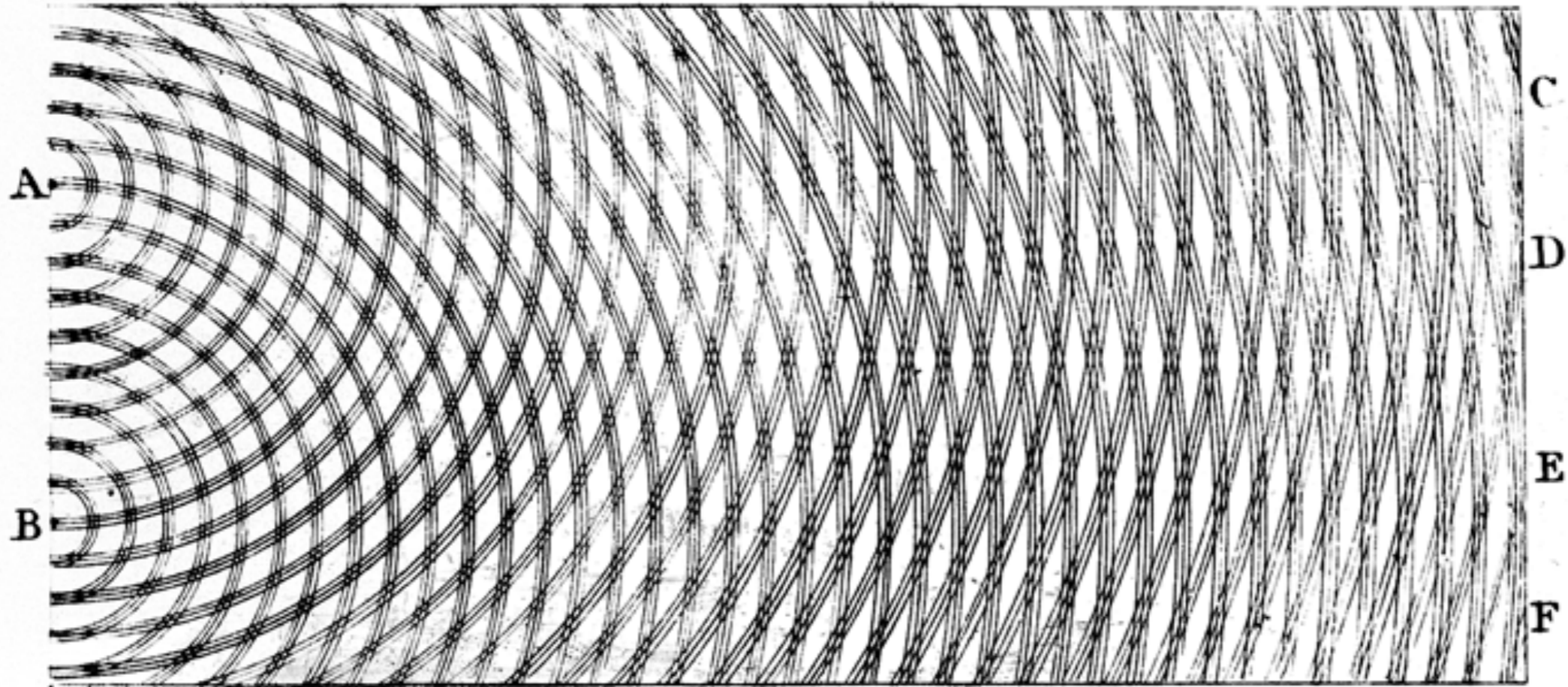
- The Sun is 30' at 1au (~1/100 radian)
- Alpha Cen is ~3000000 times further away
- The Sun appears 0.006" in diameter from Alpha Cen



Basic Principles of Interferometry



Young's experiment

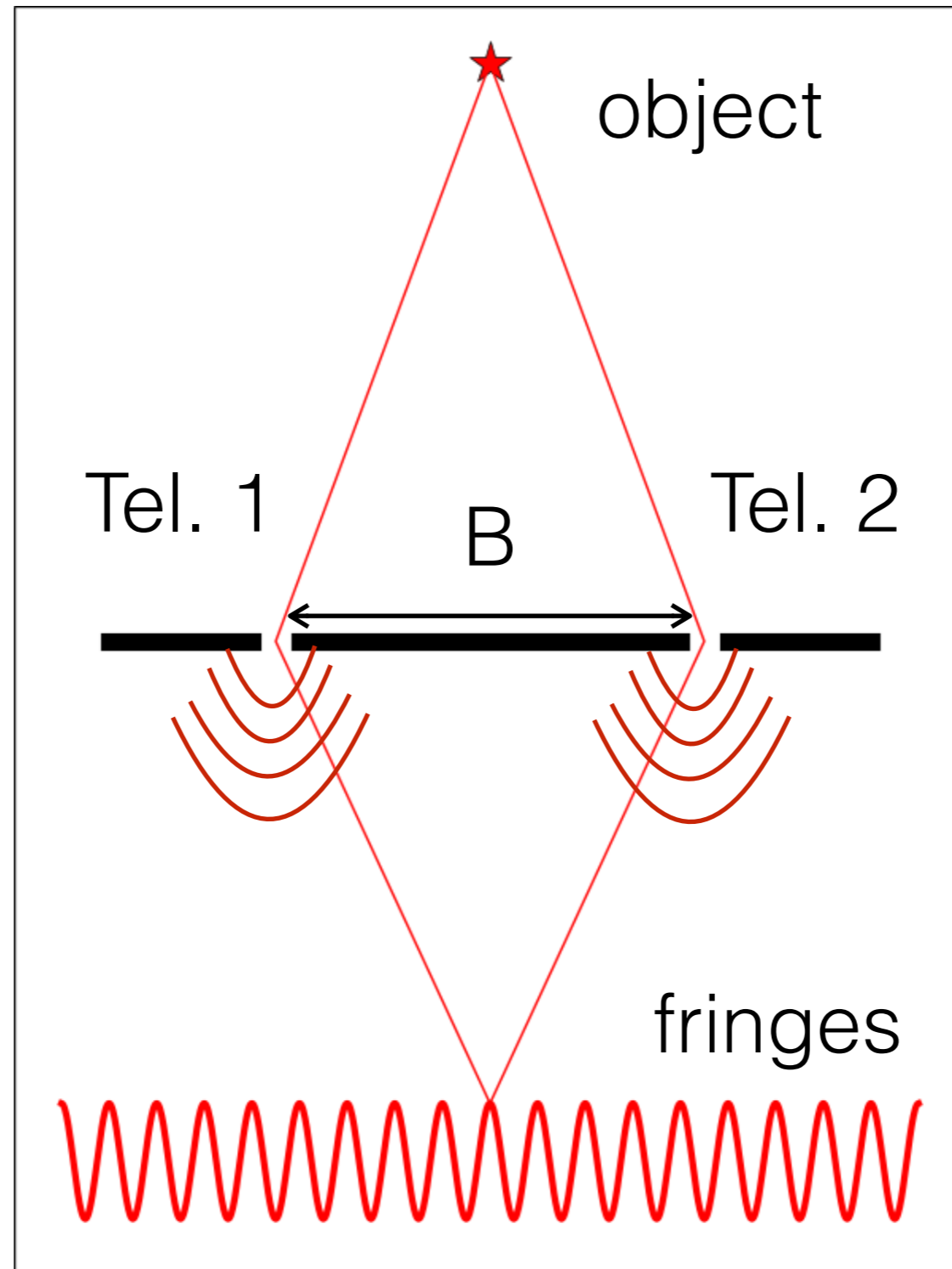


"On the Theory of Light and Colours"
Thomas Young, 1801



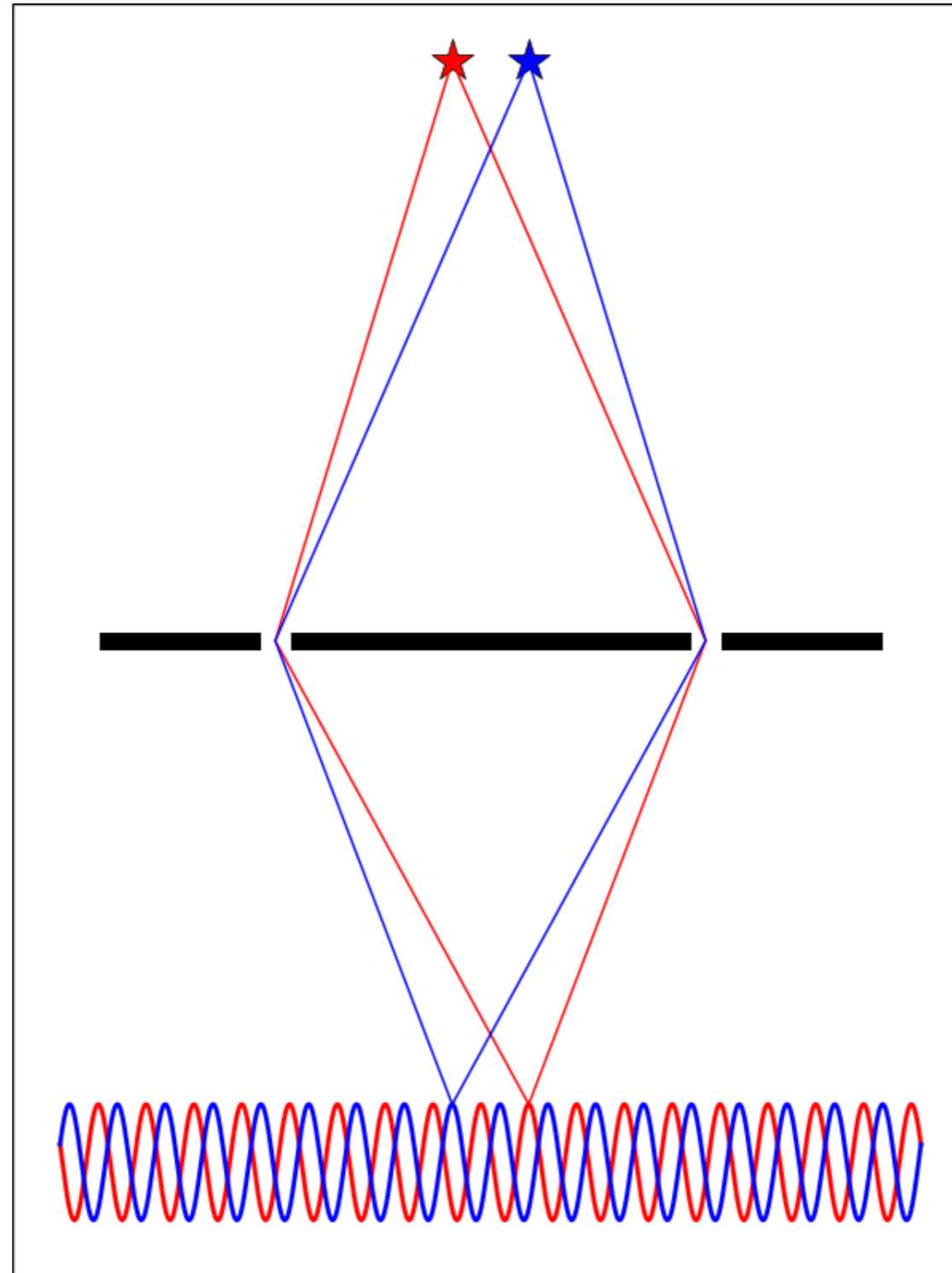


A Simple interferometer



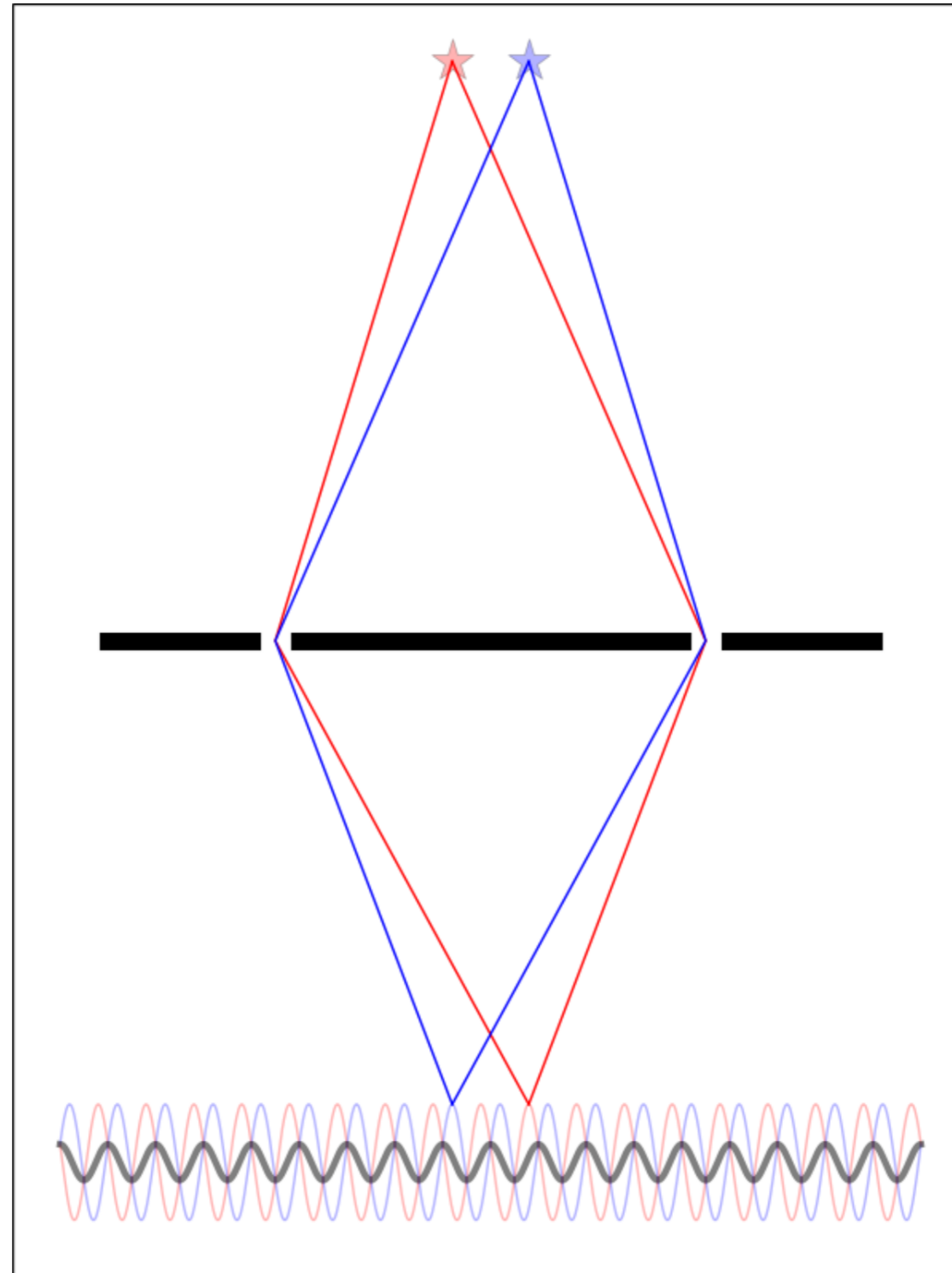


Angular Resolution





Angular Resolution





Basic principles

- Fringes replace images
- 2 objects separated by angle \mathbf{s} will produce fringes offset by $\mathbf{B.s}$
- Fringes will disappear for $\mathbf{B.s} = \lambda/2$
- If fringes amplitude is measured with accuracy, separation power $< \lambda/2B$



Accurate Formulation

- The complex visibility is the normalized Fourier Transform of the brightness distribution:

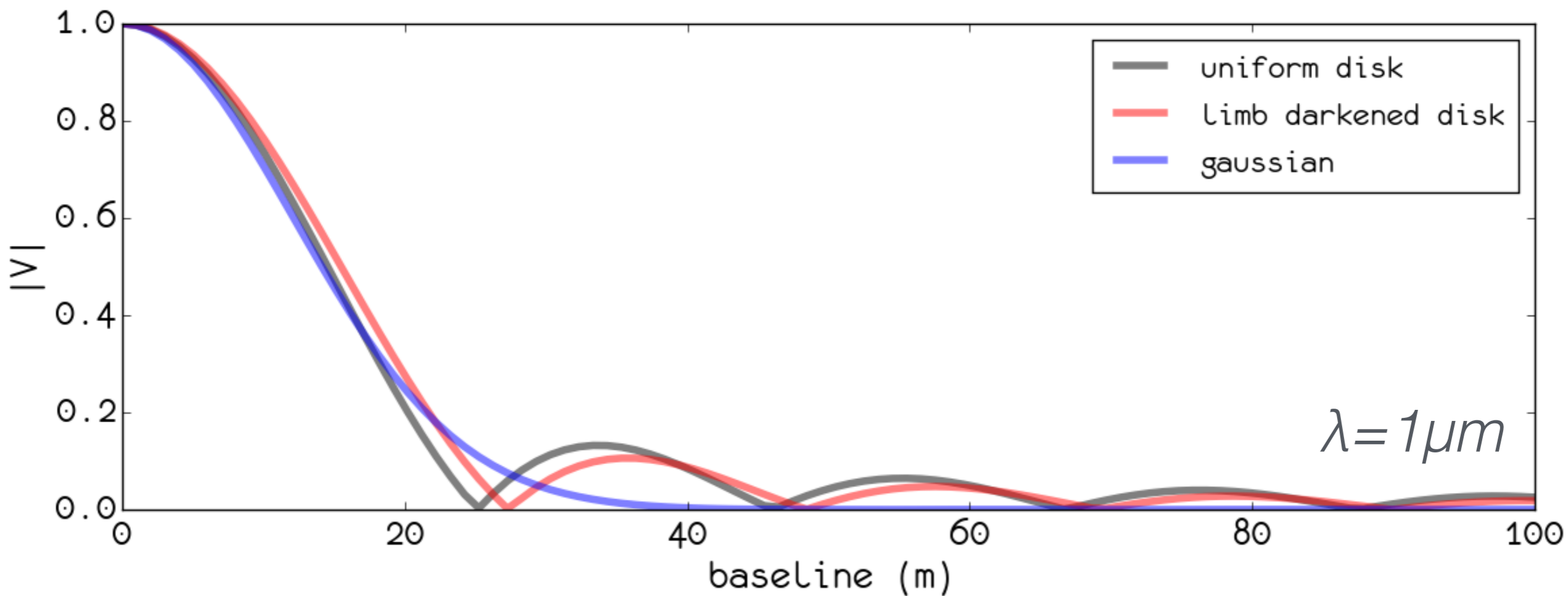
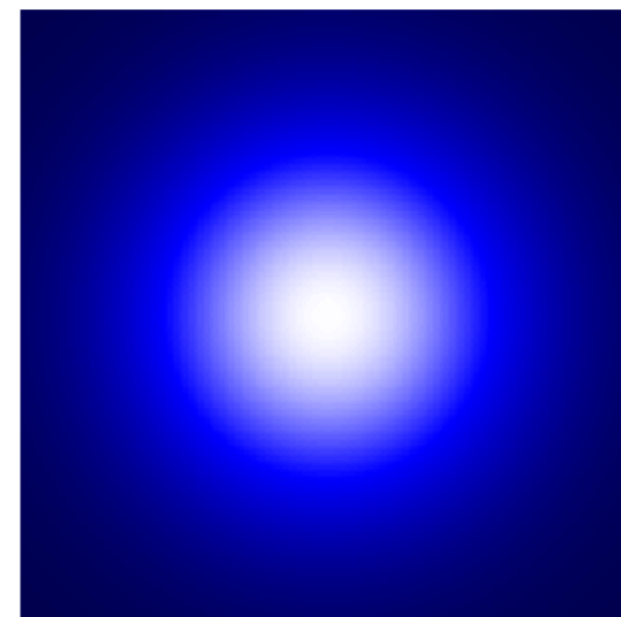
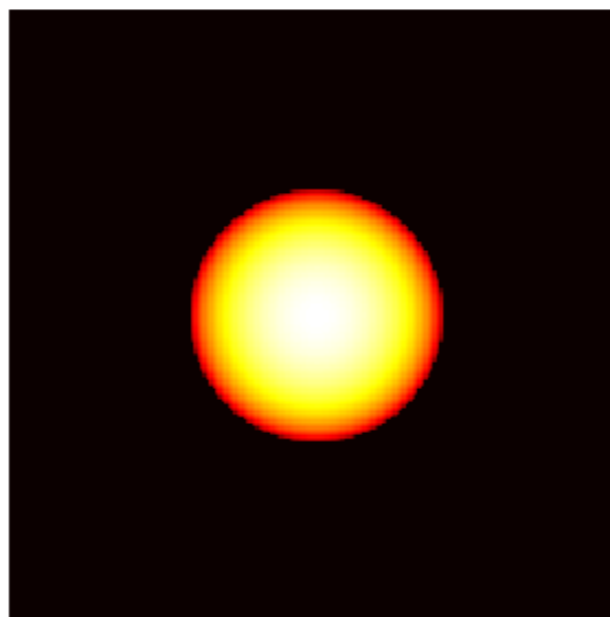
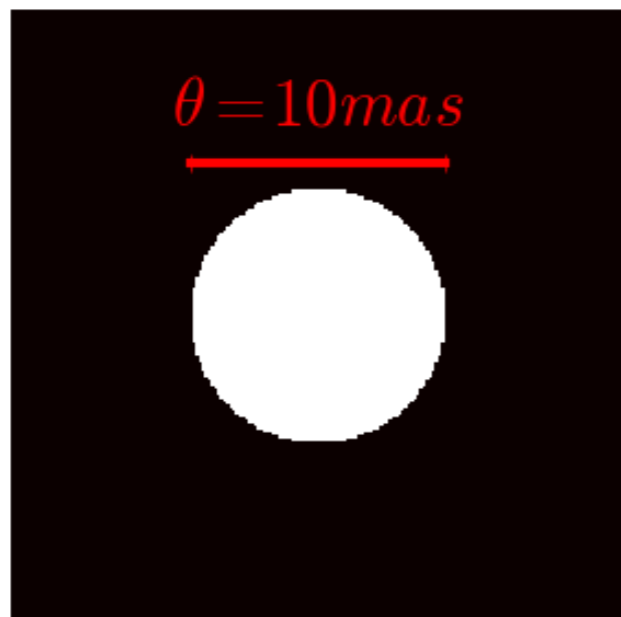
$$V(u, v, \lambda) = \frac{\int I(x, y, \lambda) e^{-i(xu + yv)/\lambda} dx dy}{\int I(x, y, \lambda) dx dy}$$

- This is the van Cittert-Zernike Theorem

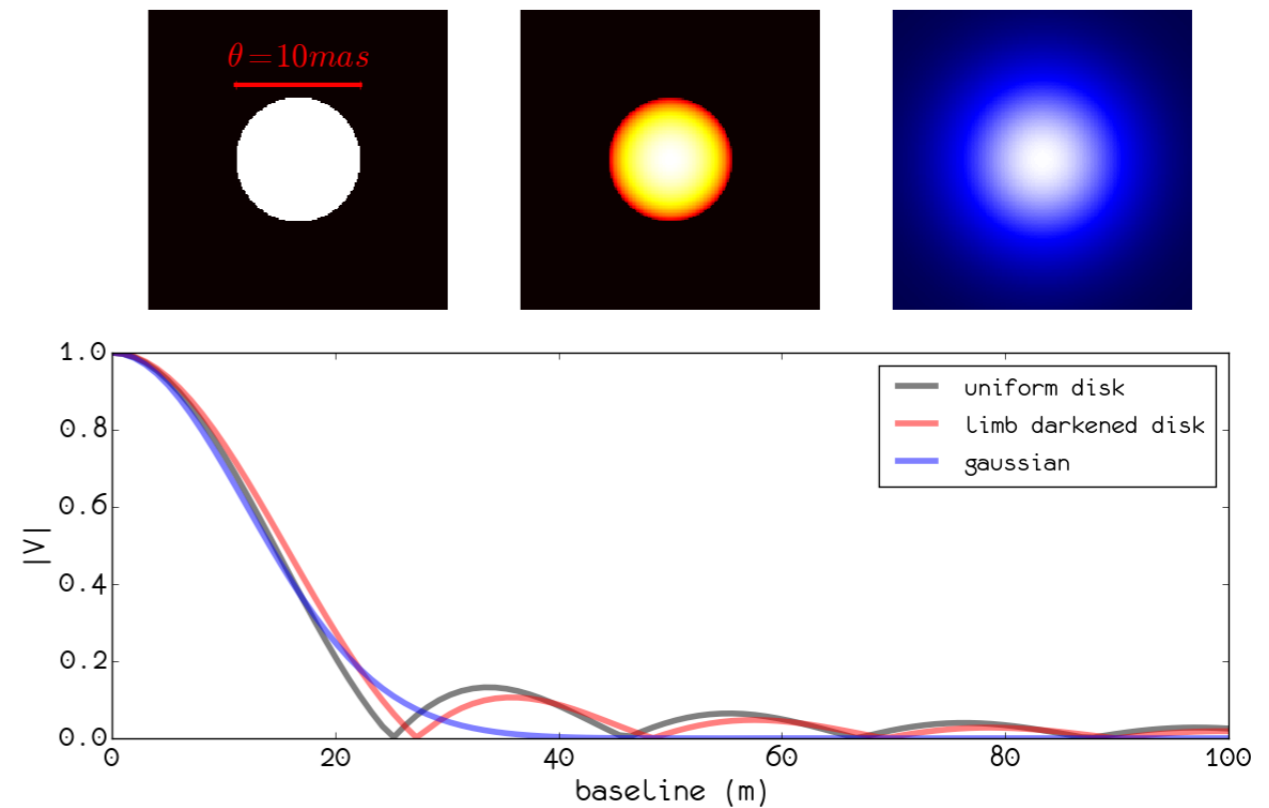
$$V_{\text{UD}}(B, \lambda) = \left| 2 \frac{J_1(x = \pi B \theta / \lambda)}{x} \right|$$

centro-symmetric:
Hankel transform

$$V(B, \lambda) = \frac{\int I(r, \lambda) J_0(rB/\lambda) r dr}{\int I(r, \lambda) dr}$$



- Measuring diameters == inverting $V(B, \Theta, \lambda)$
- True stars are NOT uniform disks
- limb darkening
 - lowers the visibility lobes
 - bias the diameter measurements



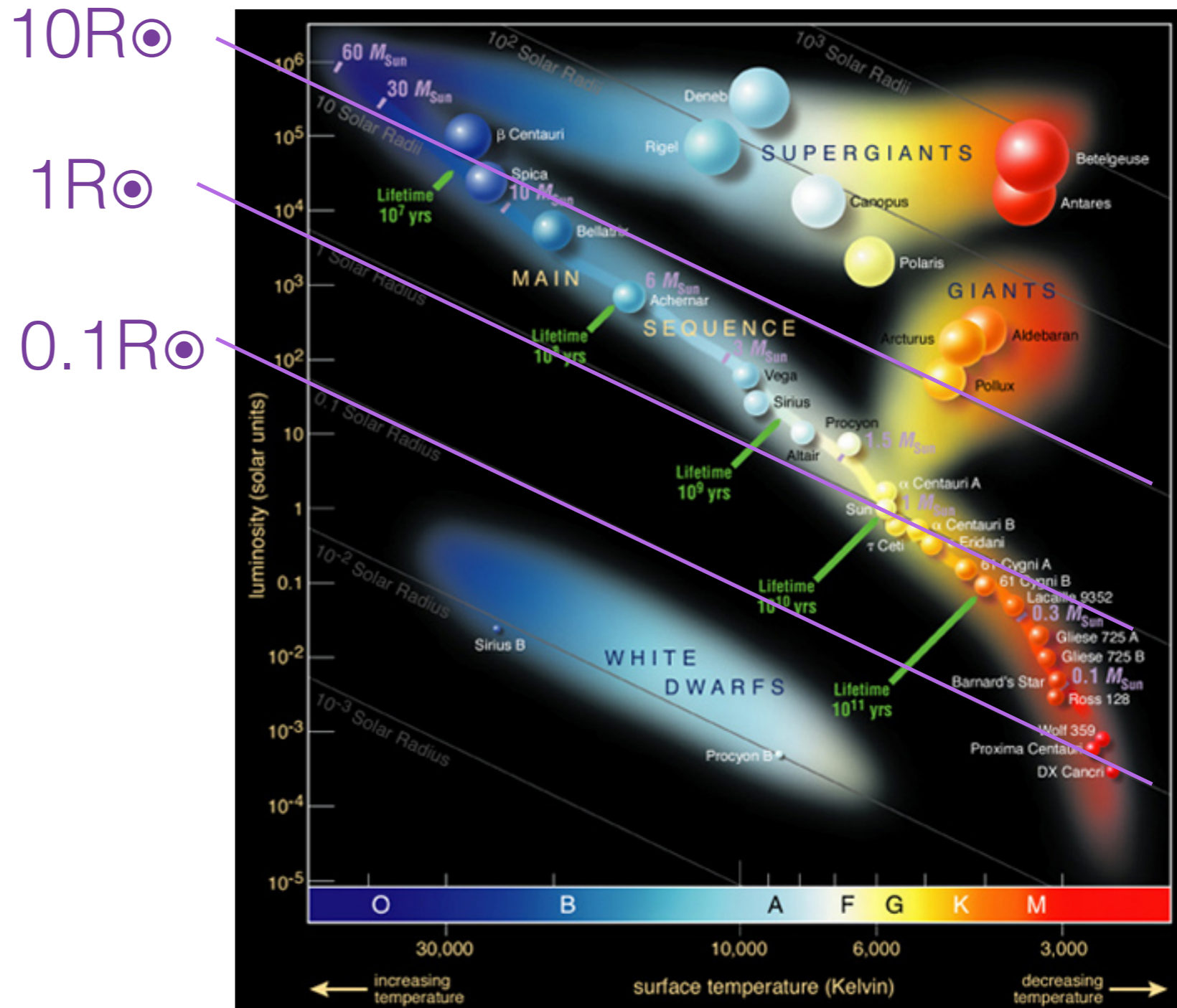


diameters of stars

- Relation between fundamental parameters of stars:
Temperature,
Luminosity,
Radius

- Absolute $L \sim R^2 T^4$

- Apparent $L \sim \Theta^2 T^4$





What have we seen so far?

Telescope of **diameter D**:

- **low pass** spatial frequency filter
- angular resolution $\sim \lambda/D$
- strongly limited by atmospheric turbulence

Interferometer of **baseline B**:

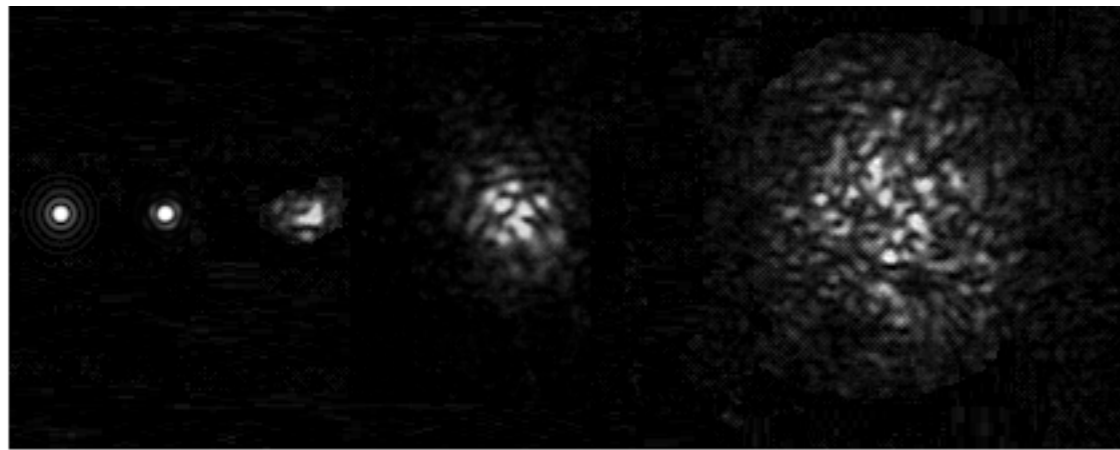
- **band pass** spatial frequency filter
- angular resolution $\sim \lambda/B$
- effect of atmospheric turbulence???



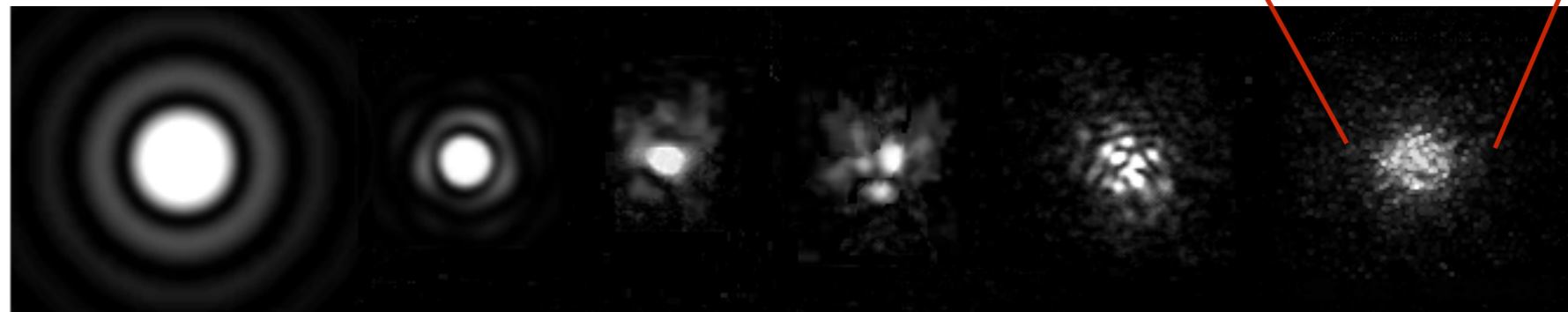
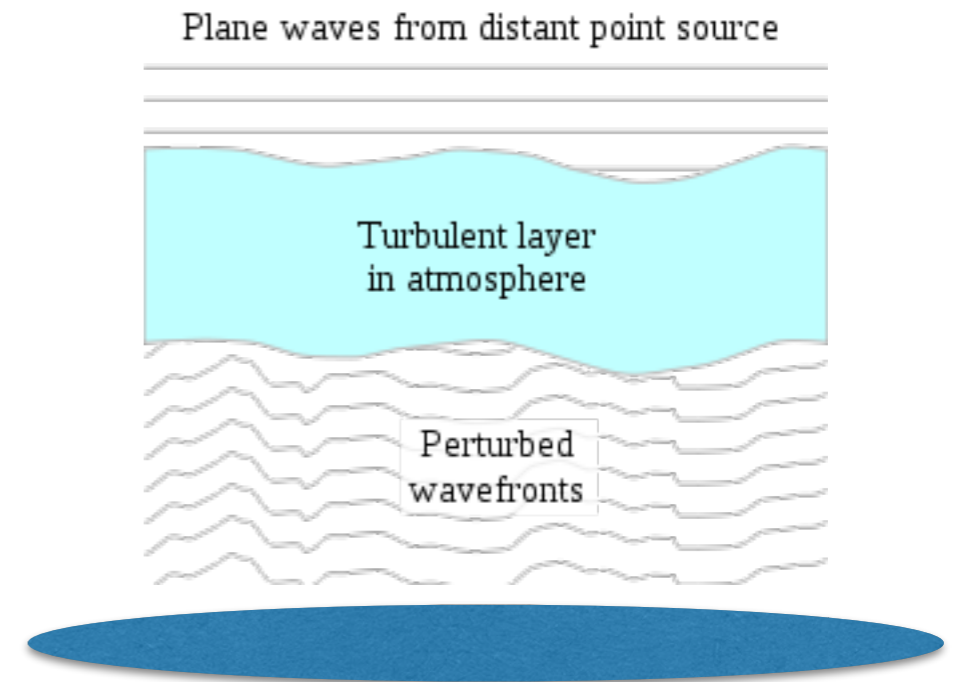
Practical Use of Optical Interferometry



Turbulence: single aperture



Single Aperture images as turbulence degrades



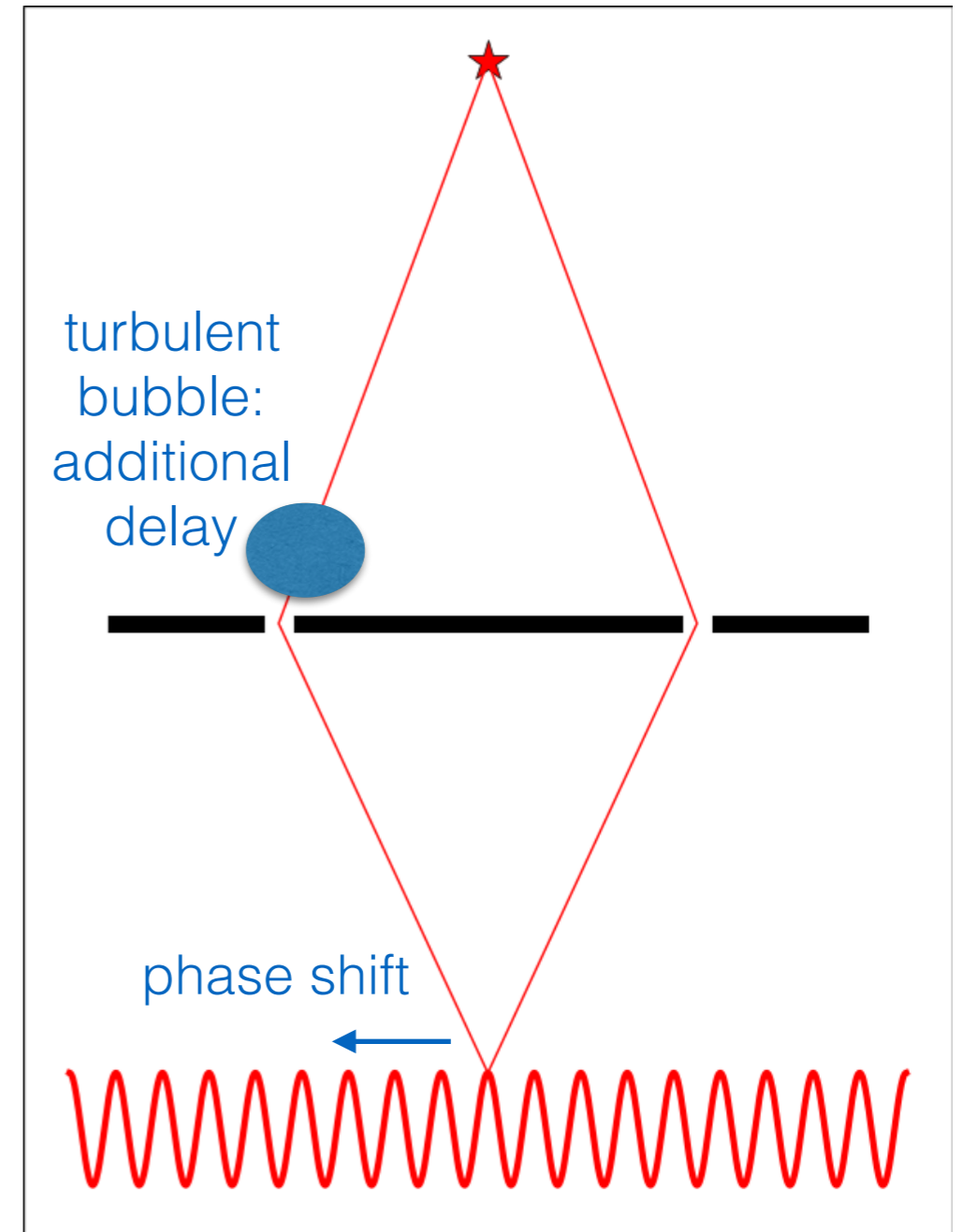
Single Aperture images as telescope aperture increases





1rst order: Piston

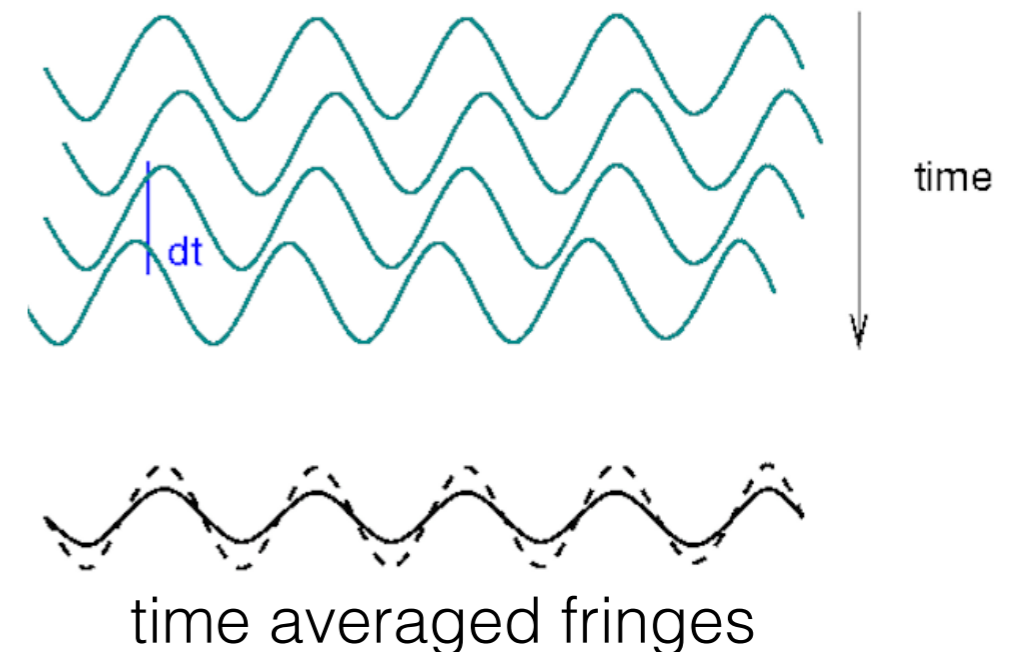
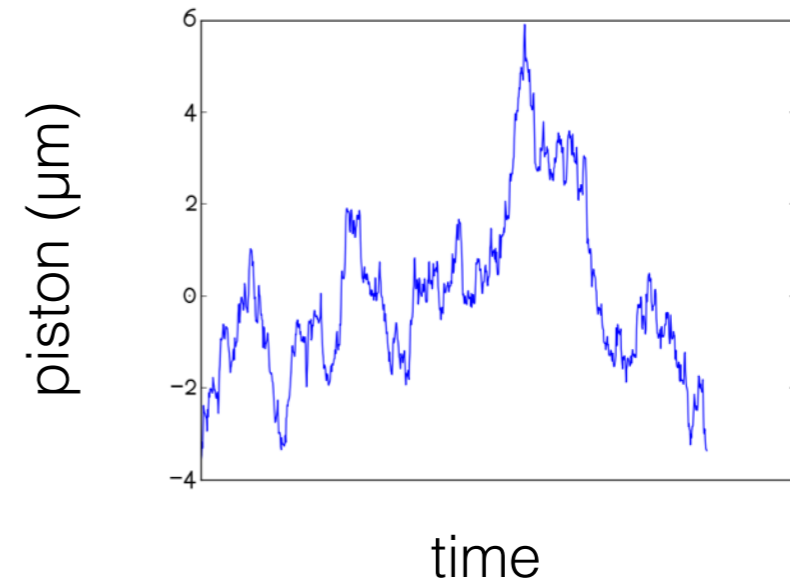
- First order: difference of refraction index produced **differential delay**
- Additional delay produce a **phase shift** in fringes.





Piston effects

- Turbulence has a **low frequency excess** spectrum
- averaging in time: **contrast is lowered** and **phase information is lost**
- The longer the exposure time, the worse the contrast loss (!)





Piston effect

Why do radio interferometer measure phases?

- in cm regime, piston $\ll \lambda$
- in mm regime, piston dominated by water vapor fluctuations, which can be measured by radiometer (ALMA)
- in optical and near-IR amplitude of piston is $\gg \lambda$





Fundamental effect of turbulence

Turbulence has a negative power law power spectrum. There is more effect at low frequencies than high frequencies (*Excess Low Freq. noise*)

- Short exposures freeze the turbulence
- Long exposures result in loss of fringe contrast





The need for calibration

- Measuring diameters rely on inverting $V(B, \Theta, \lambda)$
- Measure of $V(B, \Theta, \lambda)$ is biased by atmosphere turbulence
- Necessity to measure objects with known $V(B, \Theta, \lambda)$:
calibrators
- **Stellar calibrators** are preferably unresolved ($V \sim 1$) to avoid relying on diameter estimation
- Calibrators should be observe under **same conditions** (instrument, turbulence) as the unknown target



What we have seen so far

- Fringe **visibility** is the main observable
- Visibility is the **Fourier Transform of the brightness distribution**
- Interferometer is a **spatial frequency band pass filter**
- 2T: **stellar angular diameters** can be inferred from measurements and known $V(B, \Theta, \lambda)$
- Atmospheric piston leads to **loss of absolute phase** and the need for **short exposures** and **stellar calibrators**



The need for phase

- Binary star

$$V(u, v, \lambda, x, y, f) = \frac{\overset{\textit{star 1}}{V_1(u, v, \lambda)} + \overset{\textit{star 2}}{fV_2(u, v, \lambda)} \overset{\textit{modulation}}{e^{2i\pi(xu+yv)/\lambda}}}{1 + f}$$

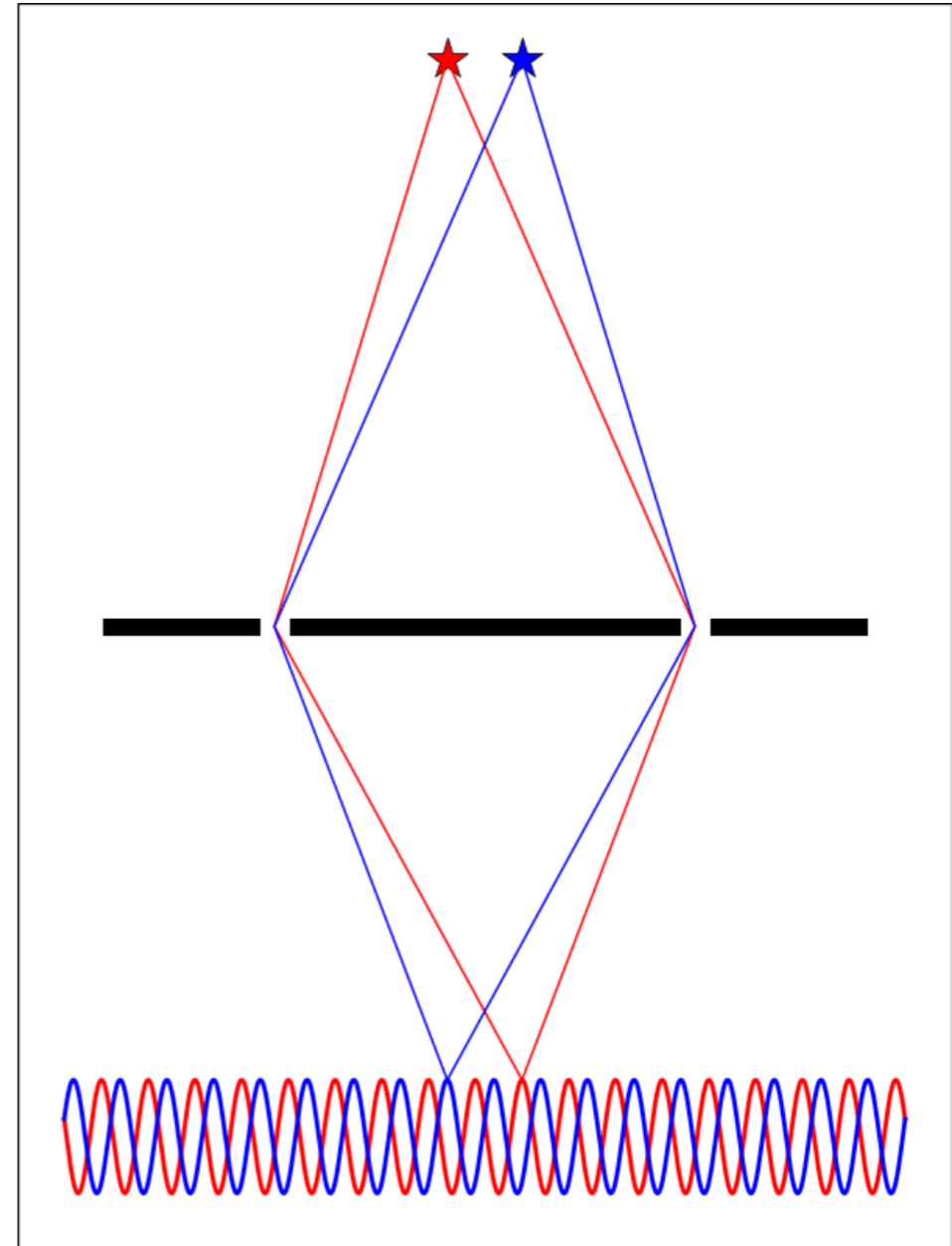
baseline
wavelength
separation
flux ratio

- $|V(x, y)| = |V(-x, -y)|$
- If one measures only $|V|$, the asymmetry of an object cannot be assessed!



Phase = Astrometry

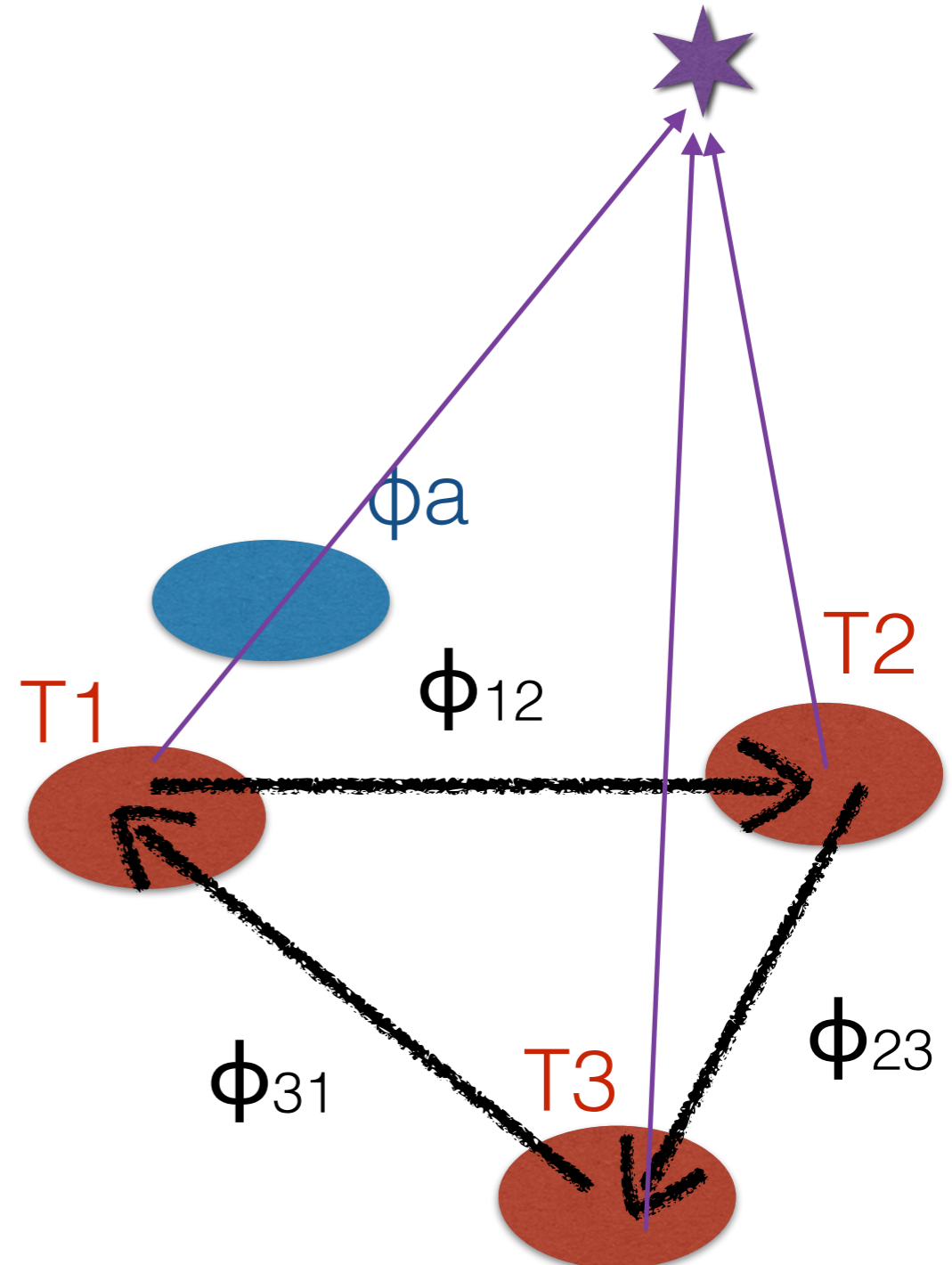
- The phase of the fringes is the astrometric position of the object
- Binary **fringe's contrast reduction results from a phase difference between the 2 objects**





Closure Phase

- For 2T, absolute phase is lost due to atmosphere
- For 3T there is a trick
- Measure phase sum in a **close triangle**
- $CP = (\phi_{12} + \phi_a) + (\phi_{23}) + (\phi_{31} - \phi_a) = \phi_{12} + \phi_{23} + \phi_{31}$
- CP is insensitive to atmospheric turbulence



Advanced implementation



Modern Instruments

Most modern instruments contain some of the following:

- N Telescopes > 2
- Spectrally dispersed measurements
- Astrometry and/or phase referencing





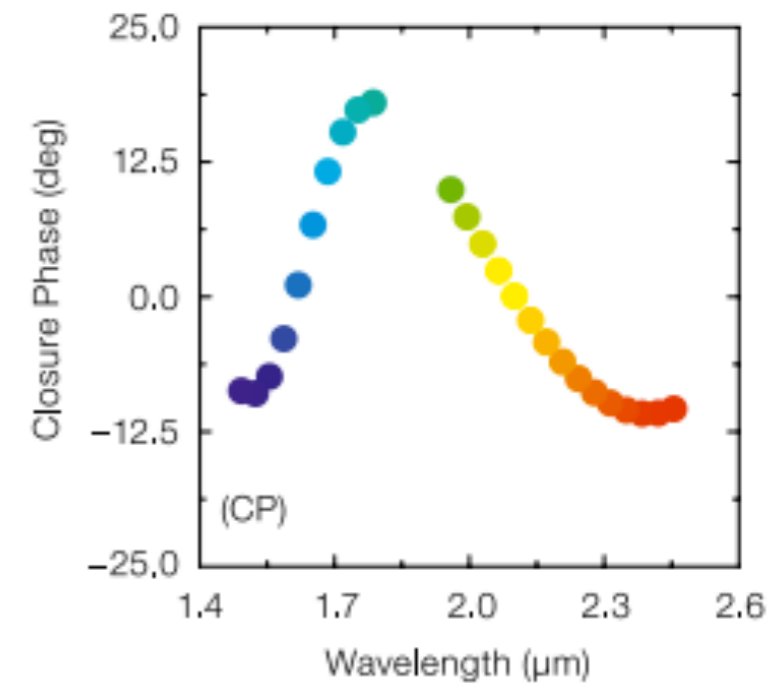
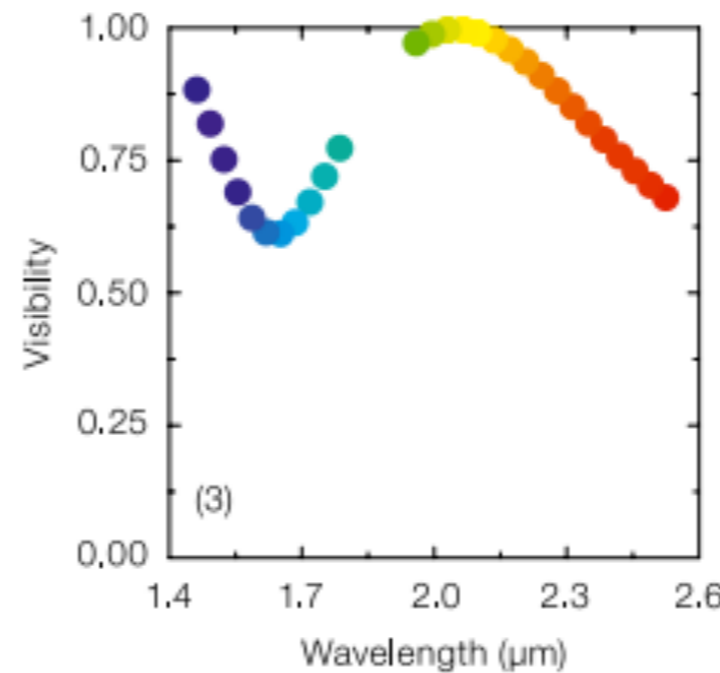
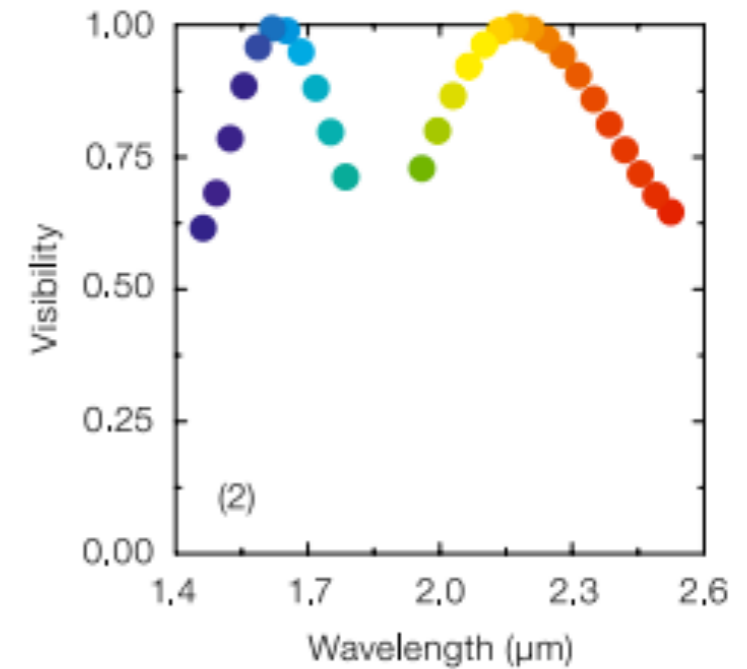
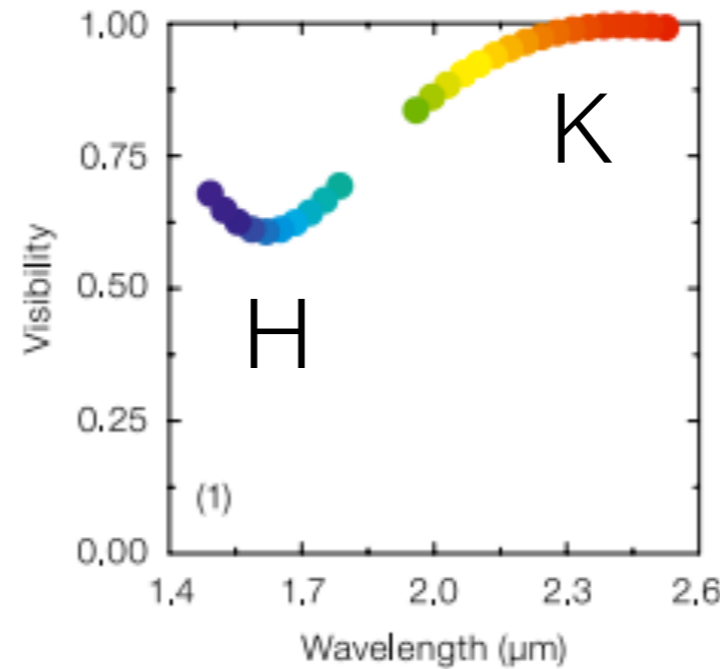
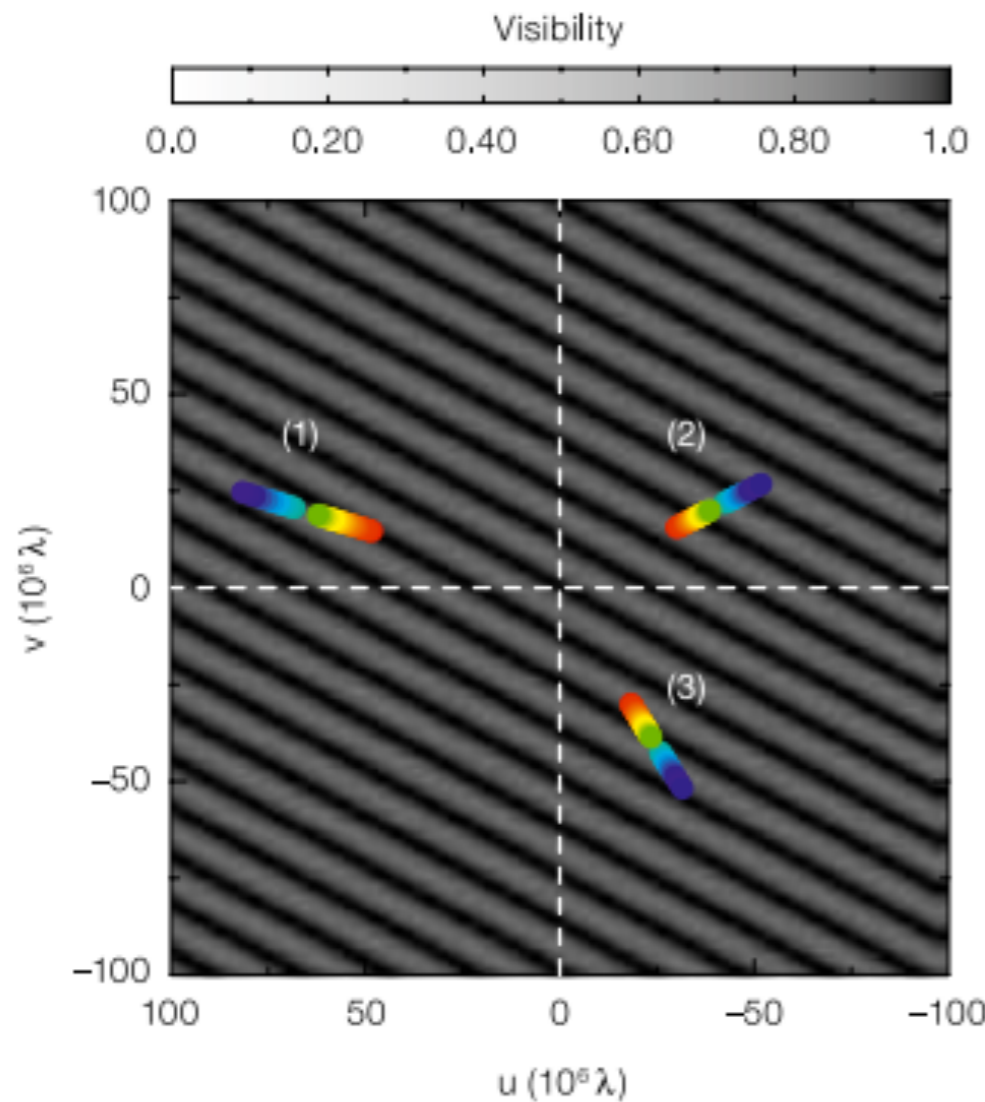
Example: AMBER@VLT

- AMBER combines 3 telescopes
- Near IR (J,H,K, $\lambda=1 \rightarrow 2.5\mu\text{m}$)
- multiple spectral channels
- spectral resolution from $R \sim 30$ to $R \sim 15000$





Binary seen by AMBER

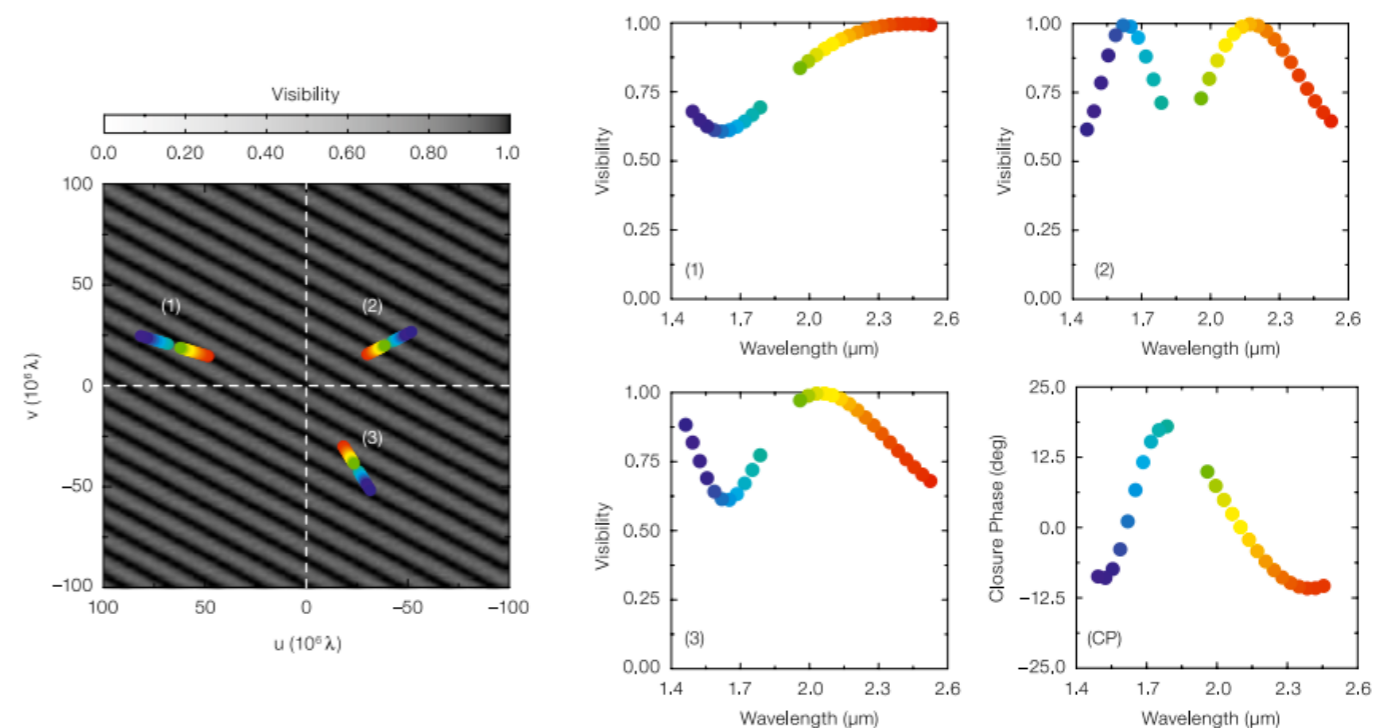


$$V(u, v, \lambda, x, y, f) = \frac{V_1(u, v, \lambda) + fV_2(u, v, \lambda)e^{2i\pi(xu+yv)/\lambda}}{1 + f}$$



Achromatic objects

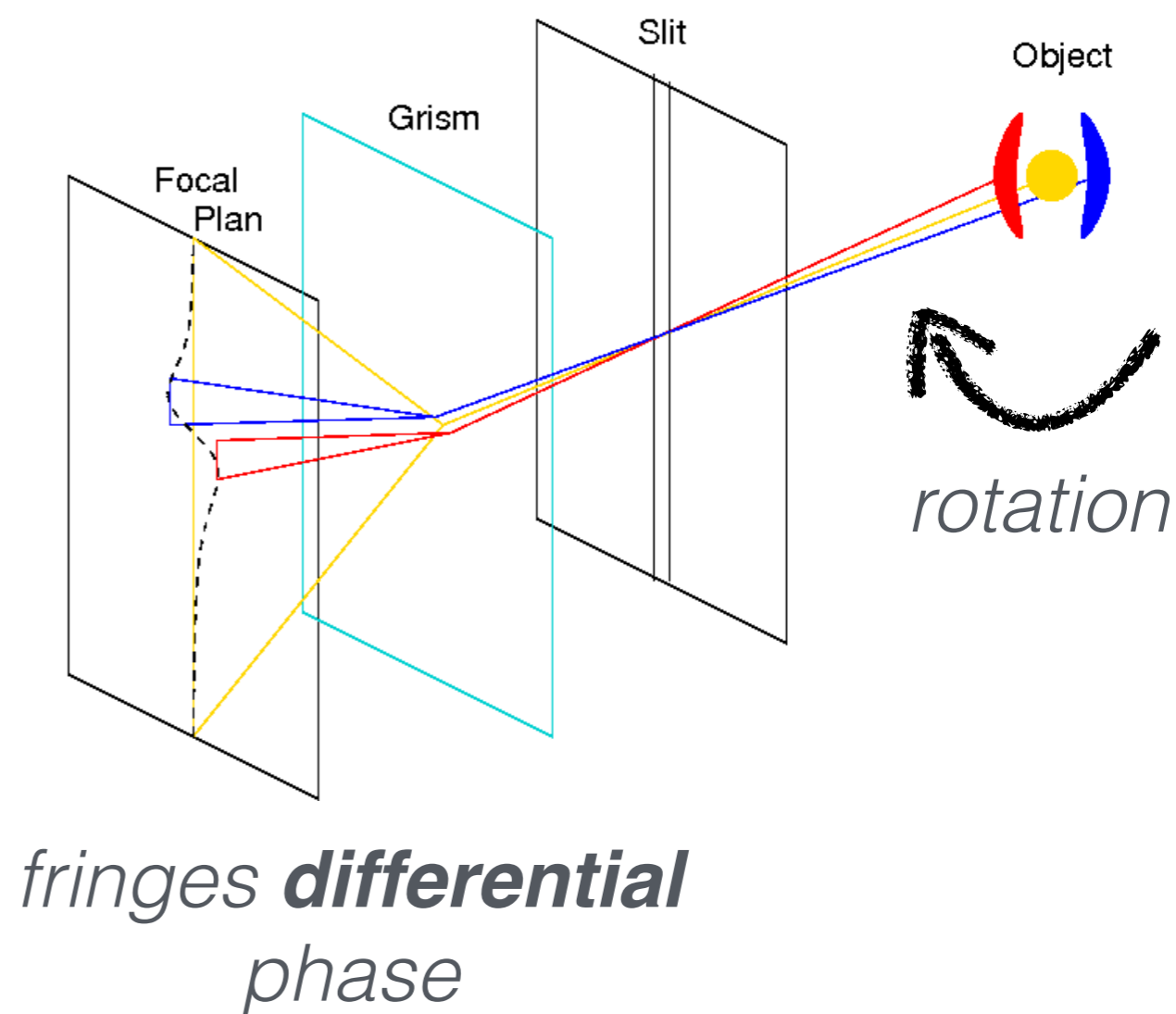
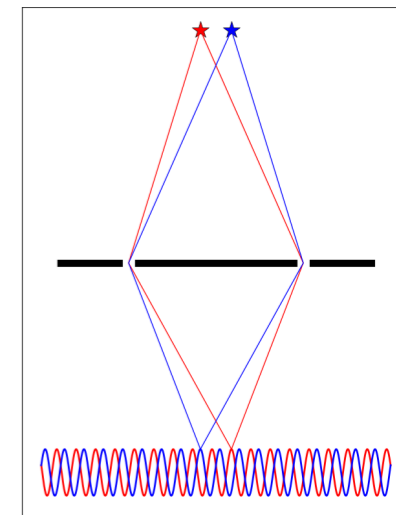
- Various spatial frequency B/λ simultaneously (**u,v coverage**)
- **Differential measurement** (less sensitive to calibration uncertainty)





Spectro-astrometry

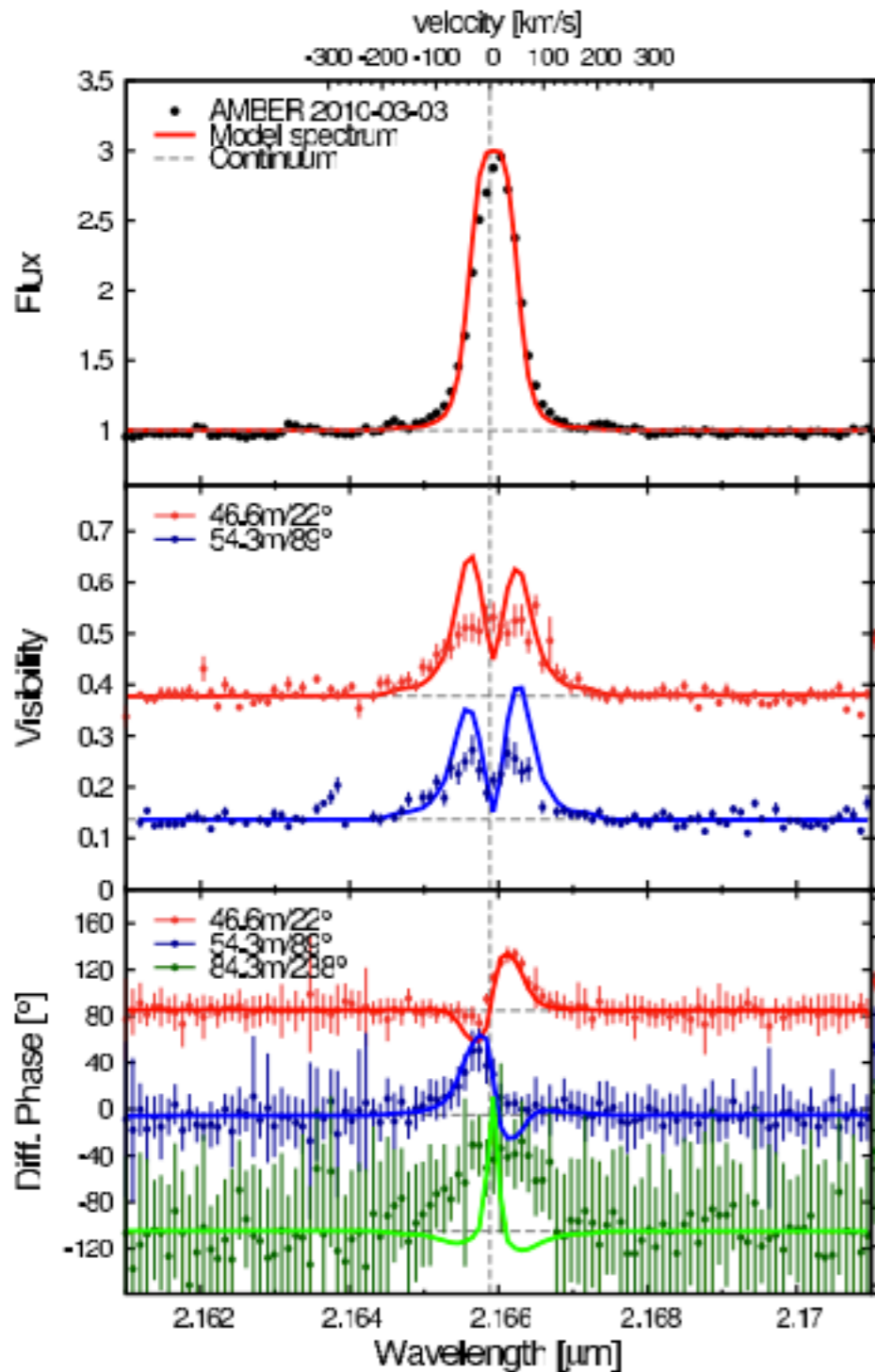
- Object in rotation (e.g. disk around a star)
- Spectral line with **Doppler shift**
- Phase of the fringes will vary throughout the line
- **Velocity field** and **geometric information** can be derived



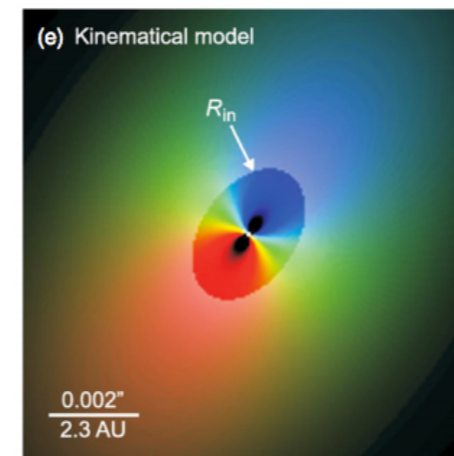


AMBER@VLT

Herbig B[e] star (Kraus+ 2012)



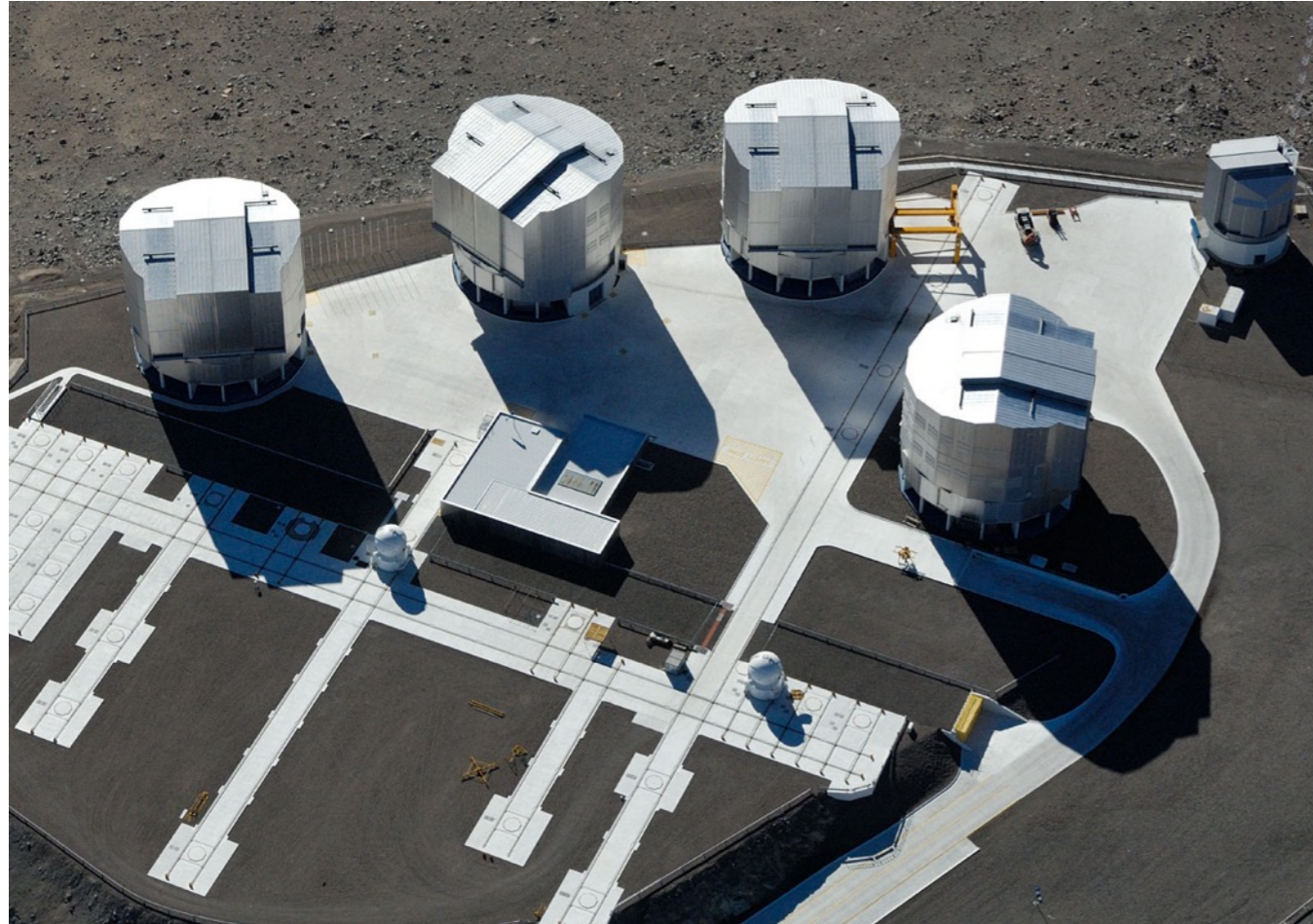
- Get differential phase in 3 baselines
- Allows to reconstruct the disk geometry
- Velocity field is Keplerian



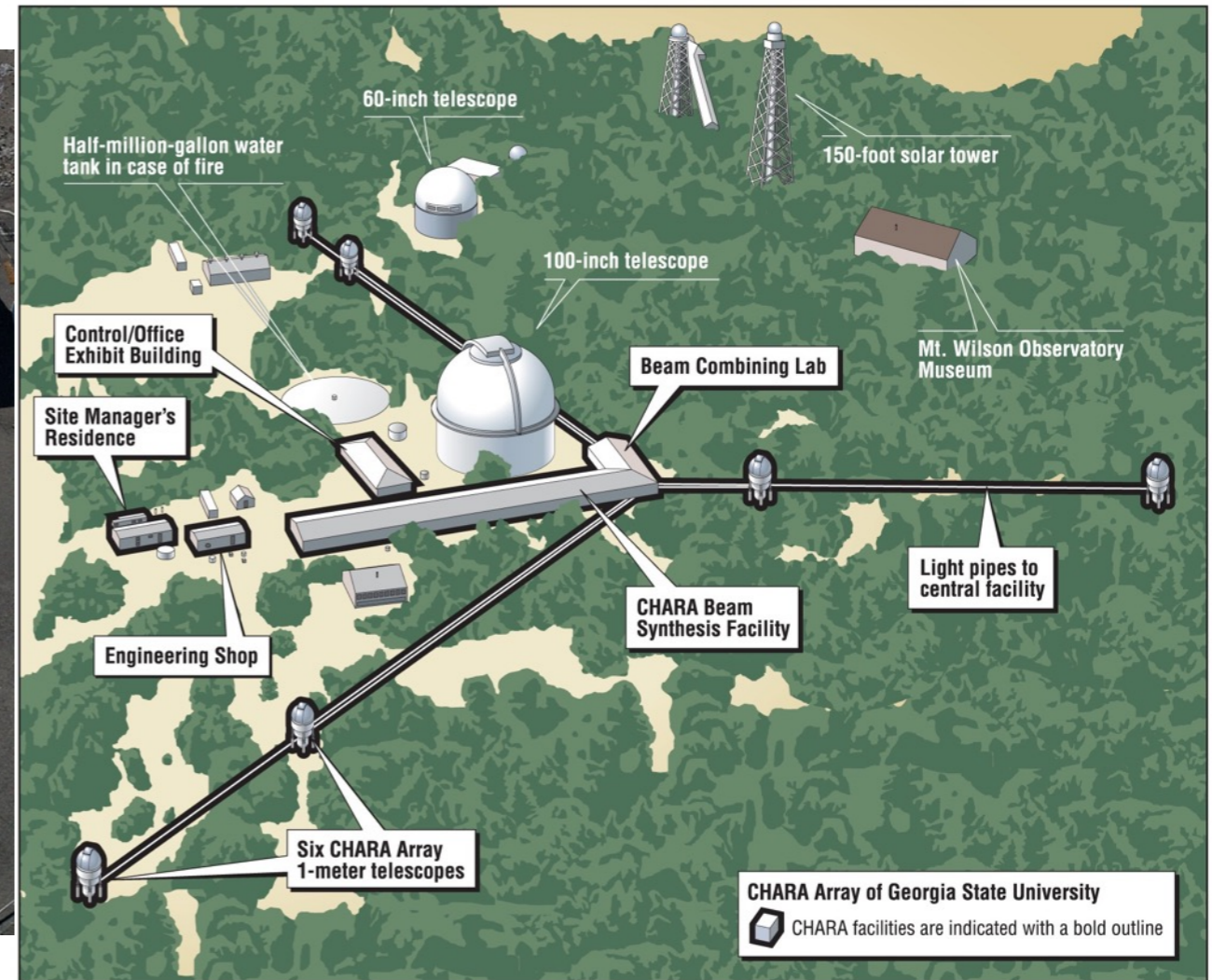
Real Interferometers



Real Interferometers



ESO VLT

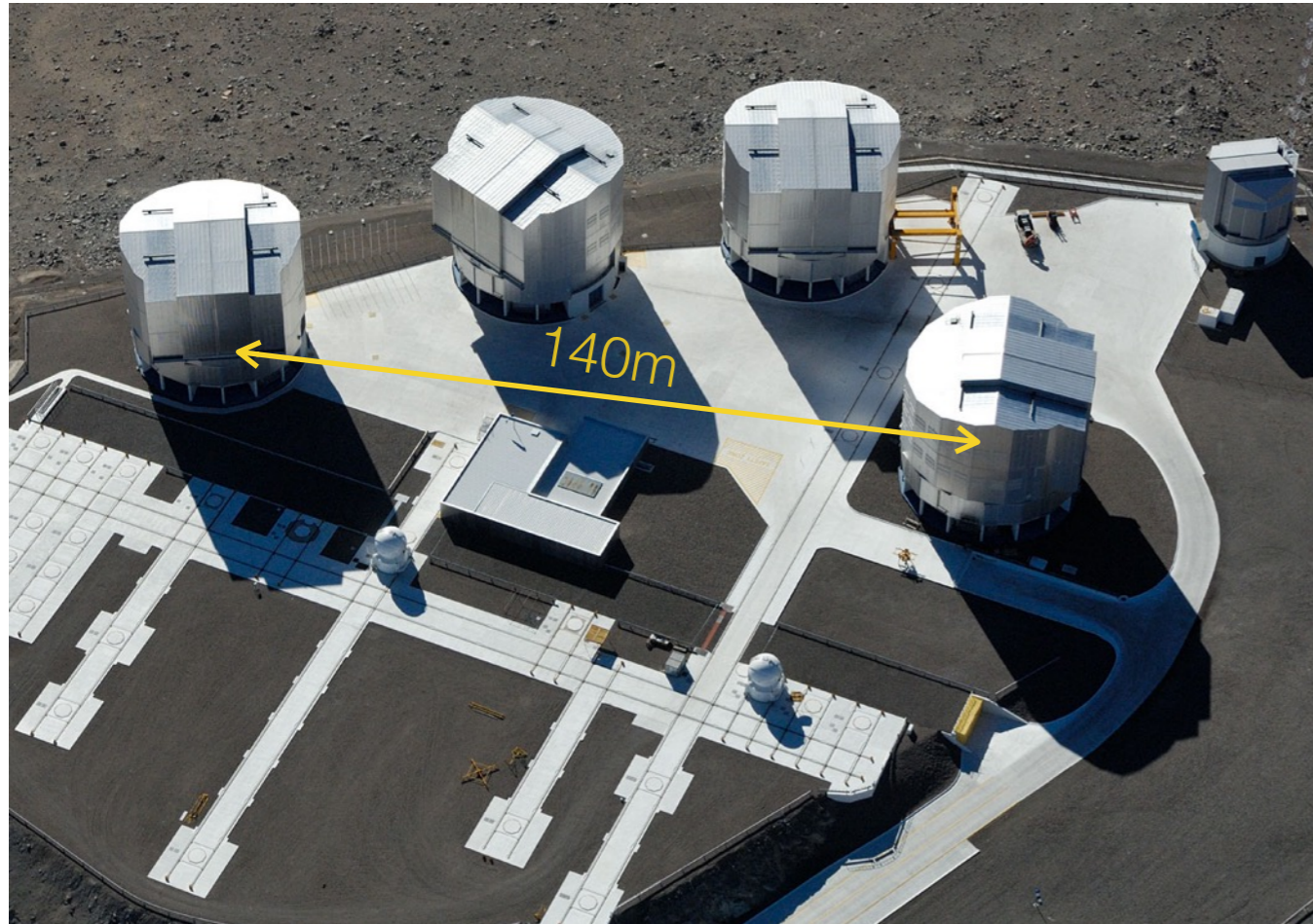


CHARA Array



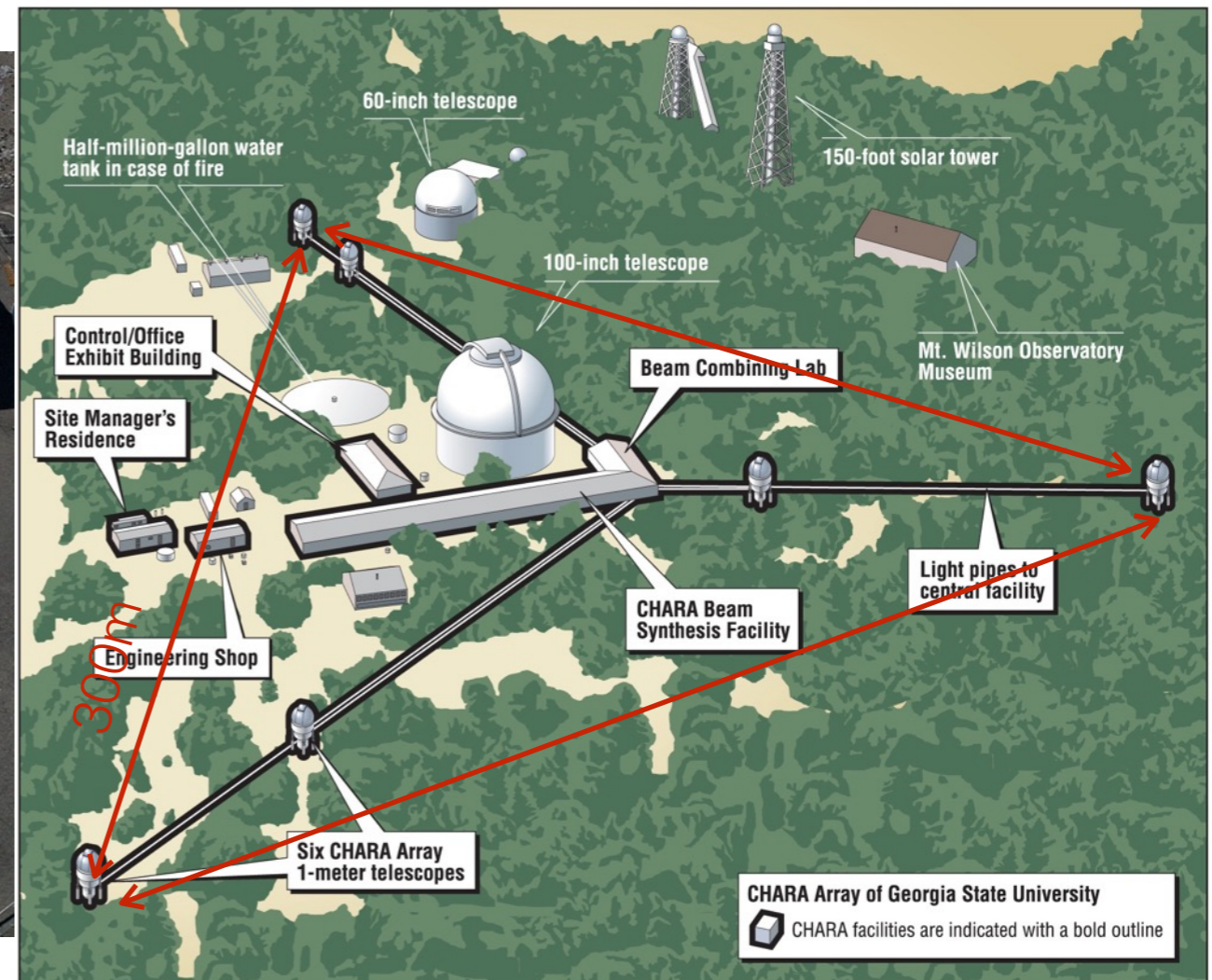


Real Interferometers



ESO VLT

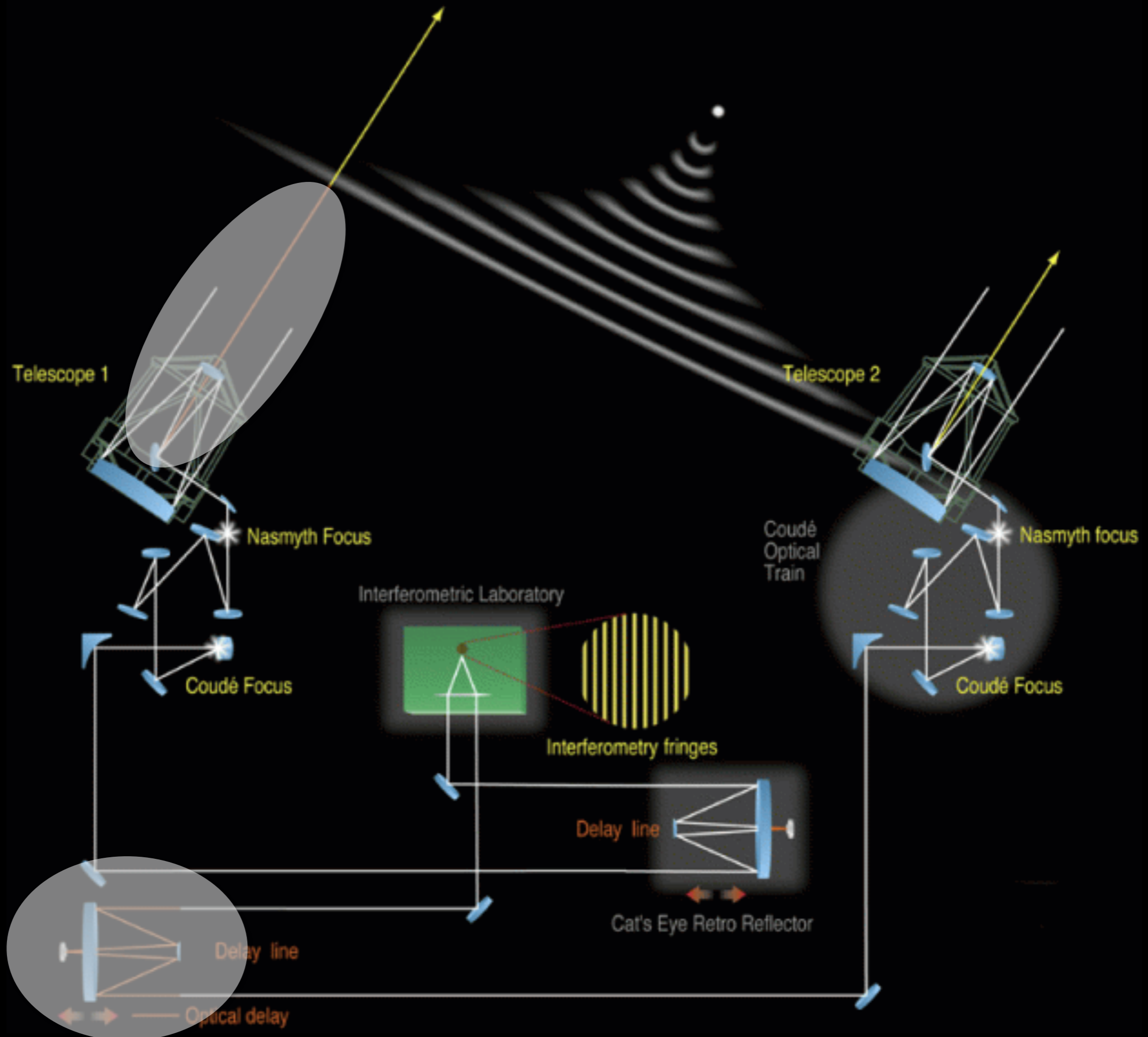
$$\lambda/B \sim 1.5\mu\text{m}/140\text{m} \sim 2\text{mas}$$



CHARA Array

$$\lambda/B \sim 0.8\mu\text{m}/330\text{m} \sim 0.5\text{mas}$$

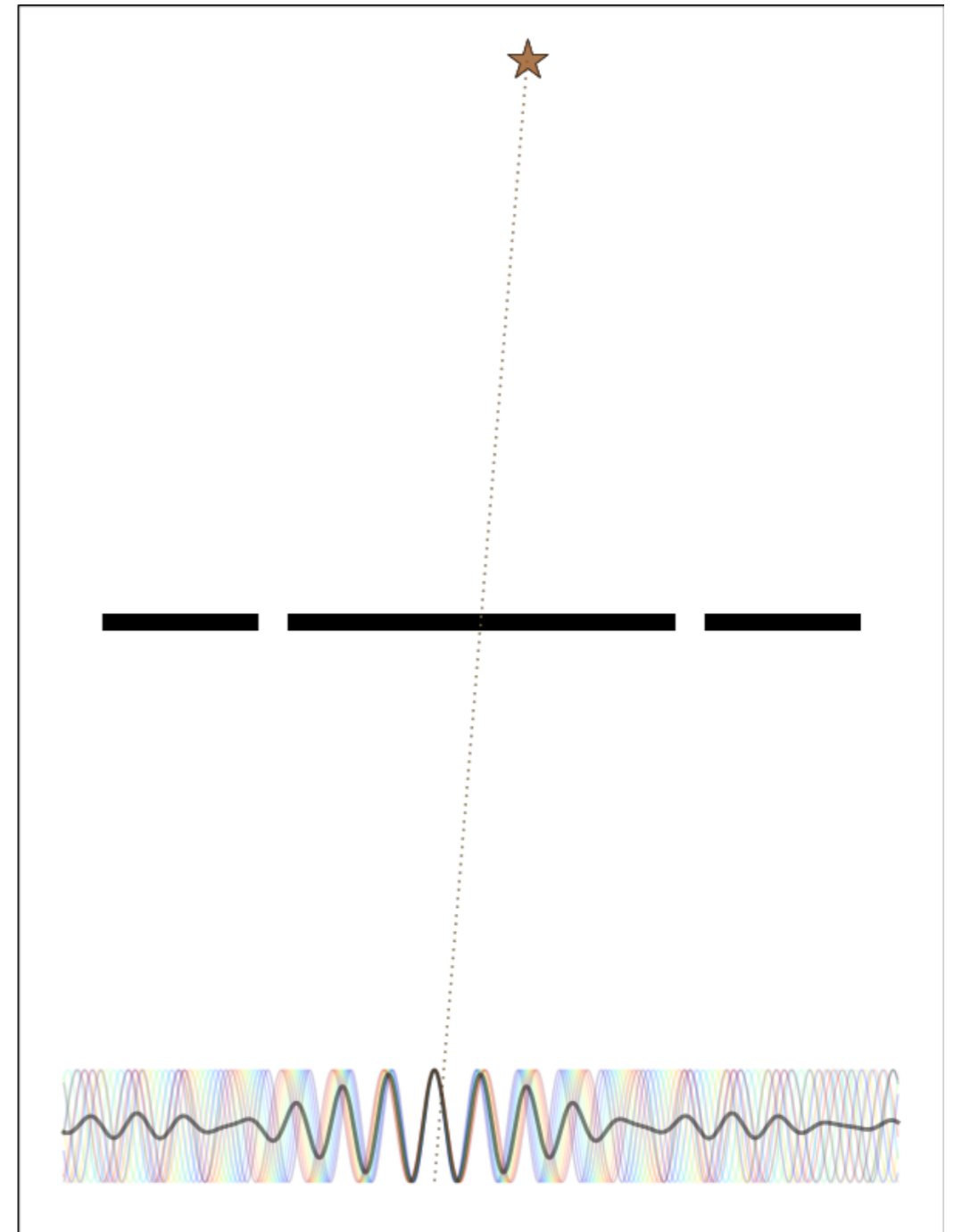






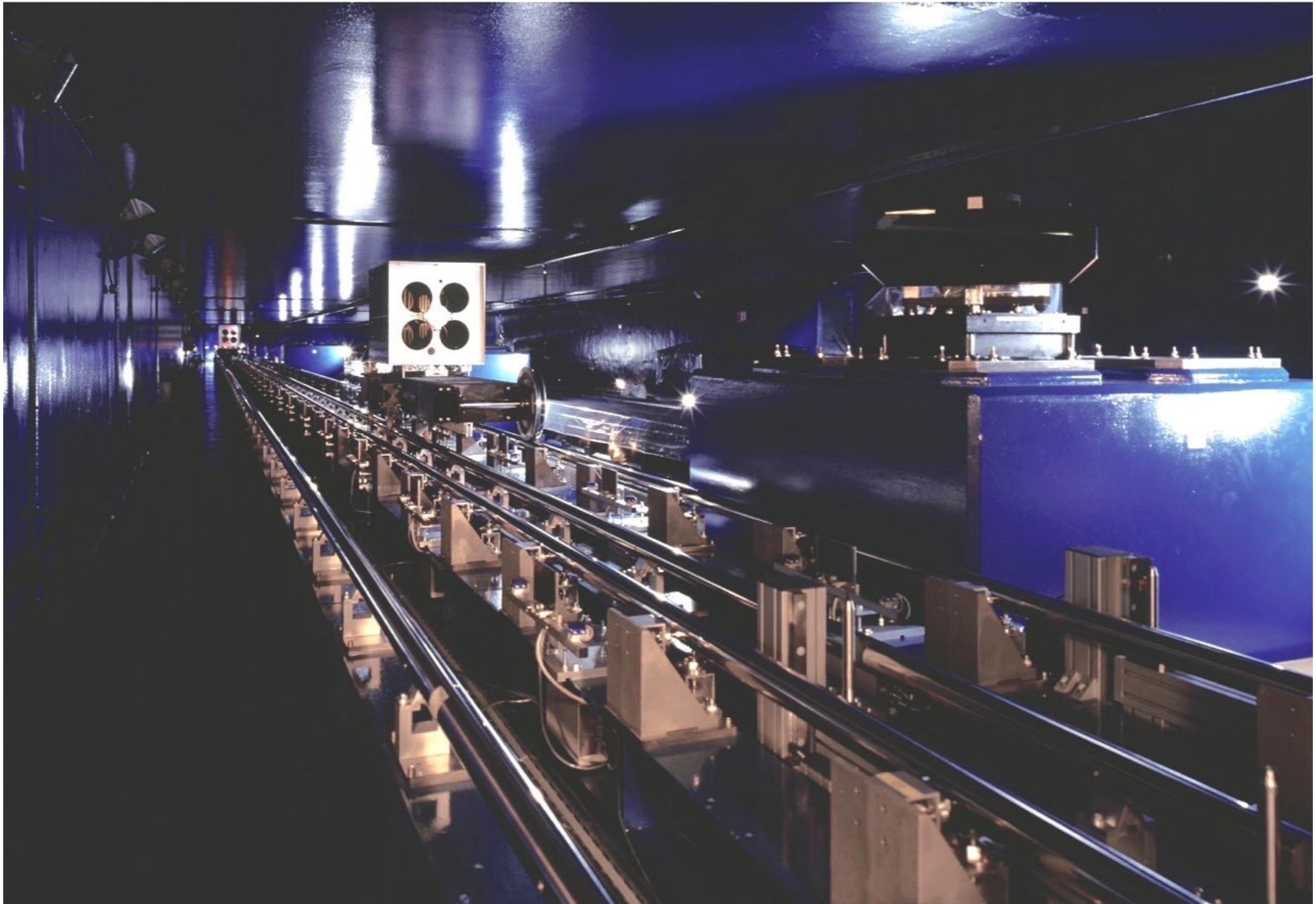
Zero-OPD

- Non-monochromatic light has a finite **coherence length**
- Real instrument observes **fringe packets**
- Delay lines are used to maintain **zero-OPD**





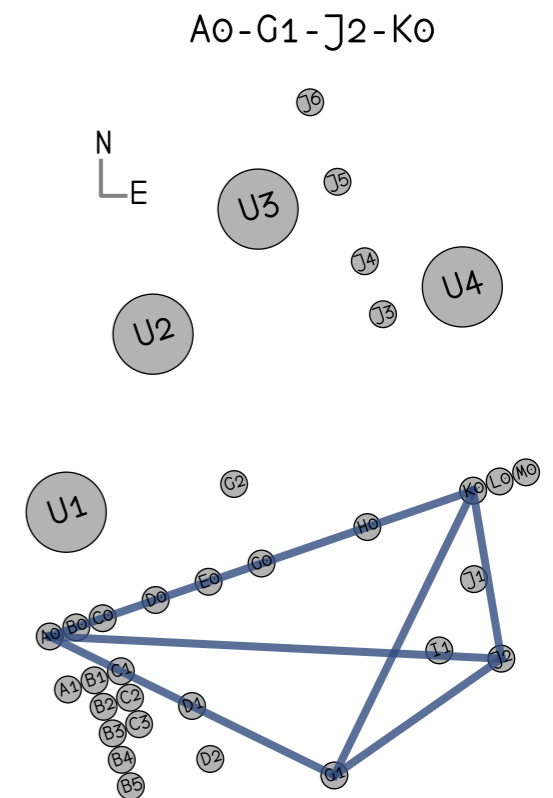
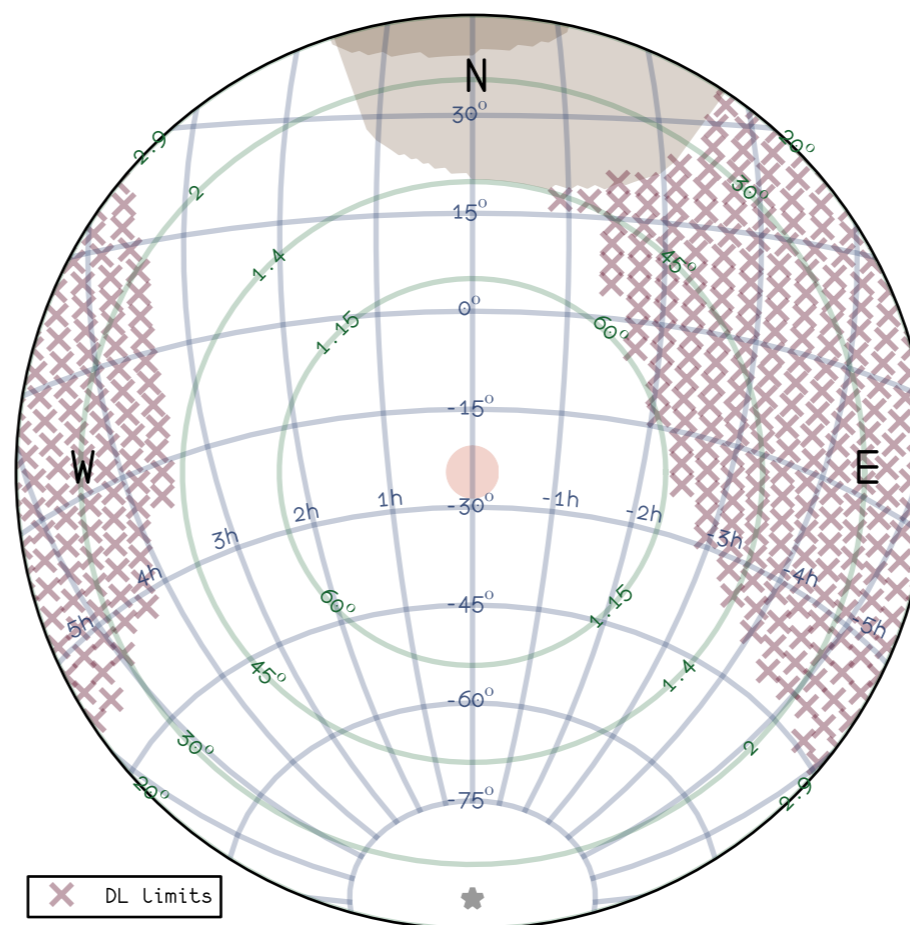
Delay Lines





Sky access

- Full sky access requires delay lines length $\sim 2B$
- Delay Line have limited stroke





Telescopes



VLTI UT



VLTI AT



VLTI MACAO (+CIAO)



Field of view?





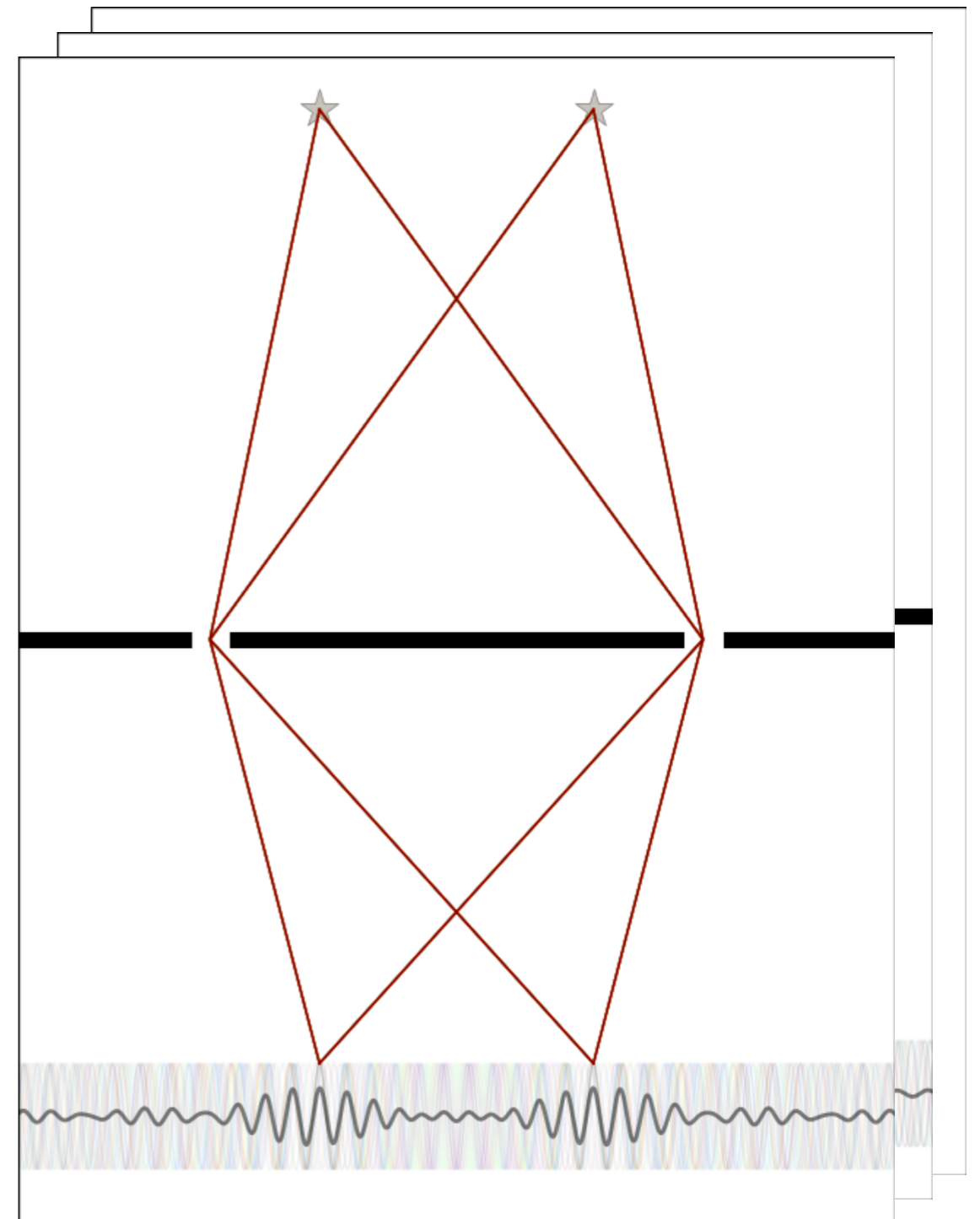
Field of view 1

- Most instruments use **single mode fibers** to clean the incoming wave front of each telescope
- The field of view of the fiber matches the **diffraction pattern of the telescope**
- In practice, the field of view of an interferometer is **λ/D**



Field of View 2

- Non-monochromatic light has a finite **coherence length**
- A binary target will produce **fringe amplitude modulation** if within the coherence length
- This limit depends on the **spectral resolution**





Take home message

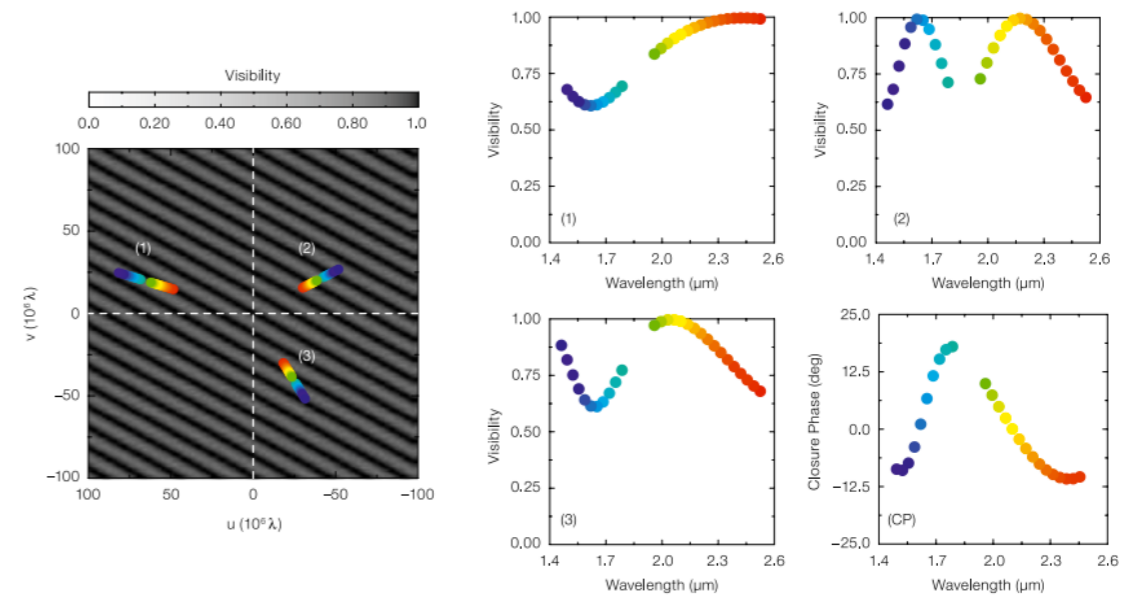
- Interferometry is not a straightforward technique...
- Angular resolution of optical interferometry is unmatched
- Understanding the technique and its limitations leads to better (realistic) proposals
- A minimum of understanding is also required to interpret correctly the data you (will) have at hands





in a few words

- An interferometer is a band pass filter for angular frequencies
- “Imaging” requires numerical image reconstruction
- Astrophysical results are obtained using advanced modeling of the observed object and its effects on the interferometric observables



$$V(u, v, \lambda, x, y, f) = \frac{V_1(u, v, \lambda) + fV_2(u, v, \lambda)e^{2i\pi(xu+yv)/\lambda}}{1 + f}$$

