

# Imfit: A New 2D Galaxy Decomposition Code

---

Peter Erwin

Max-Planck-Institute for Extraterrestrial Physics

# Brief Outline

1. A new code for fitting images of galaxies
2. Biases in fitting low-S/N galaxy images

# Imfit: (Yet Another) 2D Image-Fitting Program

- Inspirations: GIM2D, BUDDA, GALFIT
- Modular, object-oriented design using standard C++
- Uses well-tested open-source code for:
  - Image I/O (CFITSIO — [heasarc.gsfc.nasa.gov/fitsio/](http://heasarc.gsfc.nasa.gov/fitsio/))
  - FFT-based convolution (FFTW — [www.fftw.org](http://www.fftw.org))
  - Minimization algorithms
- Special focus on making it easy to add new functions
- Multi-threaded for speed (via OpenMP and FFTW)
- Open source release (GPL)

# How to Use It

```
$ imfit --config <config-file> <image-file-to-fit> [options]
```

## Examples:

*Simplest possible use:*

```
$ imfit --config sersic+exp.dat ngc1023.fits
```

*Specify an image subsection to fit (& can use compressed images):*

```
$ imfit --config sersic+exp.dat ngc1023.fits.gz[150:300,406:800]
```

*Specify a mask and a PSF image (to convolve with):*

```
$ imfit --config sersic+exp.dat ngc1023.fits --mask=ngc1023_mask.fits  
--psf=psf_for_n1023.fits
```

*Specify names for output files (best-fit parameters, model image, residual image)*

```
$ imfit --config sersic+exp.dat ngc1023.fits --save-params  
best_fit.dat --save-model best_fit.fits --save-residual resid.fits
```

# Speed

Single-threaded mode: typically ~ 50% faster than GALFIT 3  
(using  $\chi^2$  minimization with L-M algorithm for both)

BUT:

Multithreaded image computation (using OpenMP)

Multithreaded PSF convolution (FFTW library)

Typical speedup is ~3–4 × single-thread speed for 4-core CPU

# Speed

Single-threaded mode: typically ~ 50% faster than GALFIT 3  
(using  $\chi^2$  minimization with L-M algorithm for both)

BUT:

Multithreaded image computation (using OpenMP)

Multithreaded PSF convolution (FFTW library)

Typical speedup is  $\sim 3\text{--}4 \times$  single-thread speed for 4-core CPU

	GALFIT	Imfit: Single-thread	Imfit: Multi-thread
Sérisc + exp. fit (840 x 870 image)	44s	28s	9s
Same, w/ PSF convolution	125s	86s	30s

Timings on MacBook Pro (2011): 2.3 GHz Core i7 (quad-core)

# Components of a Model:

## Functions and Function Blocks

Model = one or more *function blocks*, each with one or more *functions*  
function = generates 2D surface-brightness distribution

All functions in function block **share same (x,y) location in image**

Multiple function blocks — e.g. multiple galaxies, or off-center components within a single galaxy (e.g. off-center bar or stellar nucleus)

As many function blocks as you like (though the fit will take longer!)

## Parameter Constraints

Individual parameters can be held *fixed*, or restricted to lie within upper and lower values

Indicated by (optional) extra notes on the same line as the parameter's initial value

# Example of Configuration File

```
# A function block with one function (Sersic); all parameters
# are unconstrained
x0    129.0
y0    129.0
FUNCTION Sersic
PA     18.0
ell    0.2
n      1.5
I_e    15
r_e    25
```

# Example of Configuration File

```
# A function block with one function (Sersic); all parameters
# are unconstrained
X0    129.0
Y0    129.0
FUNCTION Sersic
PA     18.0
ell    0.2
n      1.5
I_e    15
r_e    25

# Another function block with two functions (Sersic & Exp.)
# (Note that parameter values for these functions have limits)
X0    231.0    230,240      # x-value: lower limit, upper limit
Y0    307.0    300,310
FUNCTION Sersic
PA     18.0    0,90
ell    0.1     0,1
n      4.0     fixed        # this parameter's value is constant
I_e    100     0,500
r_e    30      0,100
FUNCTION Exponential
PA     18.0    0,90
ell    0.5     0.3,0.8
I_0    15      0,500
h      25      # no limits for scale length
```

# Function Objects

FunctionObject = abstract base class

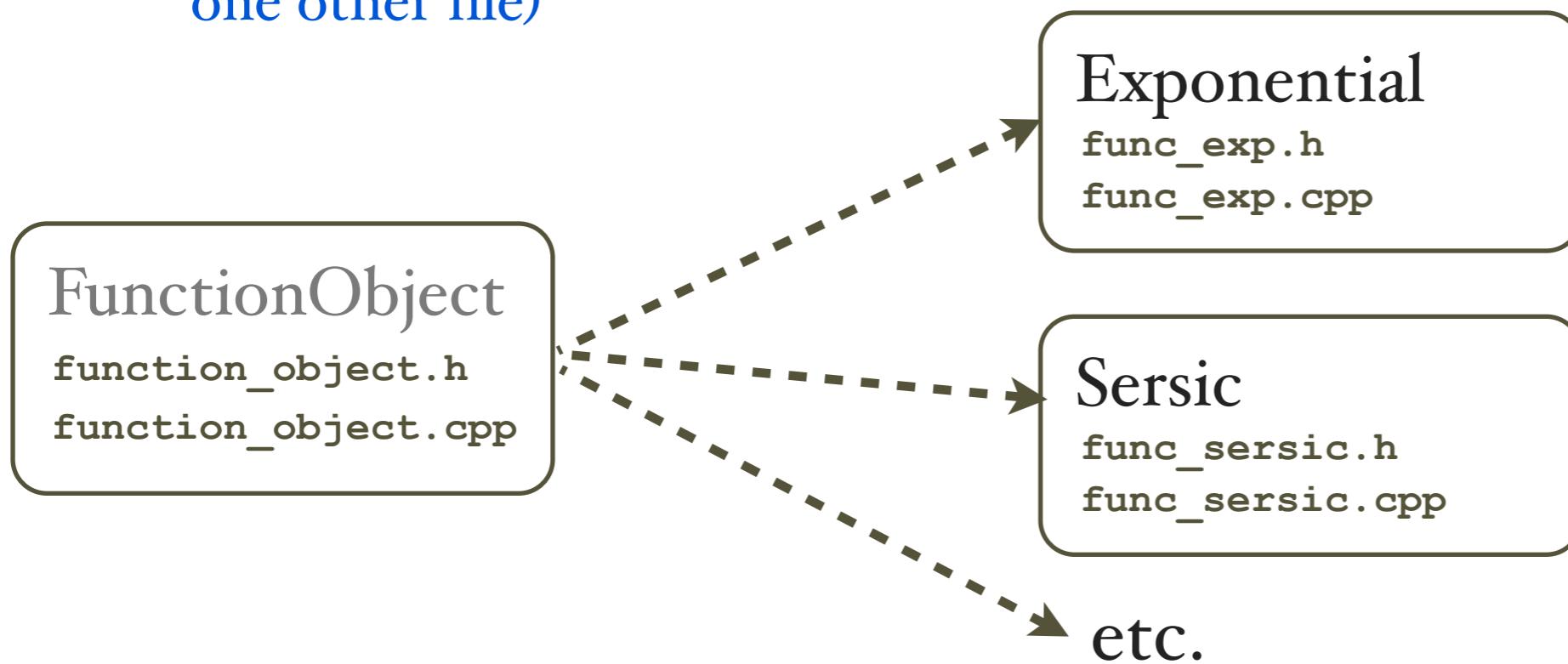
All 2D image functions are derived classes of FunctionObject

Returns pixel intensity value, given pixel coordinates and current parameters for that function

Handles pixel subsampling, geometric transforms as needed

Rest of program doesn't need to know details of how they work

Easy to write new functions: only 2 files (plus minor modification of one other file)



# Some of the Built-in Functions

Gaussian

Moffat

Sérsic w/ generalized ellipse (boxy/disk isophote shape)

Exponential w/ generalized ellipse (boxy/disk isophote shape)

# Some of the Built-in Functions

Gaussian

Moffat

Sérsic w/ generalized ellipse (boxy/disk isophote shape)

Exponential w/ generalized ellipse (boxy/disk isophote shape)

Broken Exponential (two slopes; Erwin+2008)

— disk breaks/truncations, antitruncations

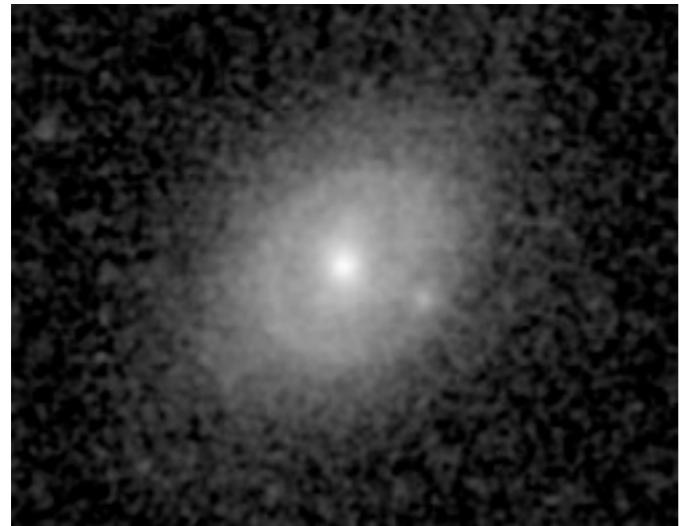
Elliptical Ring (Gaussian profile; symmetric or 2-sided)

Analytic Edge-on Disk

Edge-on Ring (symmetric & 2-sided)

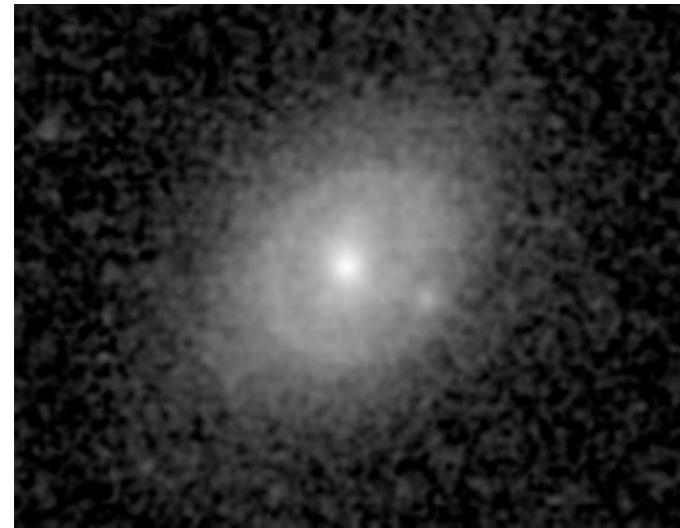
Elliptical Core-Sérsic (Graham+2003; Trujillo+2004)

# Example: Barred, Ringed Galaxy at z=0.03

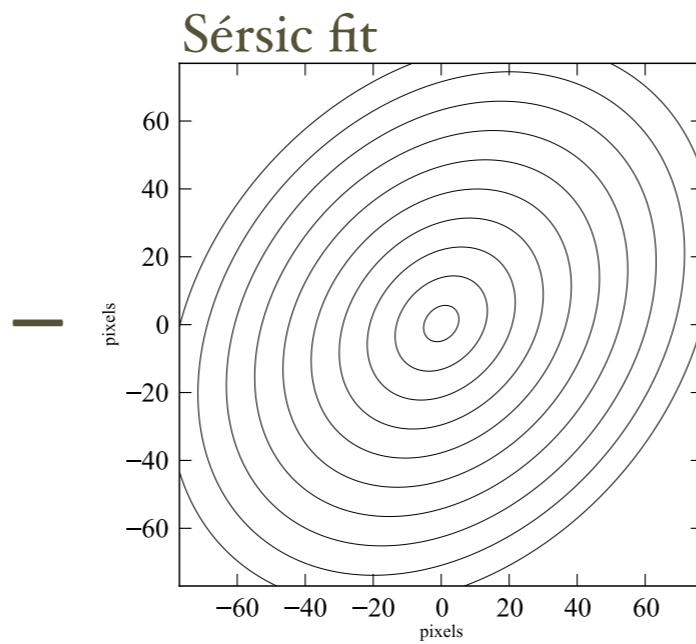


Narrow-band (*R*) continuum image

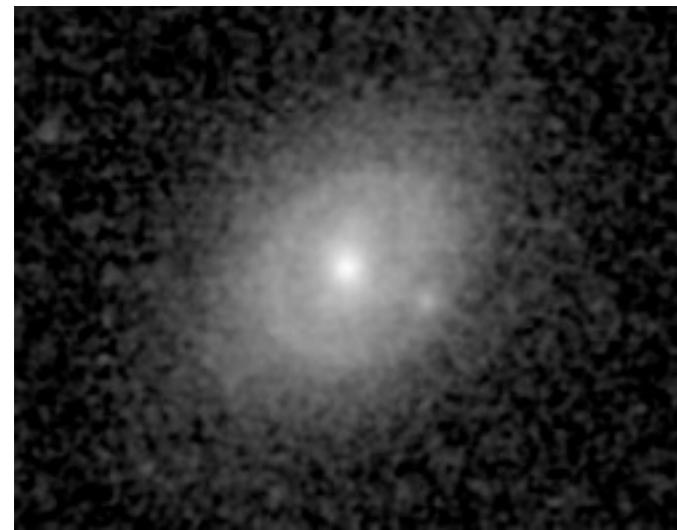
# Example: Barred, Ringed Galaxy at z=0.03



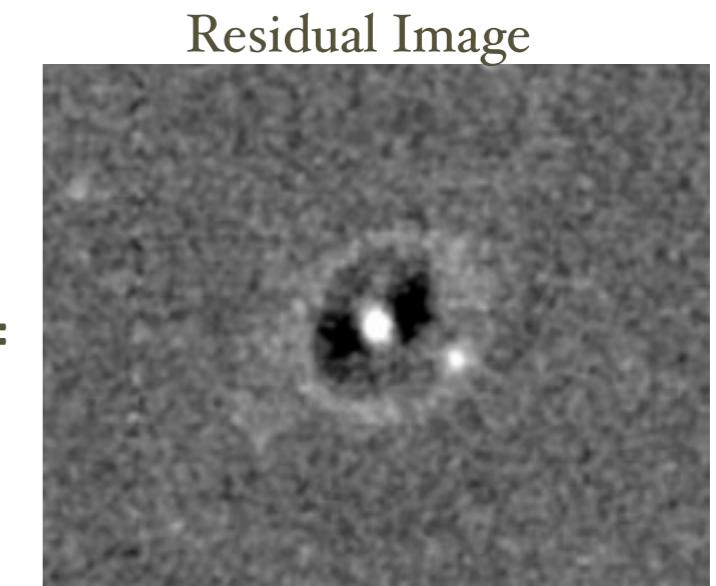
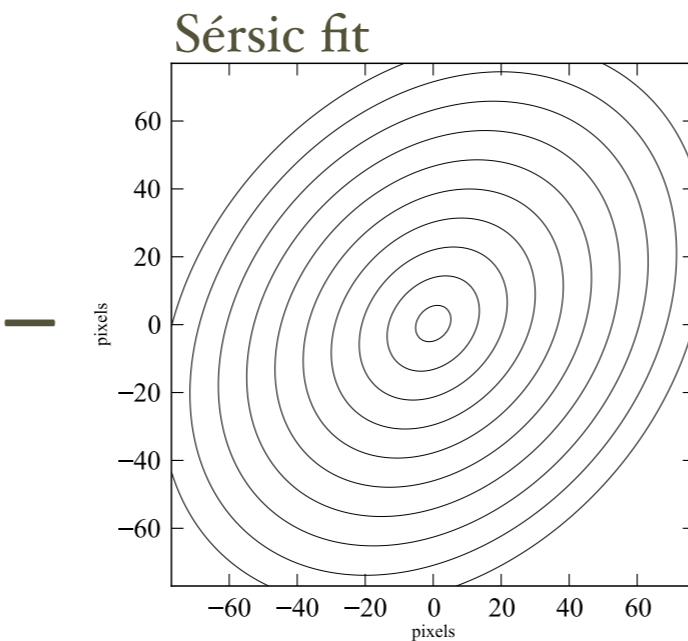
Narrow-band (*R*) continuum image



# Example: Barred, Ringed Galaxy at z=0.03

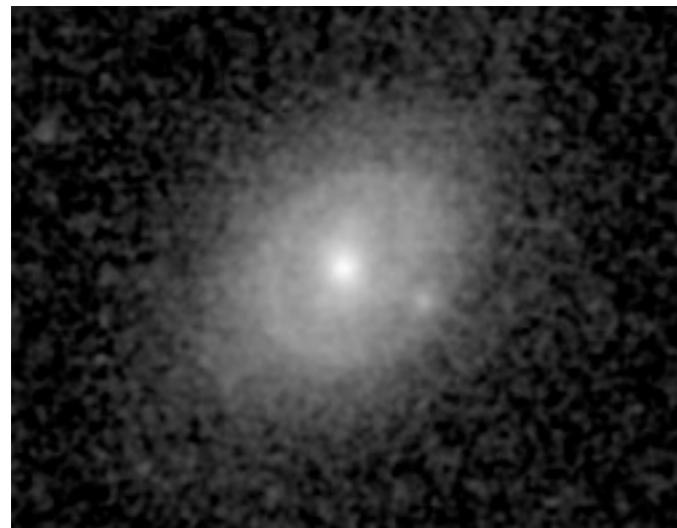


Narrow-band (*R*) continuum image

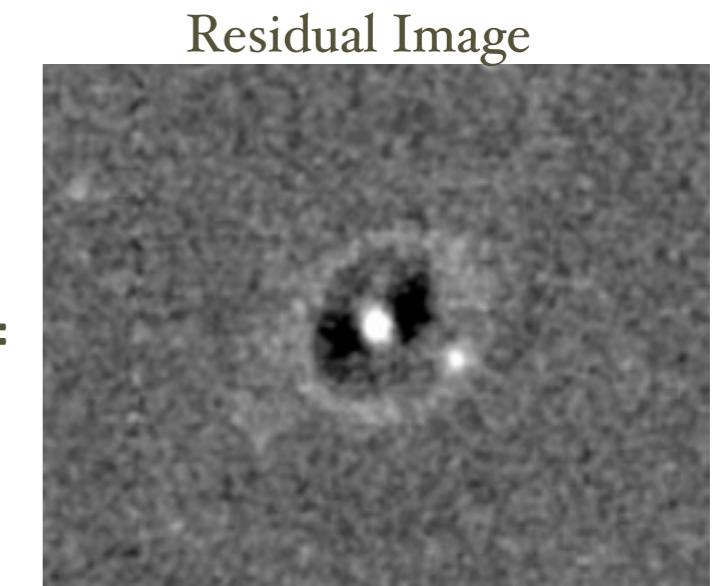
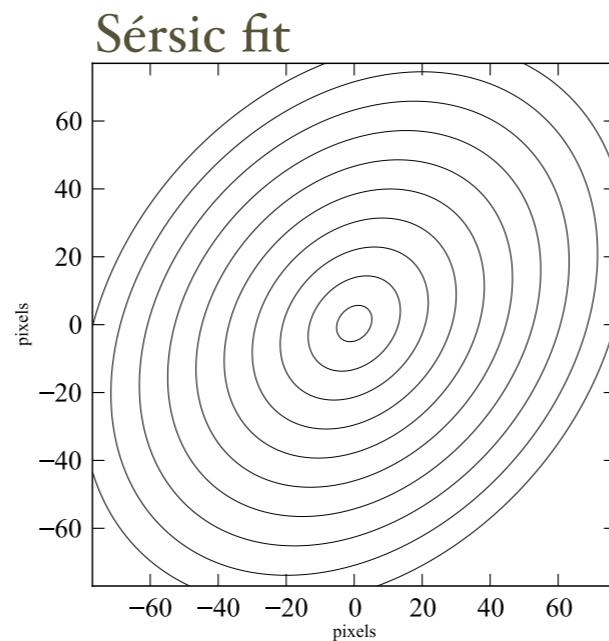


=

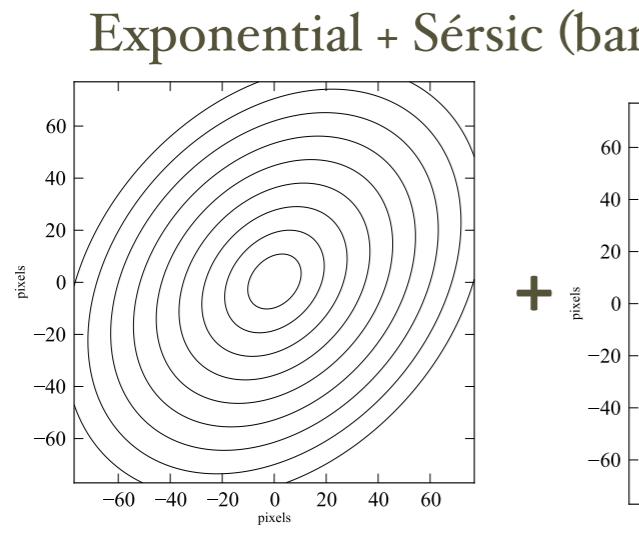
# Example: Barred, Ringed Galaxy at z=0.03



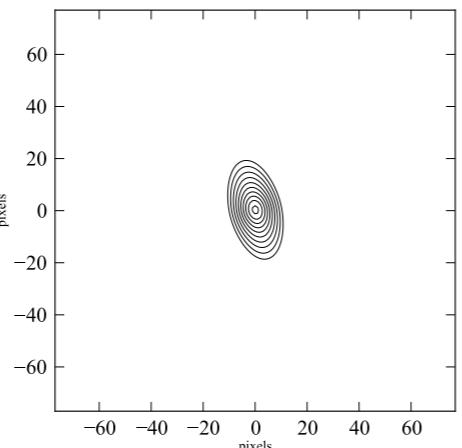
Narrow-band (*R*) continuum image



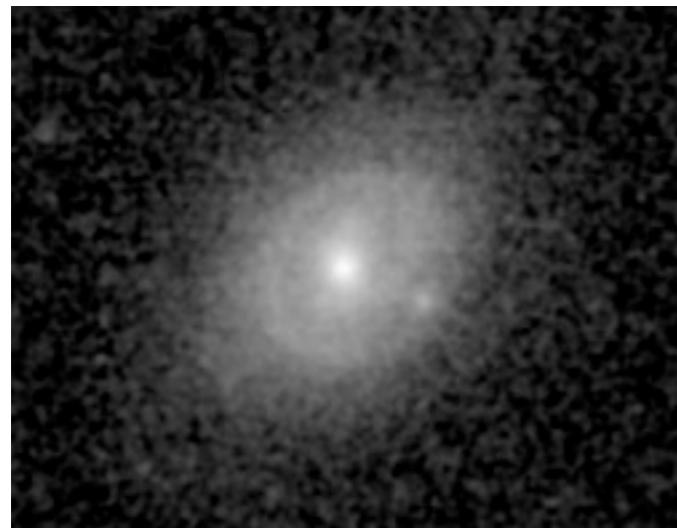
=



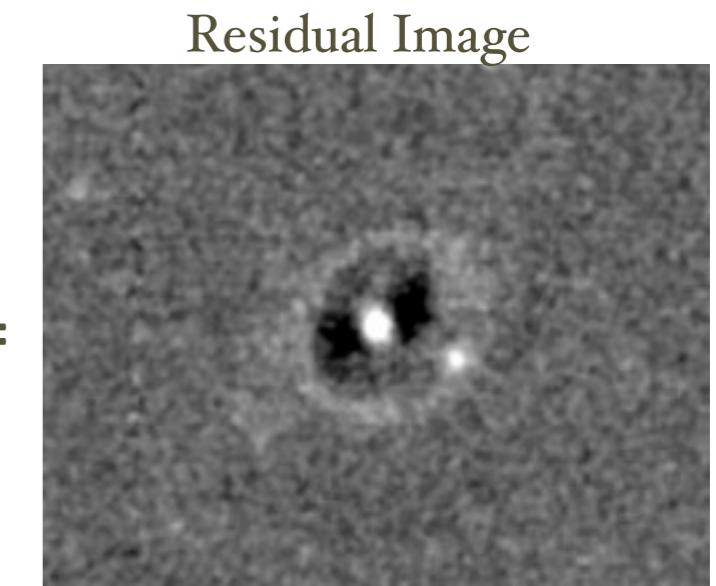
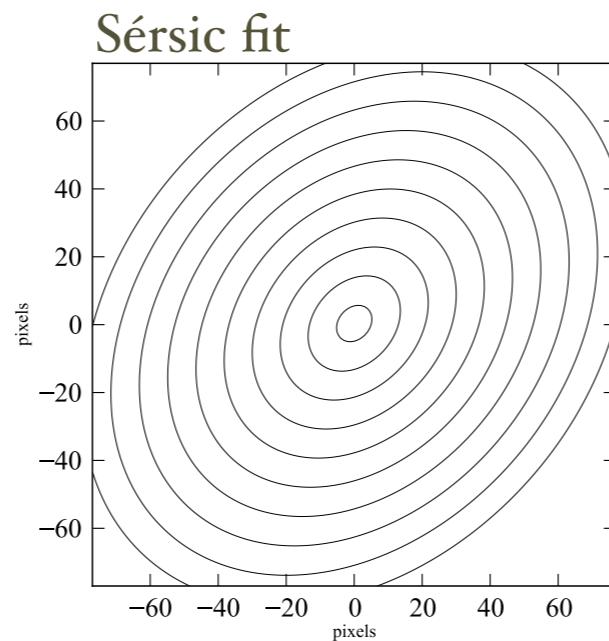
+



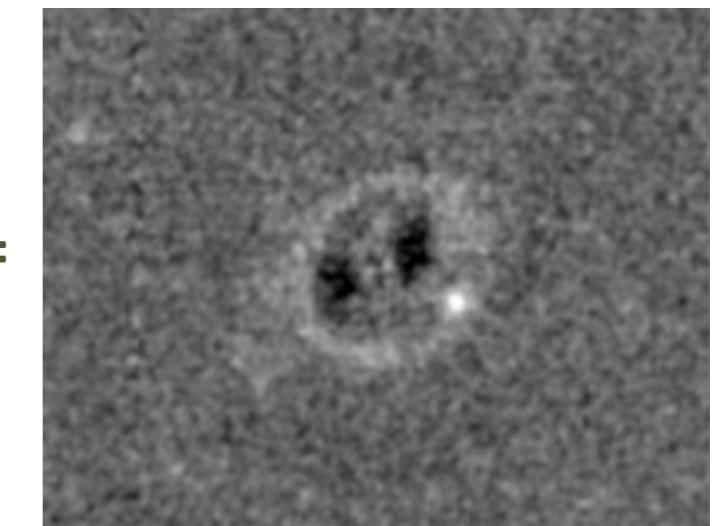
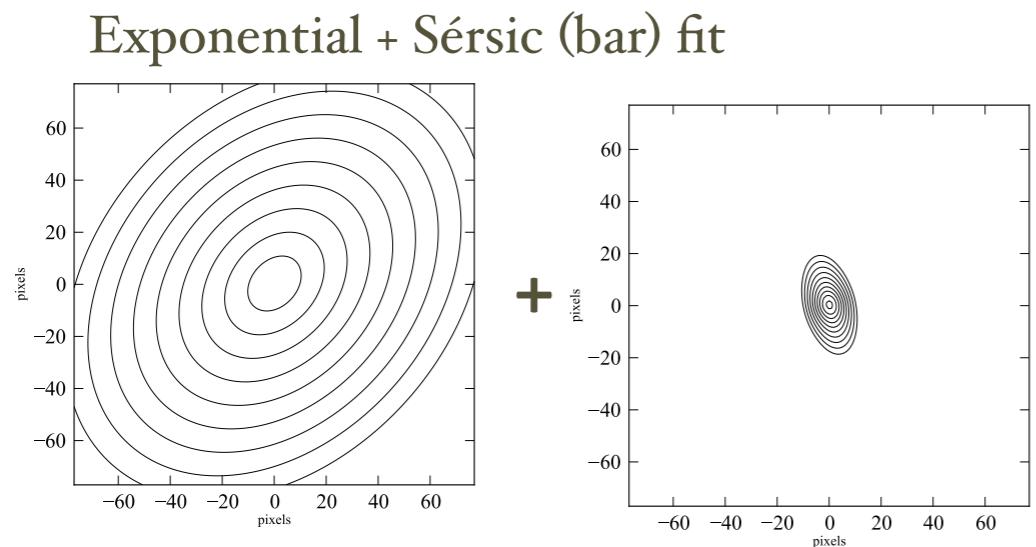
# Example: Barred, Ringed Galaxy at z=0.03



Narrow-band (*R*) continuum image

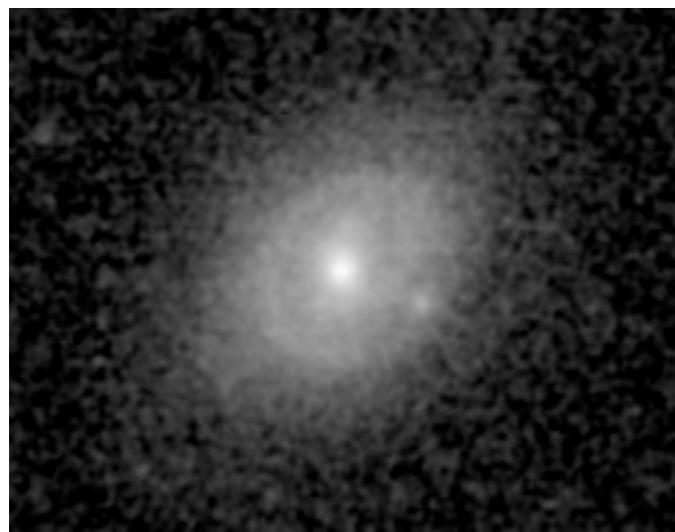


=

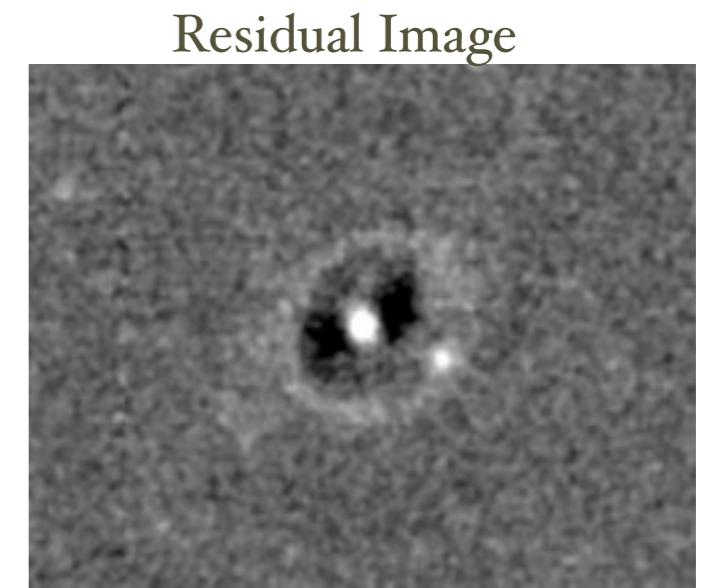
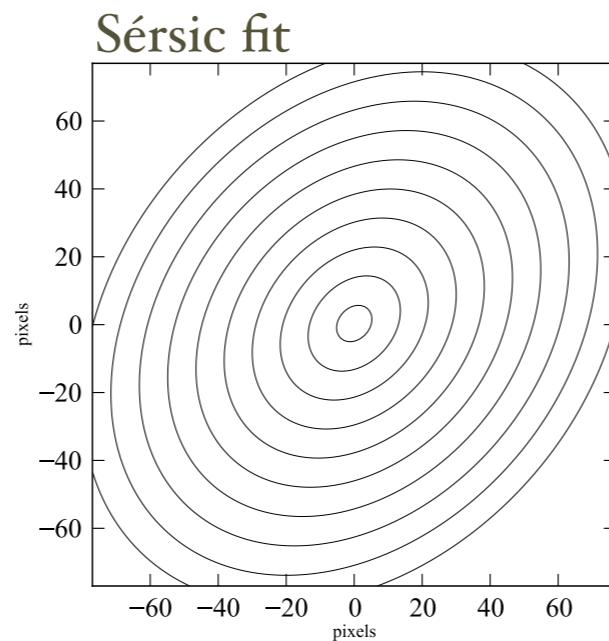


=

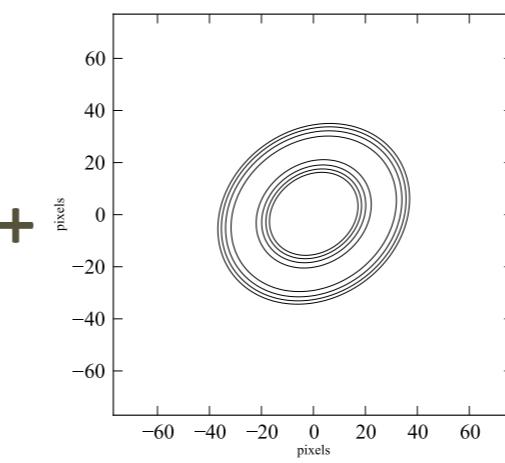
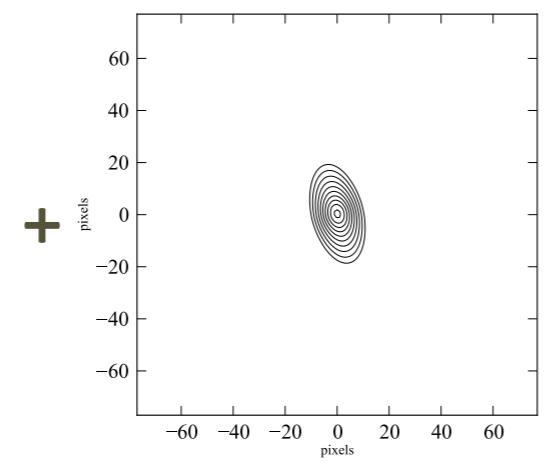
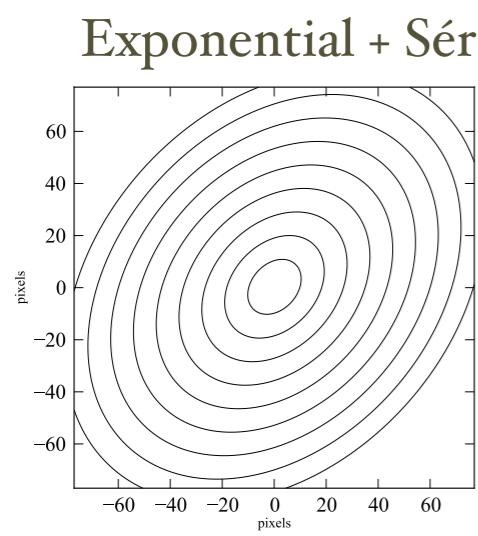
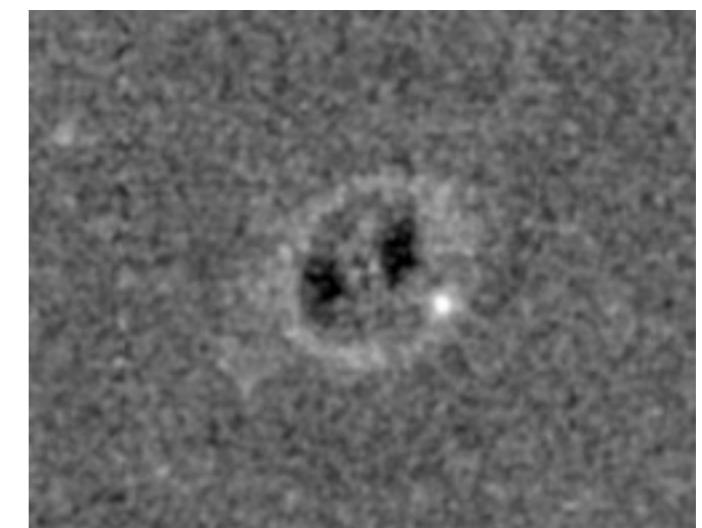
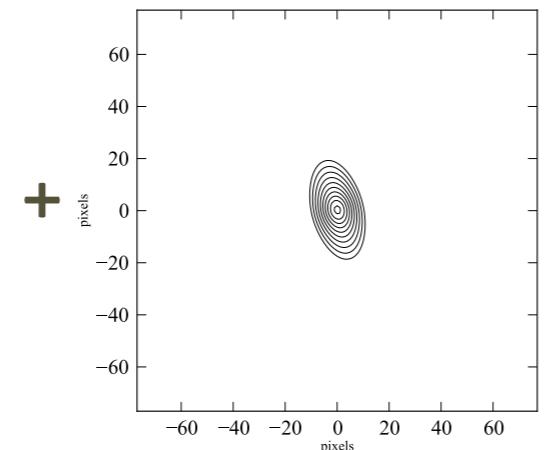
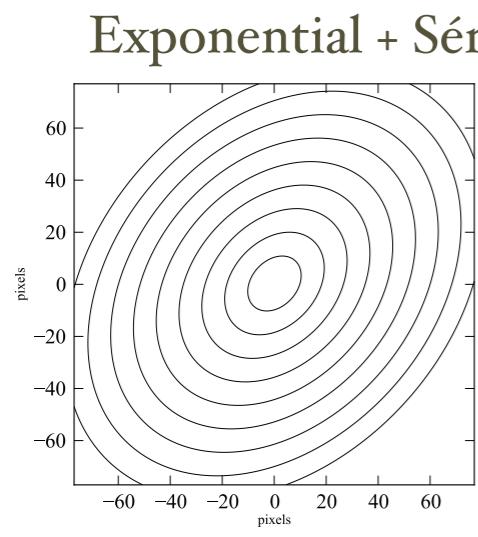
# Example: Barred, Ringed Galaxy at z=0.03



Narrow-band (*R*) continuum image

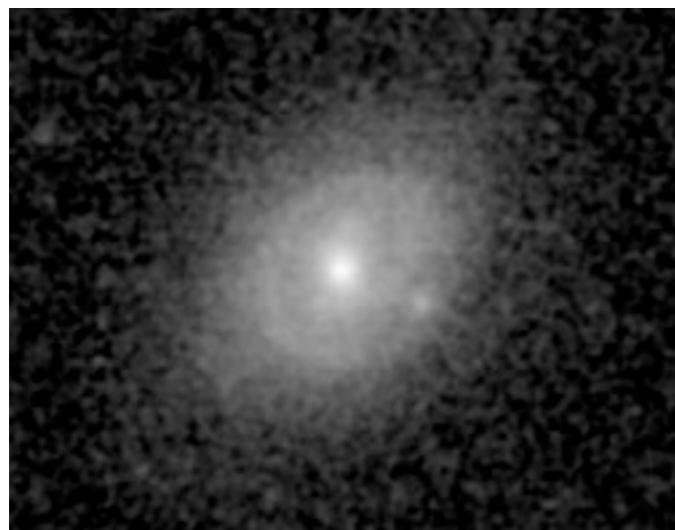


=

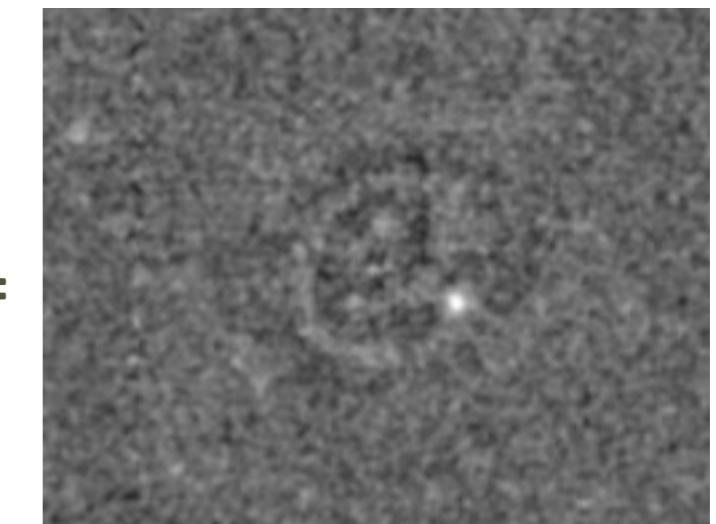
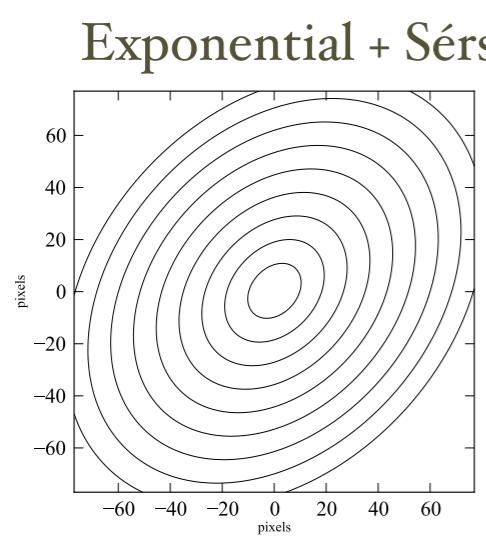
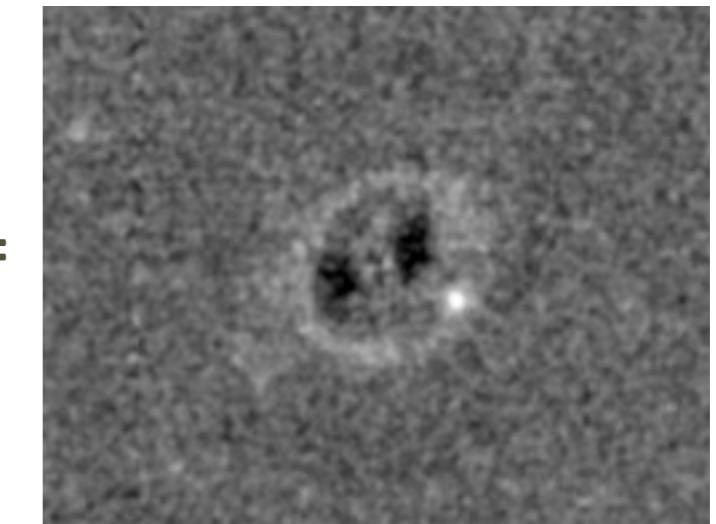
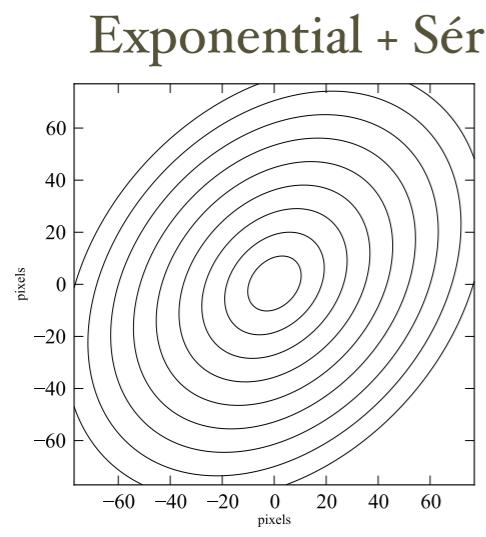
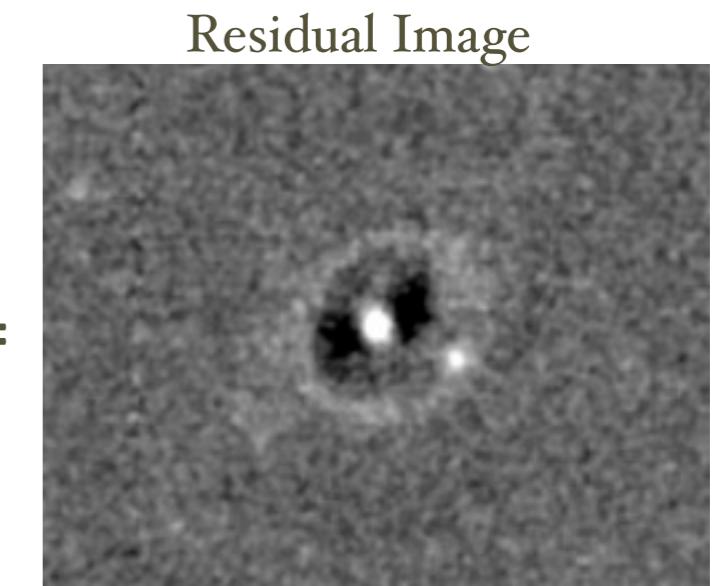
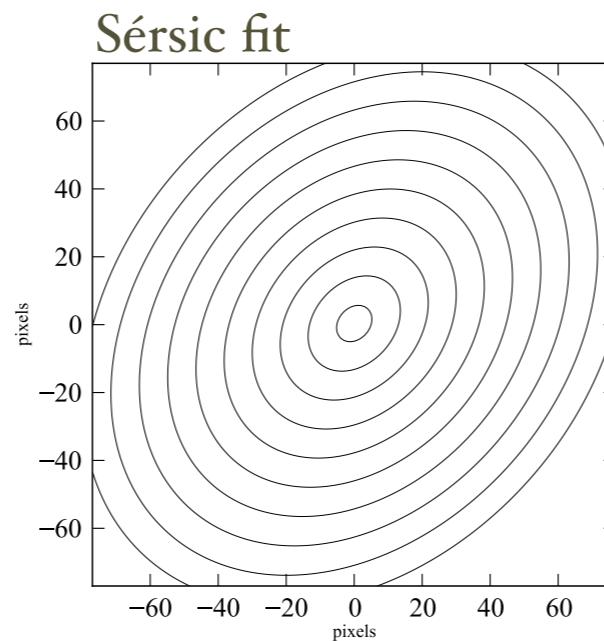


=

# Example: Barred, Ringed Galaxy at z=0.03



Narrow-band ( $R$ ) continuum image



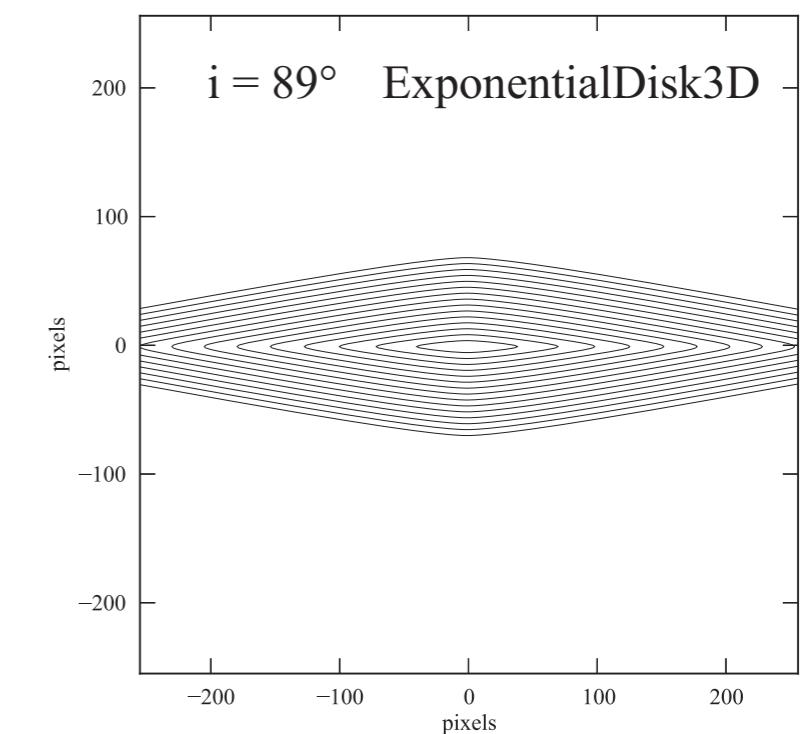
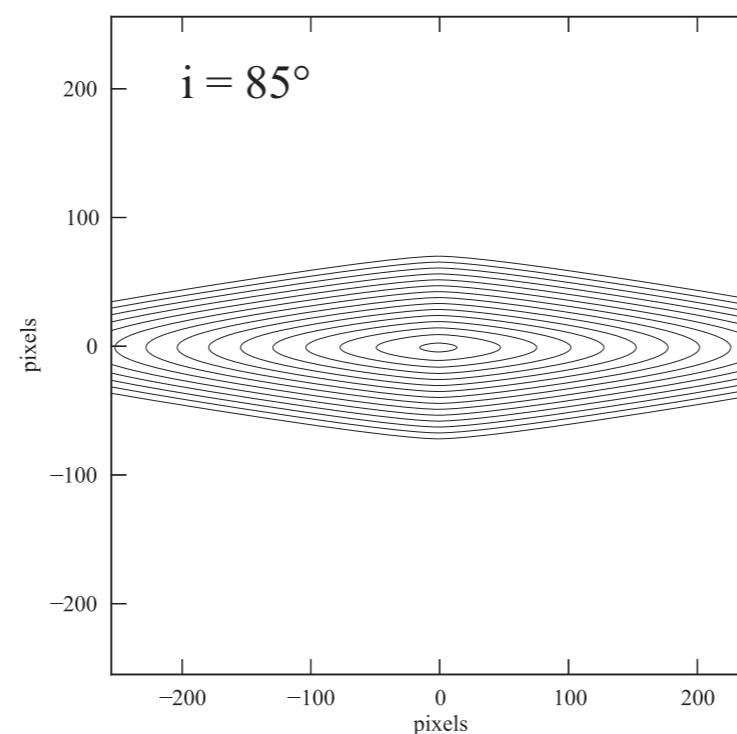
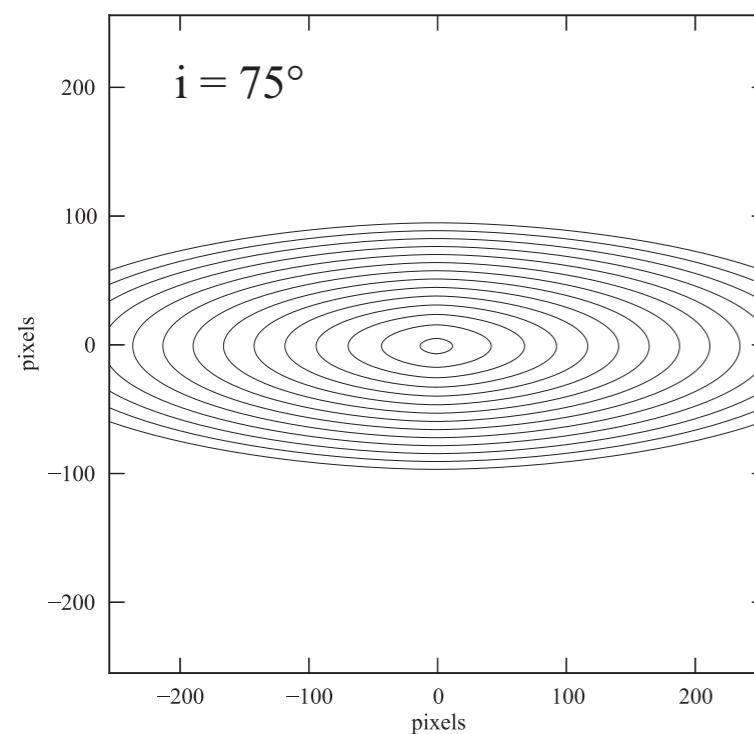
# 3D Integration Functions

Each pixel = Line-of-sight integration through  
3D luminosity-density model

Axisymmetric disk at arbitrary inclination: radial exponential  
+ generalized sech<sup>2/n</sup> vertical profile (van der Kruit 1988)

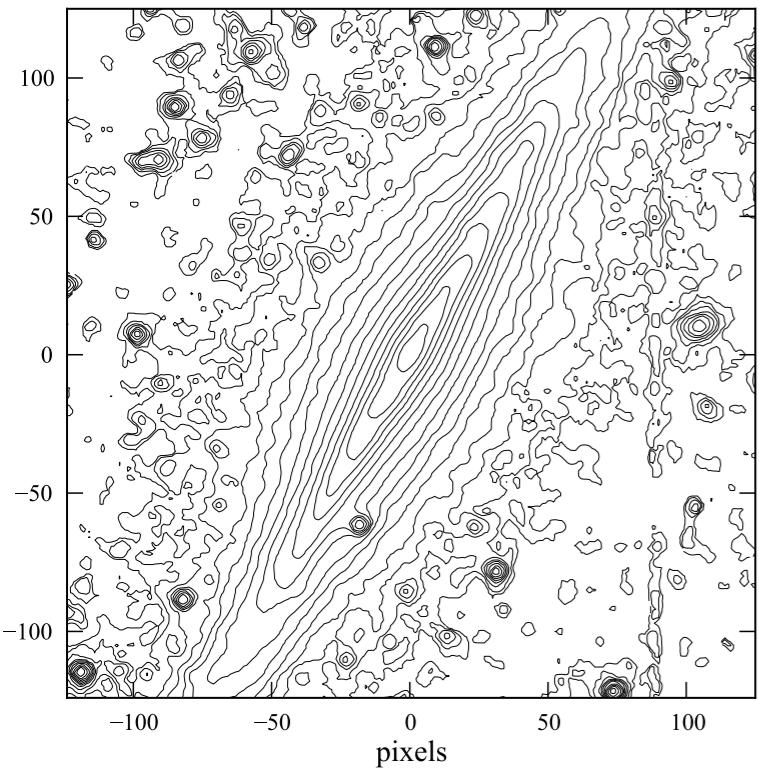
Axisymmetric broken-exponential disk

Elliptical Gaussian ring (with exponential vertical profile)



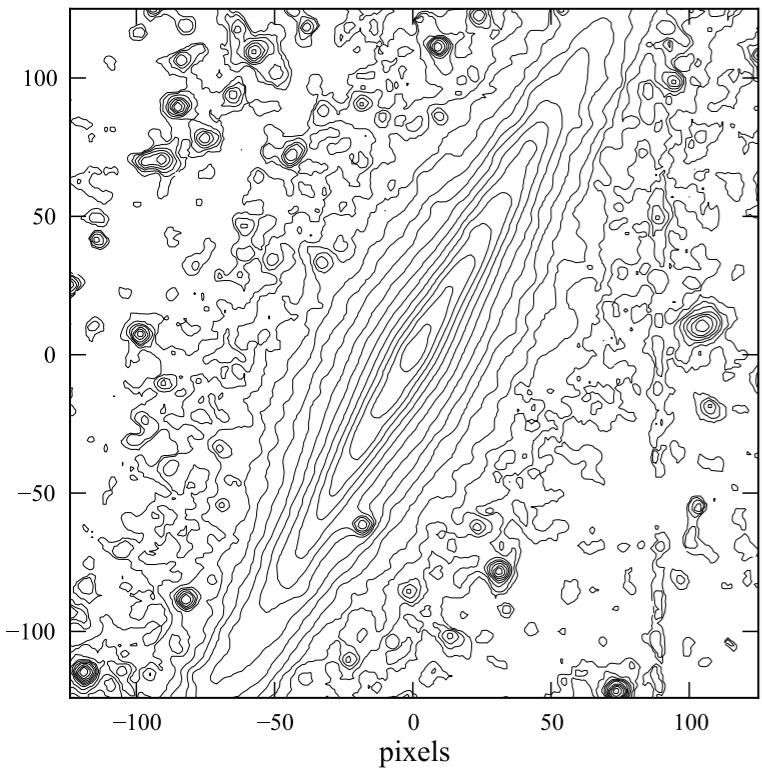
# IC 5176: Edge-on Thin + Thick Disk

Spitzer IRAC1 (3.6 $\mu$ m)

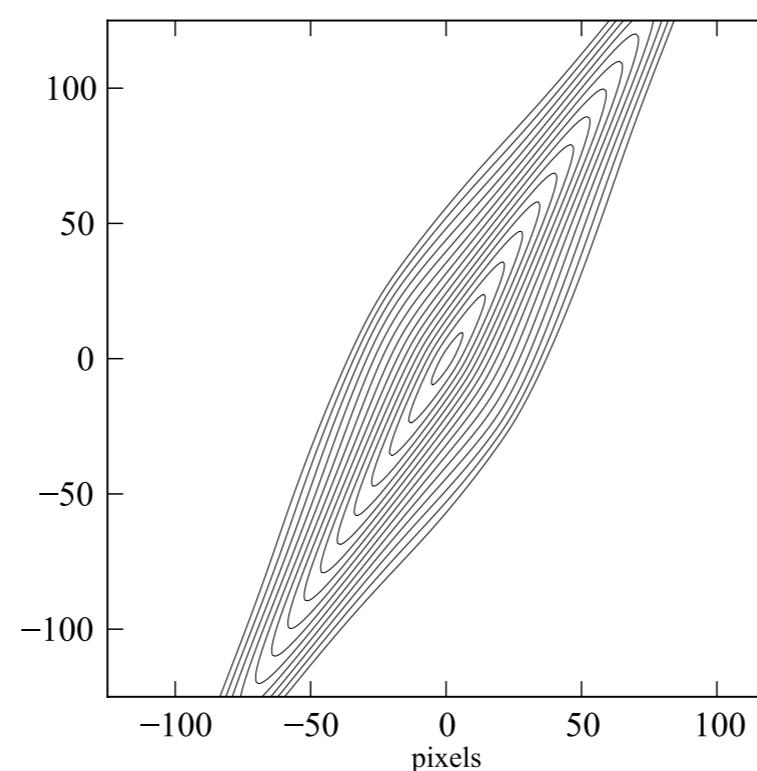


# IC 5176: Edge-on Thin + Thick Disk

Spitzer IRAC1 (3.6 $\mu$ m)

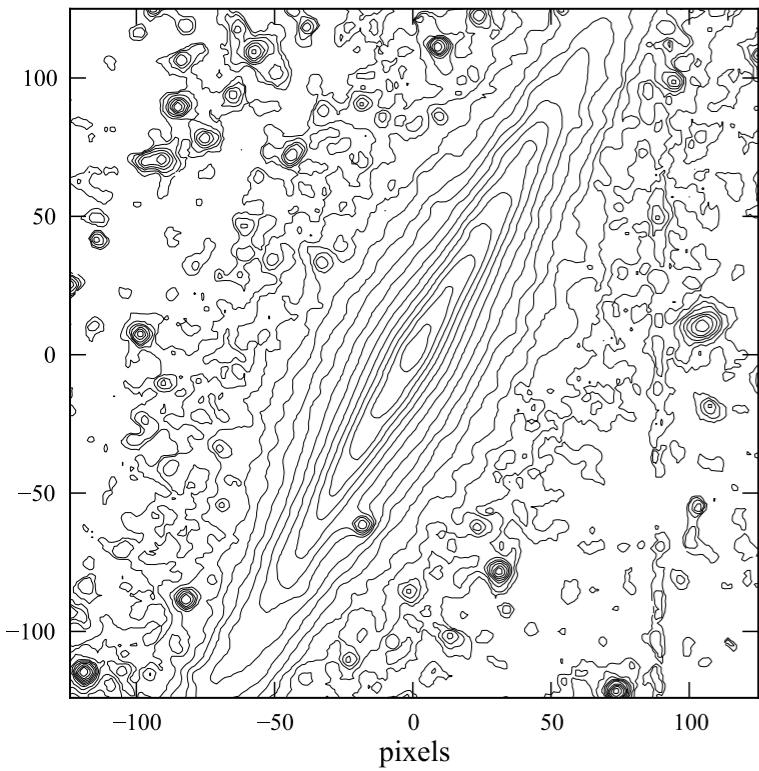


3D Thin disk

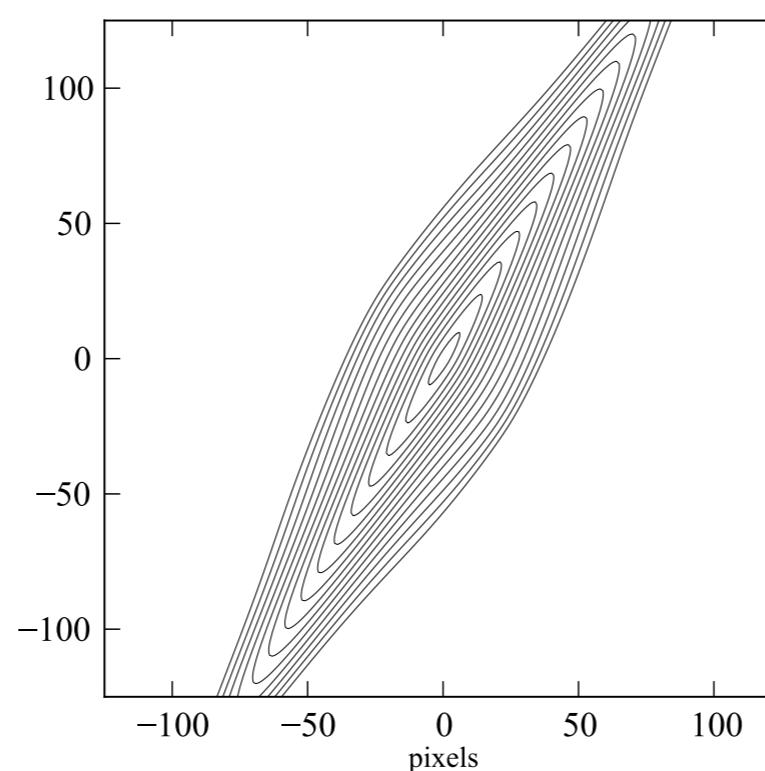


# IC 5176: Edge-on Thin + Thick Disk

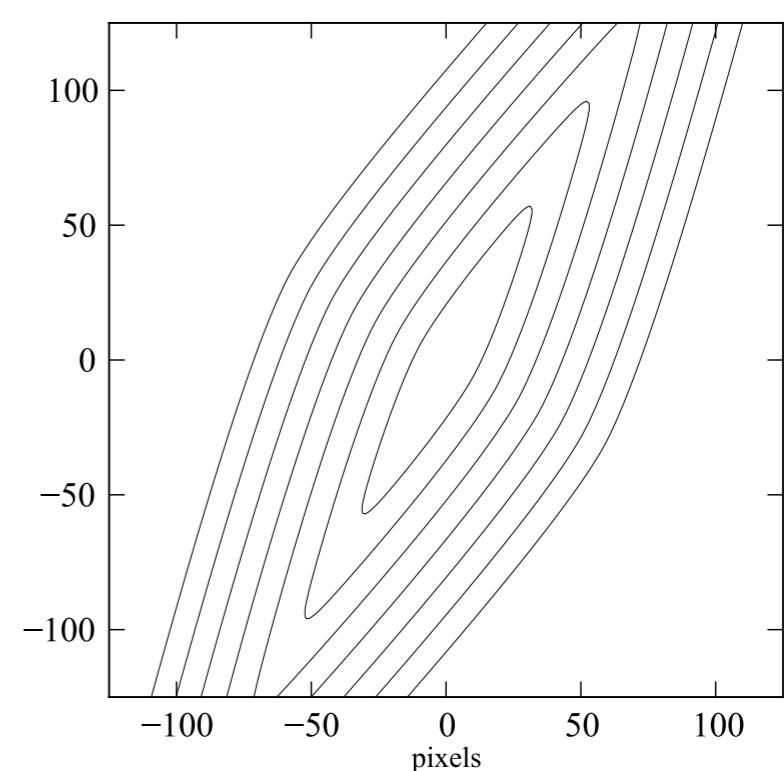
Spitzer IRAC1 (3.6 $\mu$ m)



3D Thin disk

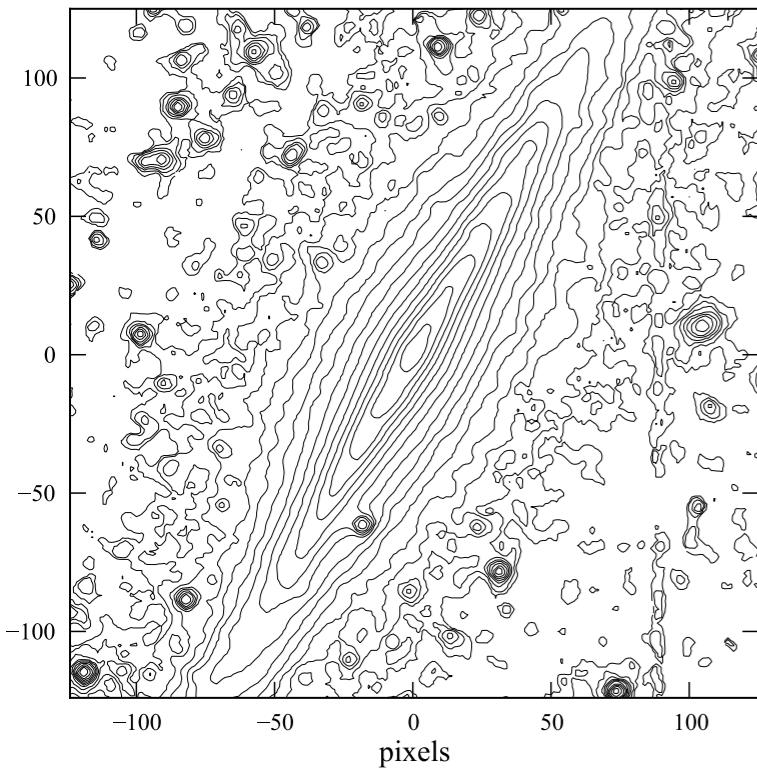


3D Thick disk

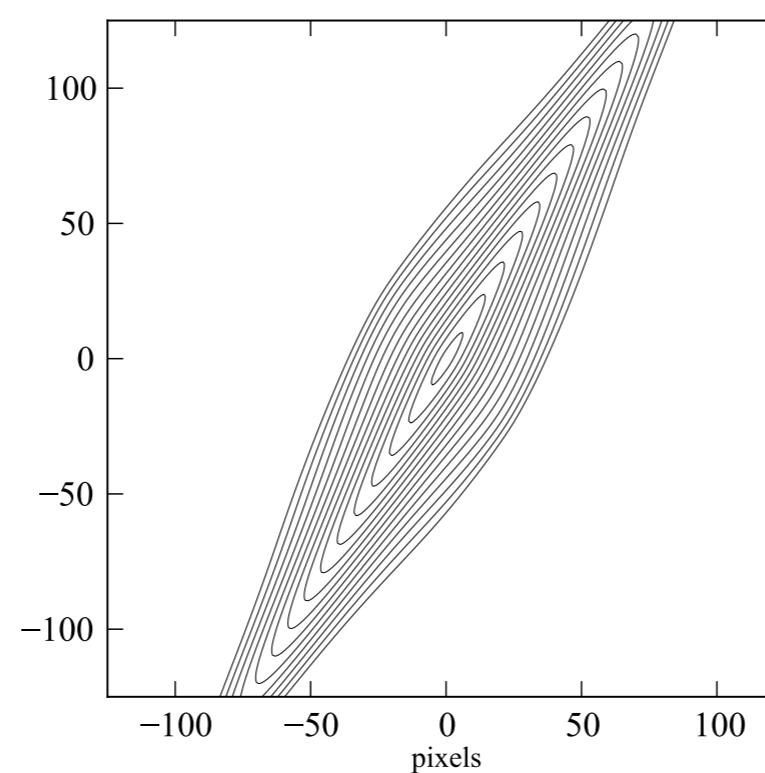


# IC 5176: Edge-on Thin + Thick Disk

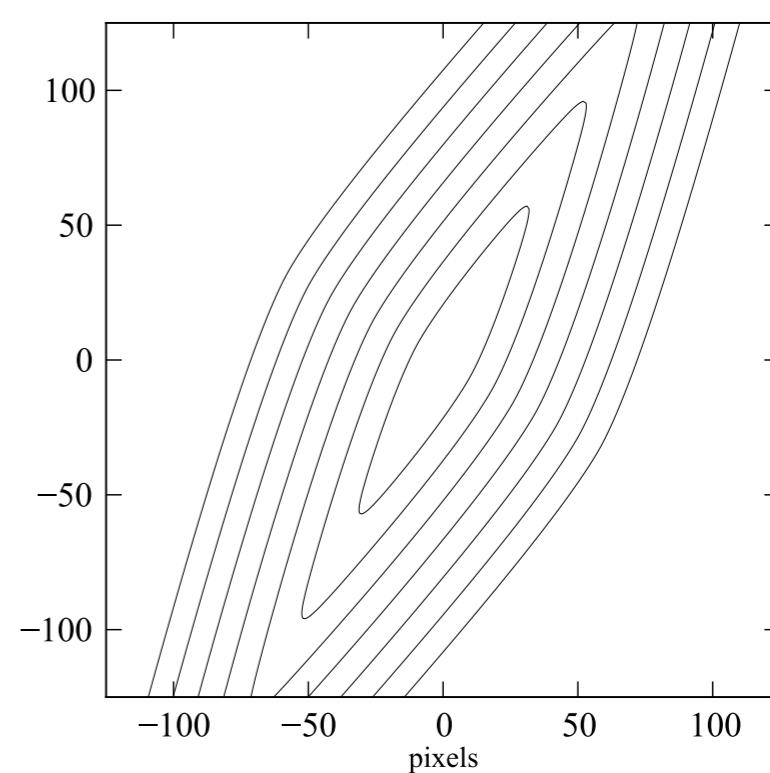
Spitzer IRAC1 (3.6 $\mu$ m)



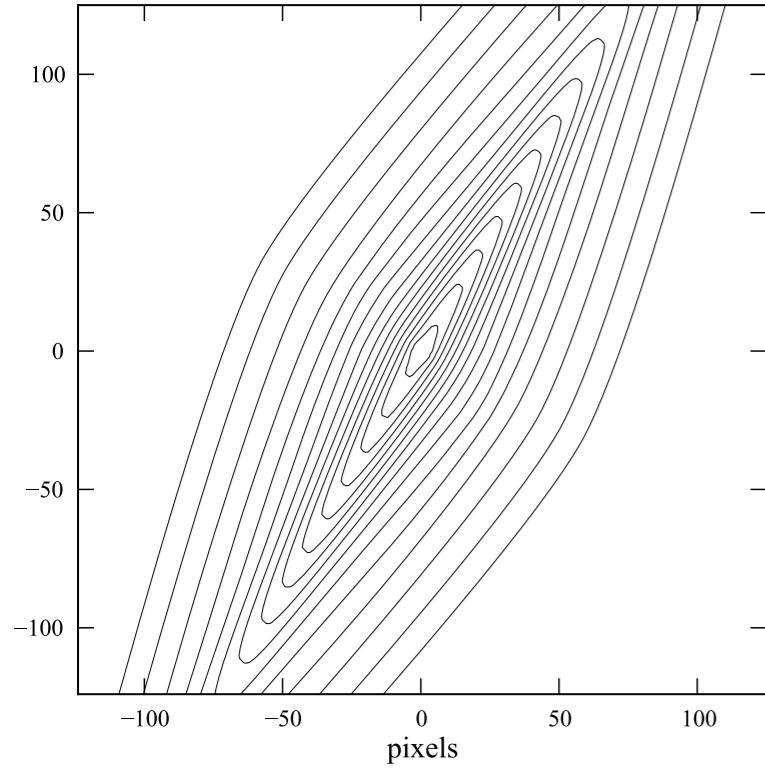
3D Thin disk



3D Thick disk

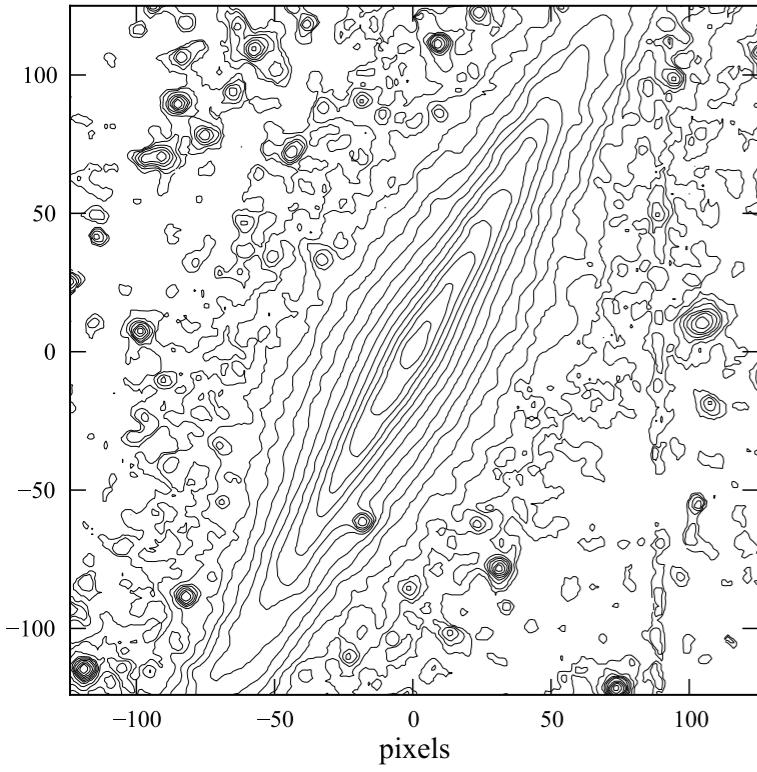


Combined model (w/ Sérsic)

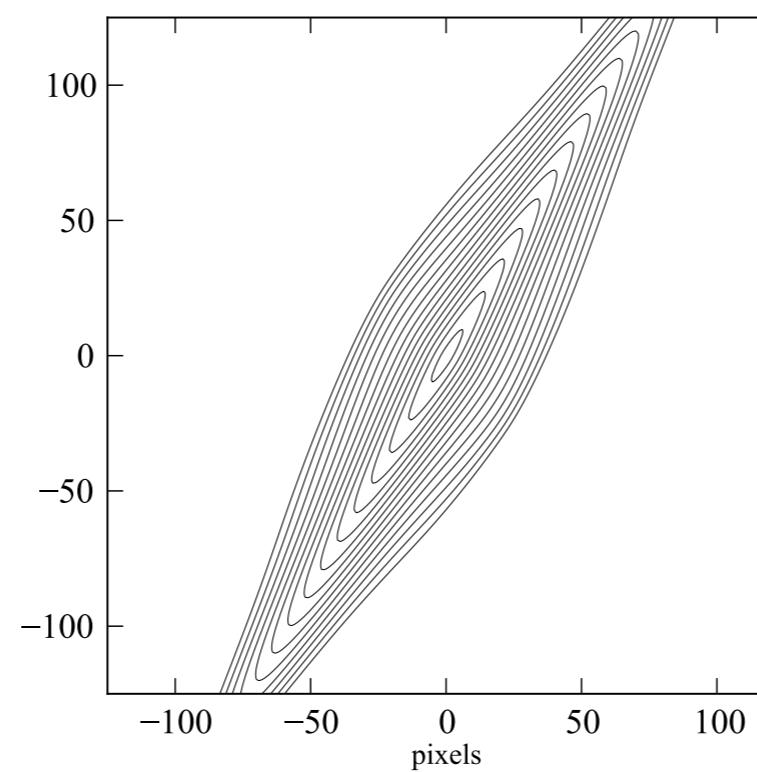


# IC 5176: Edge-on Thin + Thick Disk

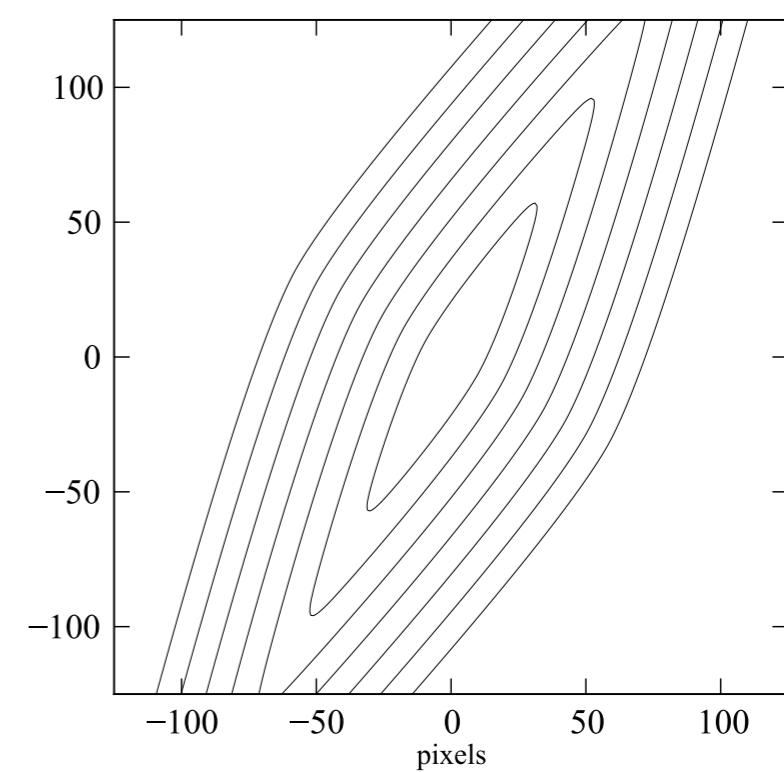
Spitzer IRAC1 (3.6 $\mu$ m)



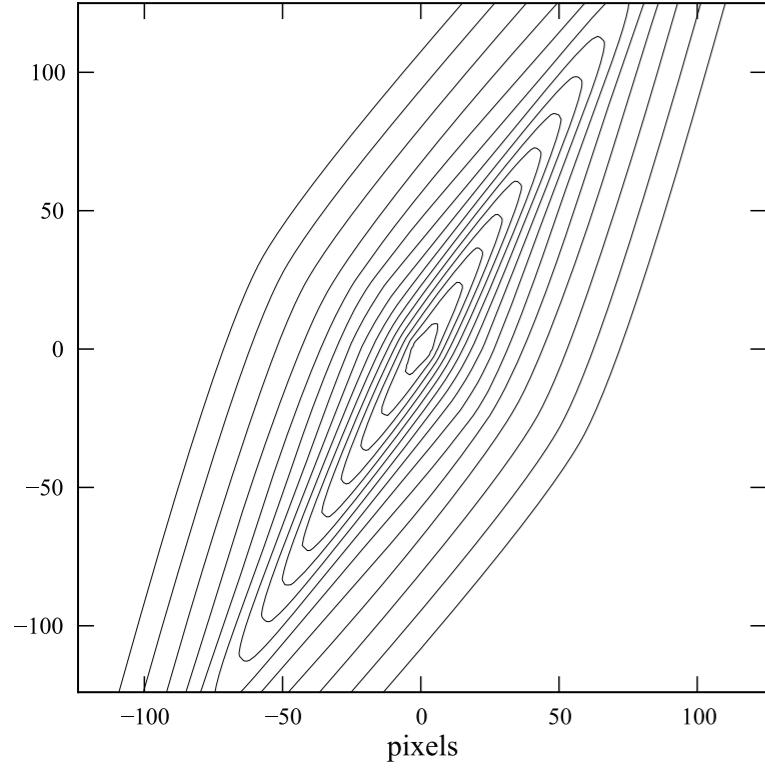
3D Thin disk



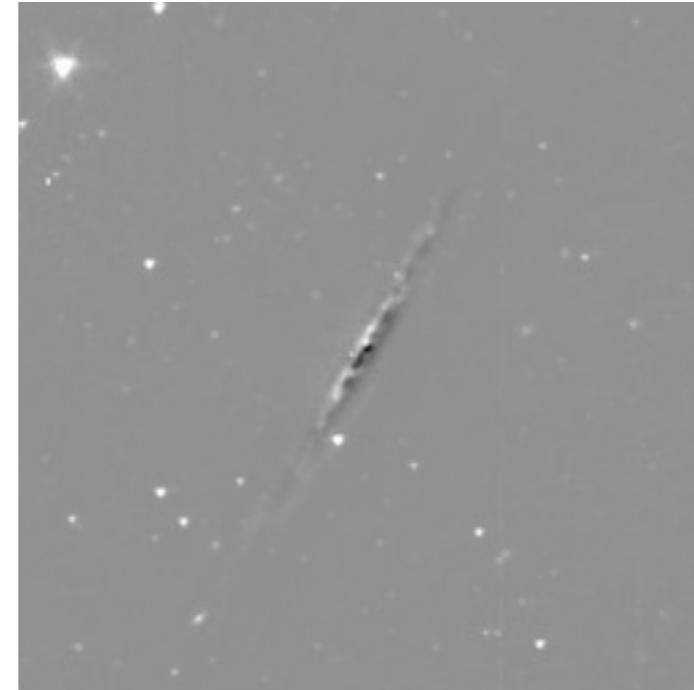
3D Thick disk



Combined model (w/ Sérsic)

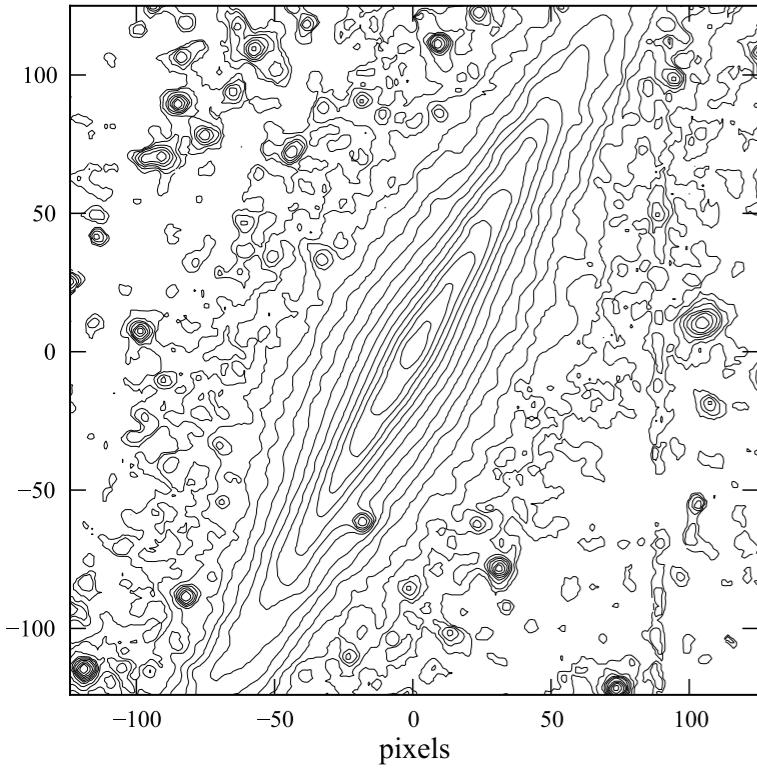


Residual

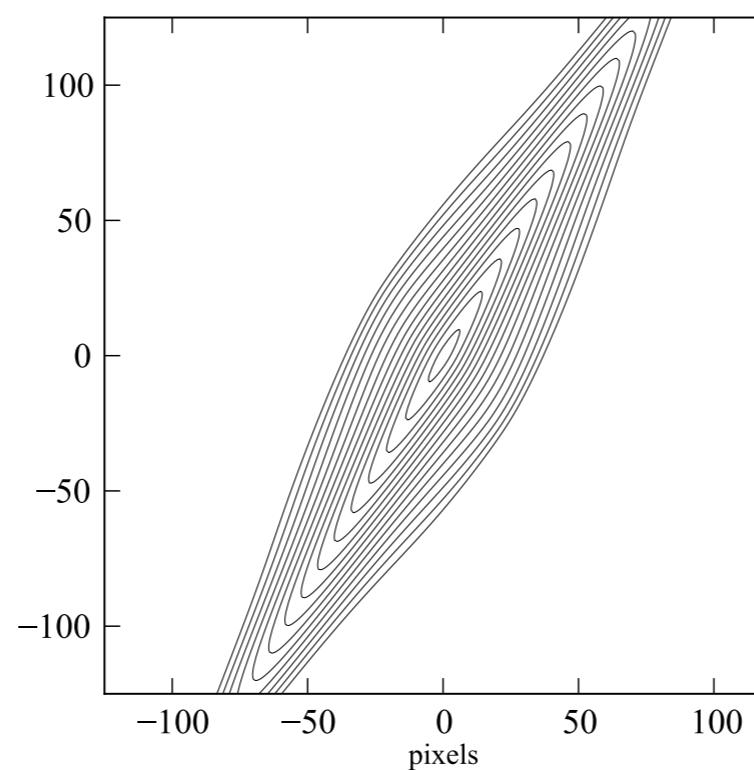


# IC 5176: Edge-on Thin + Thick Disk

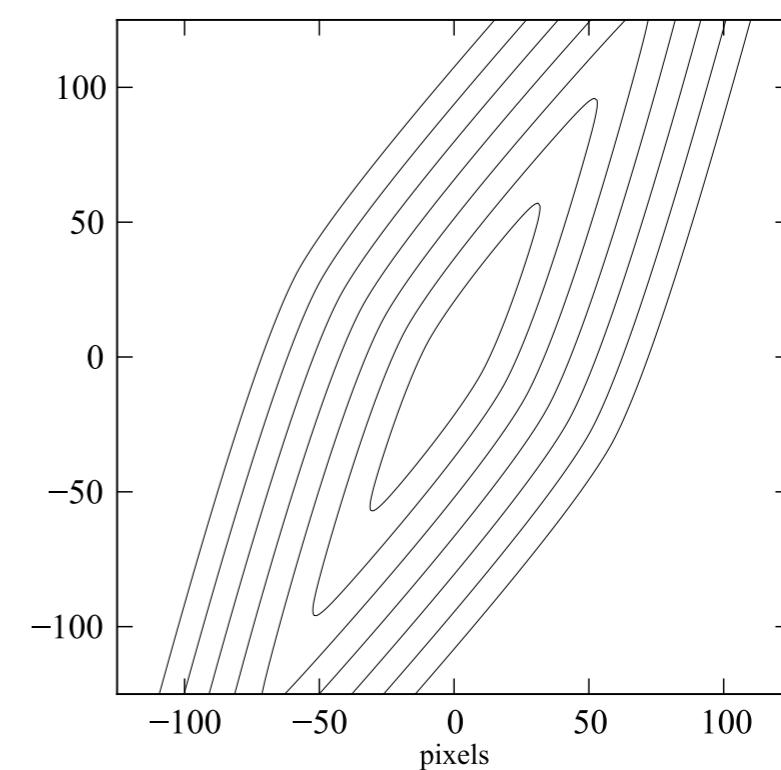
Spitzer IRAC1 (3.6 $\mu$ m)



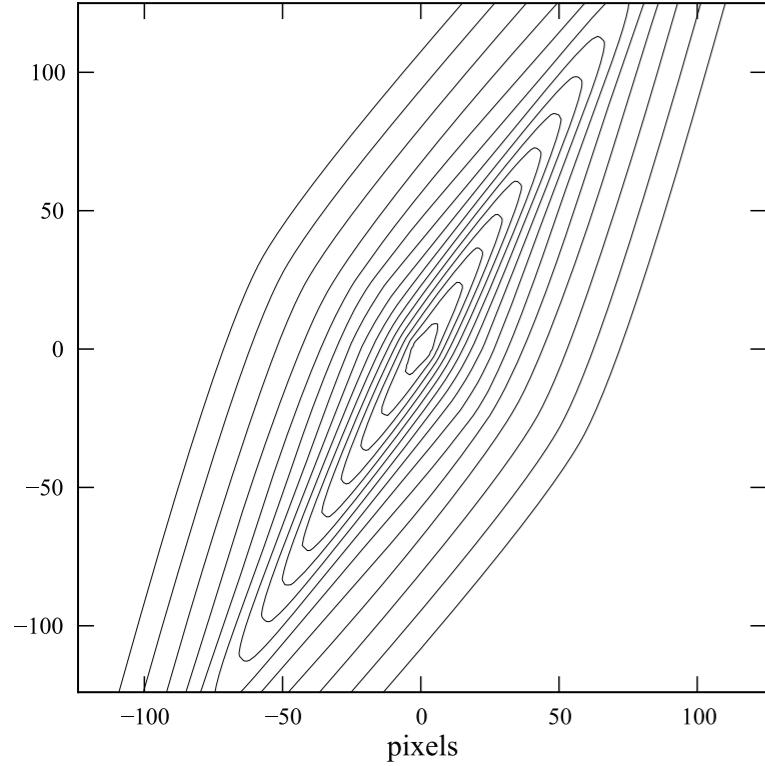
3D Thin disk



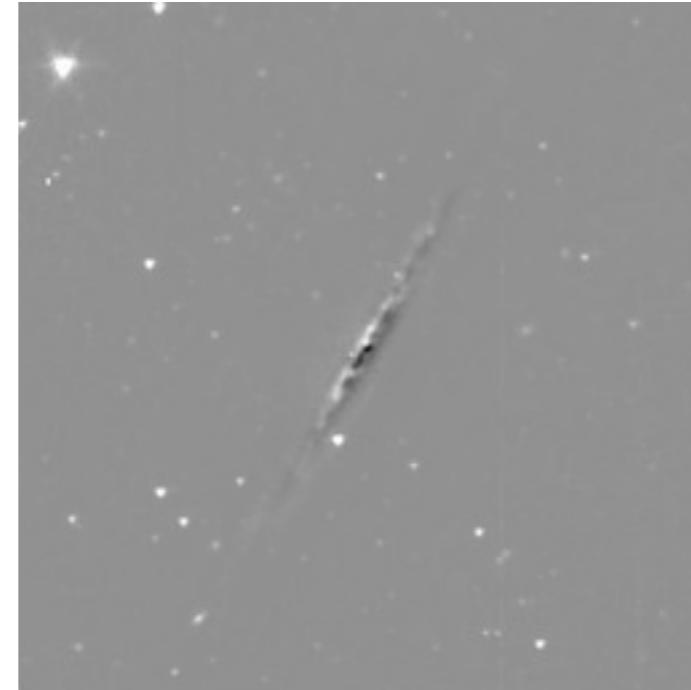
3D Thick disk



Combined model (w/ Sérsic)



Residual



1. Sérsic = 0.018
2. Thin disk = 0.72, exponential scale height = 260 pc,  $i = 87^\circ$
3. Thick disk = 0.27, exponential scale height = 1510 pc,  $i = 90^\circ$

Thick/thin height = 5.8

Thick/thin luminosity = 0.37

# Minimization Algorithms

## 1. Levenberg–Marquardt least-squares minimization

C++ version of “MPFIT” C module of Craig Markwardt  
(ultimately from Fortran MINPACK-1 code; Garbow+1980)

- very fast
- numerical differentiation
- can be trapped in local minima in fit landscape

## 2. Nelder–Mead Simplex (NLOpt library)

- less sensitive to local minima in fit landscape
- slower (~5–10 times)

## 3. Differential Evolution (Storn & Price 1997) — genetic-algorithms approach

- even less sensitive to local minima in fit landscape
- even slower (~50–100 times slower than L-M!)

# Applications

- S0/spiral decompositions for SMBH modeling (Rusli et al. 2013; Erwin et al., in prep; Saglia et al., in prep)
- Fitting of *kinematically decomposed* bulge, disk+ring components from IFU data of NGC 7217 (Fabricius et al., in prep)
- Preliminary EUCLID photometric pipeline simulations (Kümmel et al. 2013)
- Python bindings by André Luiz de Amorim (to be contributed to AstroPy project as affiliated package):

<https://github.com/streeto/python-imfit>

# What Should You Minimize When Fitting Images?

- What statistical model should you use for comparing data values with the model?
- Astronomical images are usually a combination of:
  - Poisson statistics (e.g., detected photoelectrons)
  - Gaussian noise contributions (e.g., read noise)

# What Should You Minimize When Fitting Images?

- What statistical model should you use for comparing data values with the model?
- Astronomical images are usually a combination of:
  - Poisson statistics (e.g., detected photoelectrons)
  - Gaussian noise contributions (e.g., read noise)

**Maximum likelihood approach:** maximize the product of per-pixel probabilities  $p_i$  of the data value  $d_i$  given the model value  $m_i$

$\Rightarrow$  Usually simpler to *minimize the log-likelihood*

$$\mathcal{L} = \prod_{i=1}^N p_i \quad \longrightarrow \quad -\ln \mathcal{L} = -\sum_{i=1}^N \ln p_i$$

# What Should You Minimize When Fitting Images?

- What statistical model should you use for comparing data values with the model?
- Astronomical images are usually a combination of:
  - Poisson statistics (e.g., detected photoelectrons)
  - Gaussian noise contributions (e.g., read noise)

**Maximum likelihood approach:** maximize the product of per-pixel probabilities  $p_i$  of the data value  $d_i$  given the model value  $m_i$

$\Rightarrow$  Usually simpler to *minimize the log-likelihood*

$$\mathcal{L} = \prod_{i=1}^N p_i \quad \longrightarrow \quad -\ln \mathcal{L} = -\sum_{i=1}^N \ln p_i$$

So... minimize log-likelihood of combined Gaussian & Poisson contributions  
Sounds pretty simple, right?

Actually, Poisson + Gaussian log-likelihood is  
pretty scary ...

$$-\ln \mathcal{L} = \sum_{i=1}^N \left( m_i - \ln \left[ \sum_{x_i=0}^{\infty} \frac{m_i^{x_i}}{x_i!} \exp \left( \frac{-(d_i - x_i)^2}{2\sigma^2} \right) \right] \right)$$

[e.g., Llacer & Nuñez 1992]

Actually, Poisson + Gaussian log-likelihood is  
pretty scary ...

$$-\ln \mathcal{L} = \sum_{i=1}^N \left( m_i - \ln \left[ \sum_{x_i=0}^{\infty} \frac{m_i^{x_i}}{x_i!} \exp \left( \frac{-(d_i - x_i)^2}{2\sigma^2} \right) \right] \right)$$

[e.g., Llacer & Nuñez 1992]

Actually, Poisson + Gaussian log-likelihood is  
pretty scary ...

$$-\ln \mathcal{L} = \sum_{i=1}^N \left( m_i - \ln \left[ \sum_{x_i=0}^{\infty} \frac{m_i^{x_i}}{x_i!} \exp \left( \frac{-(d_i - x_i)^2}{2\sigma^2} \right) \right] \right)$$

[e.g., Llacer & Nuñez 1992]

Actually, Poisson + Gaussian log-likelihood is  
pretty scary ...

$$-\ln \mathcal{L} = \sum_{i=1}^N \left( m_i - \ln \left[ \sum_{x_i=0}^{\infty} \frac{m_i^{x_i}}{x_i!} \exp \left( \frac{-(d_i - x_i)^2}{2\sigma^2} \right) \right] \right)$$

[e.g., Llacer & Nuñez 1992]

“Run away! Run away!”



# Simple Solution I

Use the Gaussian approximation to the Poisson distribution:

$$\sigma_s = \sqrt{s}$$

Reduces to familiar  $\chi^2$ :

$$-2 \ln \mathcal{L} = \chi^2 = \sum_{i=1}^N \frac{(d_i - m_i)^2}{\sigma_i^2}$$

Can estimate sigma from:

- data values (+ Gaussian read noise)
- model values (+ Gaussian read noise)
- external error/variance map (e.g., from a reduction pipeline)

# Simple Solution II

Ignore Gaussian contributions and use Poisson distribution

$$p_i(d_i|m_i) = \frac{m_i^{d_i} e^{-m_i}}{d_i!}$$

Reduces to “Cash statistic”  $C$  (Cash 1979):

$$-2 \ln \mathcal{L} = C = 2 \sum_{i=1}^N (m_i - d_i \ln m_i)$$

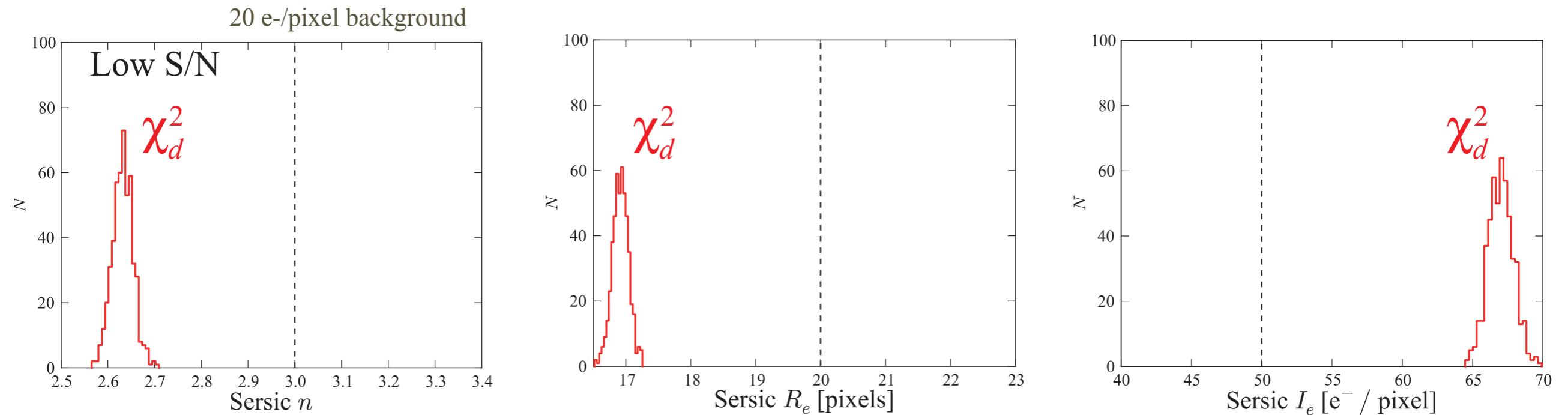
About as easy to calculate as  $\chi^2$

Especially apt for low-count regimes (well-known in X-ray fitting)

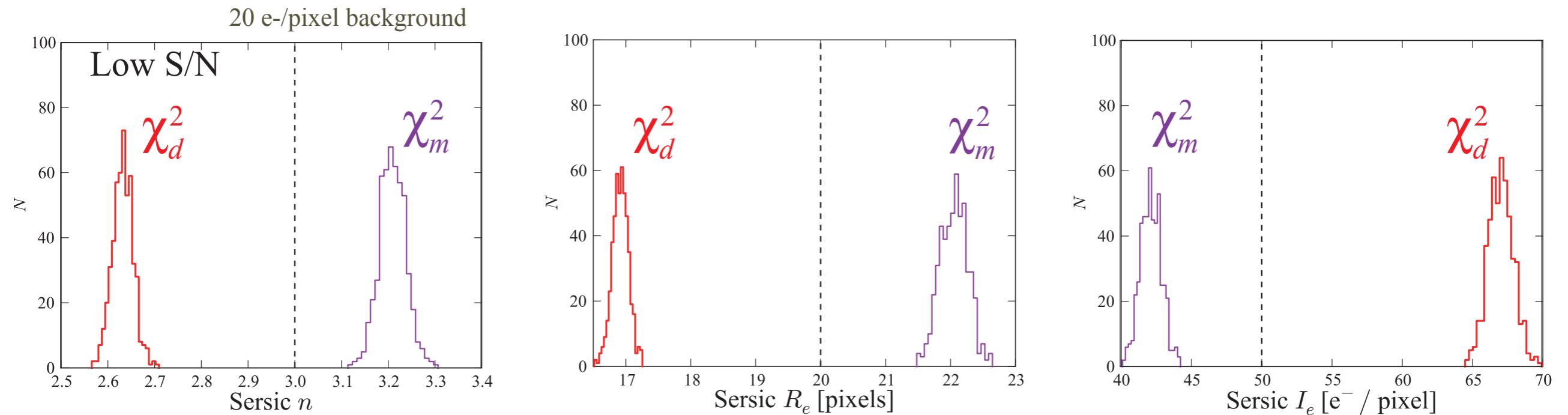
# Model Images

- 500 realizations of simple elliptical  $n = 3$  Sérsic model
- Three S/N regimes:
  - low = 20 electrons/pixel background
  - medium & high = 5 & 25 times
- True Poisson statistics (+ optional Gaussian read noise)
- Fit with Imfit using data-based  $\chi^2$ , model-based  $\chi^2$ , and Cash statistic (simplification: assume we know sky exactly)

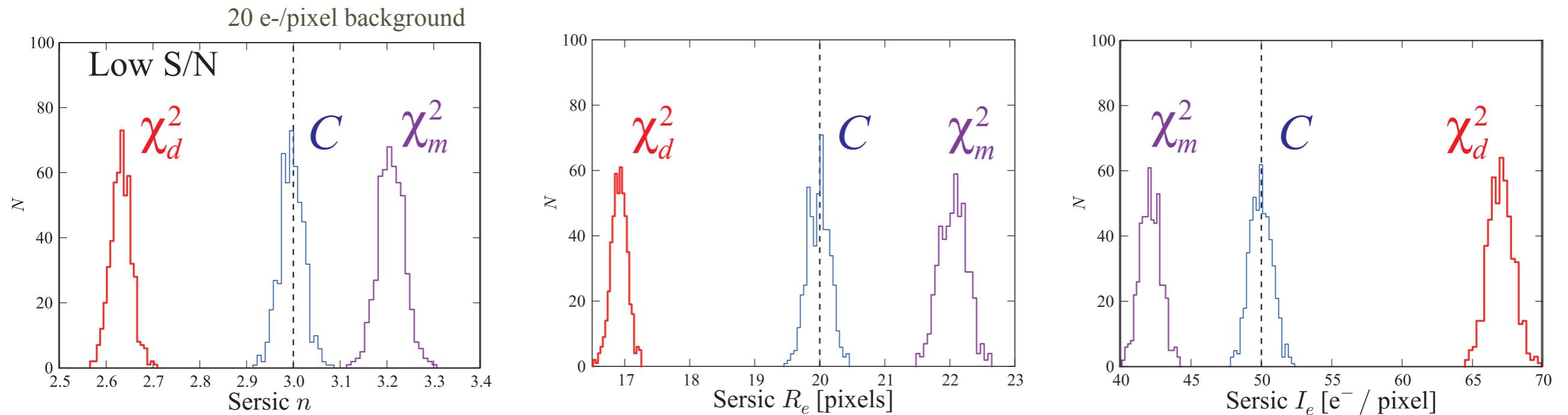
# Chi-Squared Biases



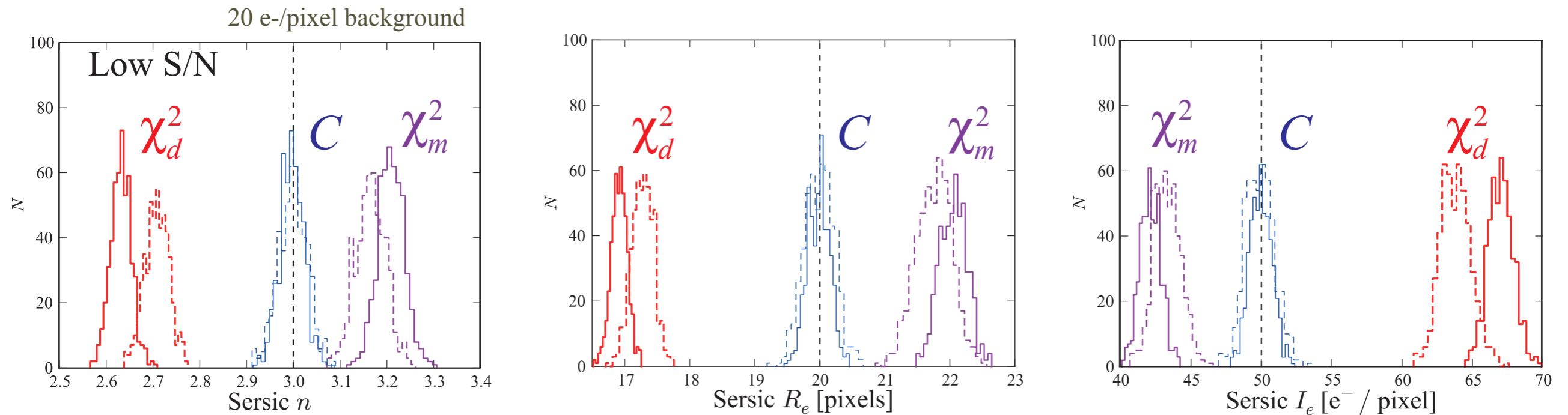
# Chi-Squared Biases



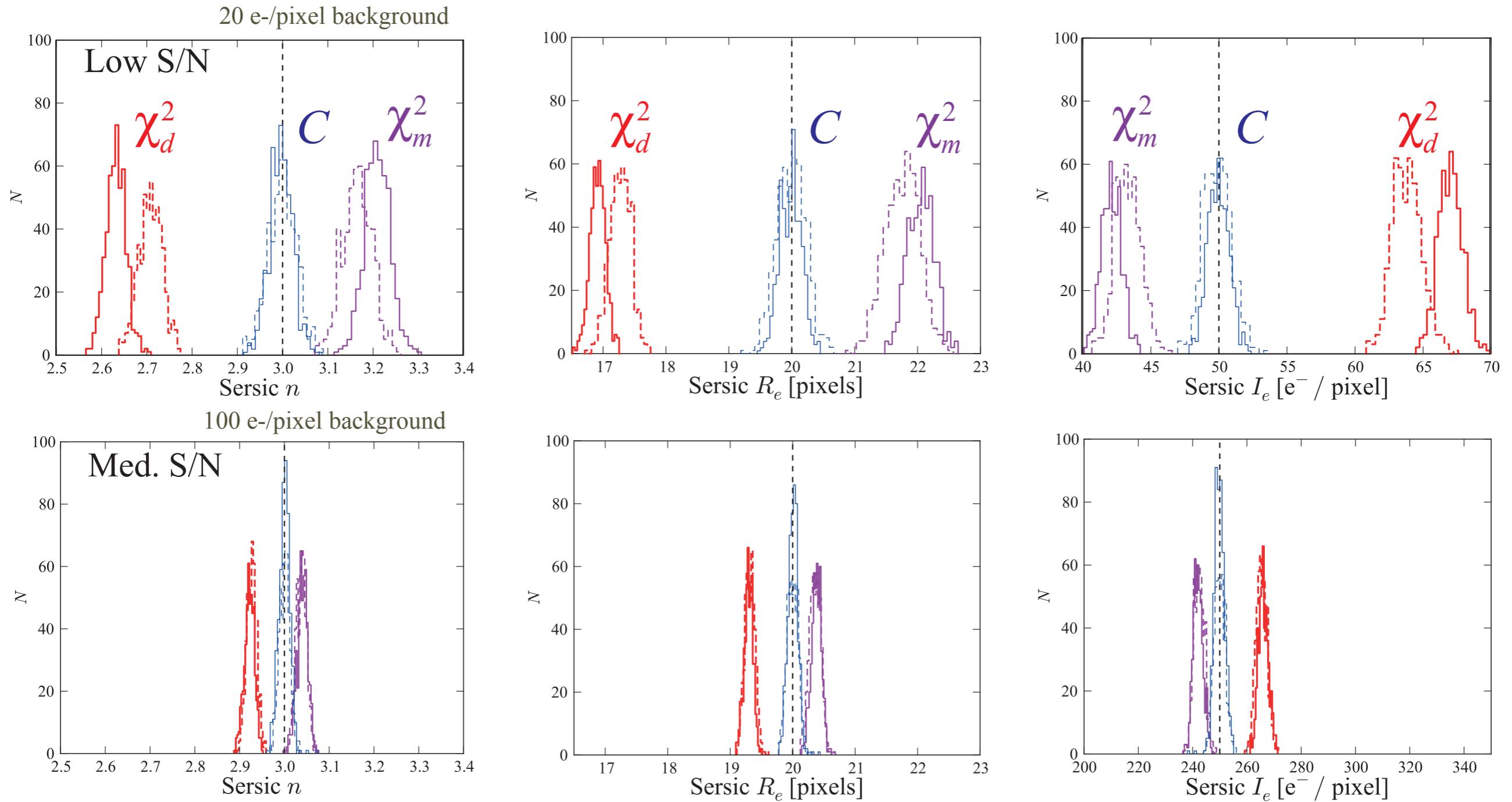
# Chi-Squared Biases



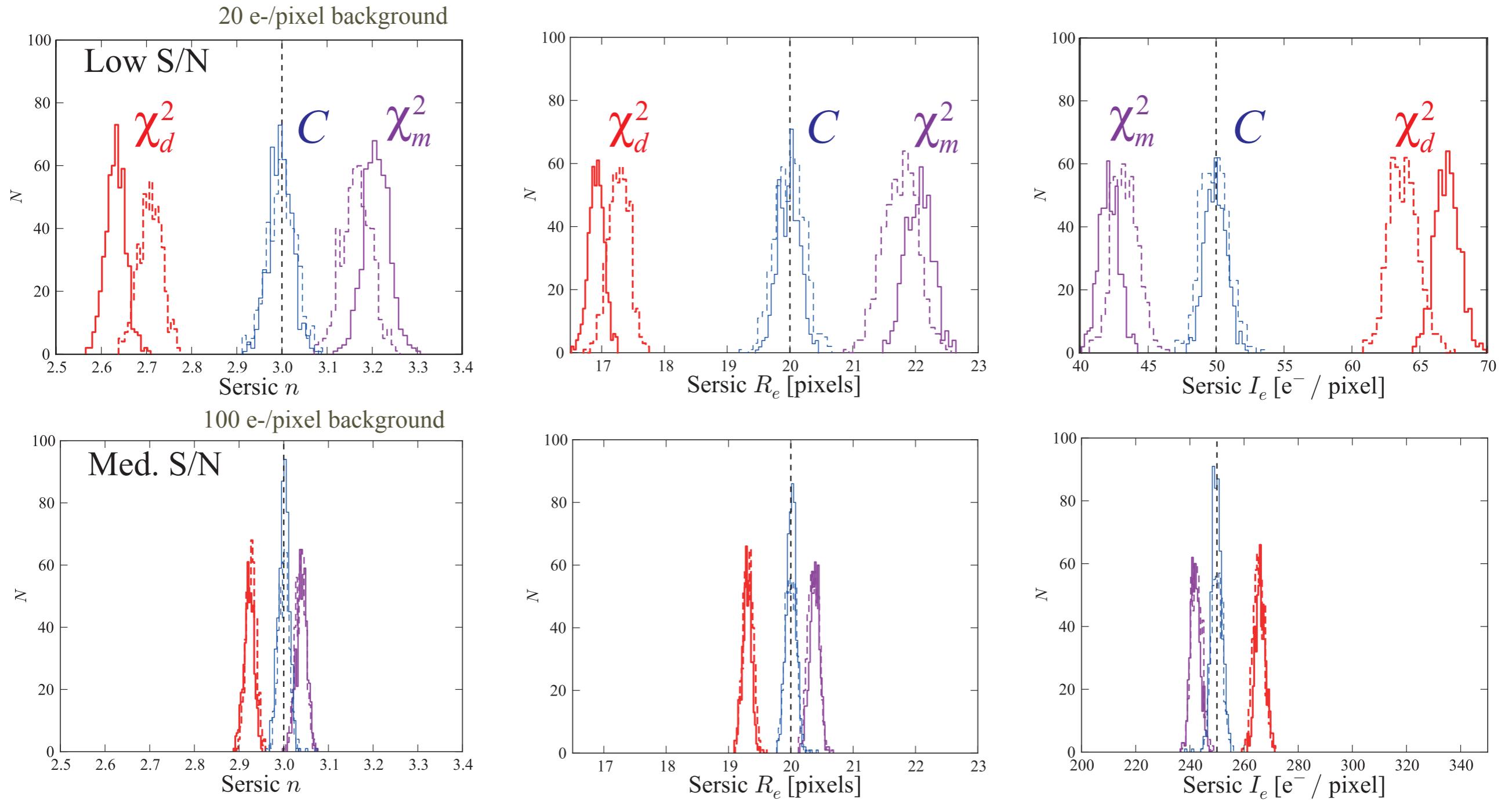
# Chi-Squared Biases



# Chi-Squared Biases



# Chi-Squared Biases



$\chi^2$  fits yield *biased* model parameters; model-based bias is smaller  
 Bias shrinks as S/N increases

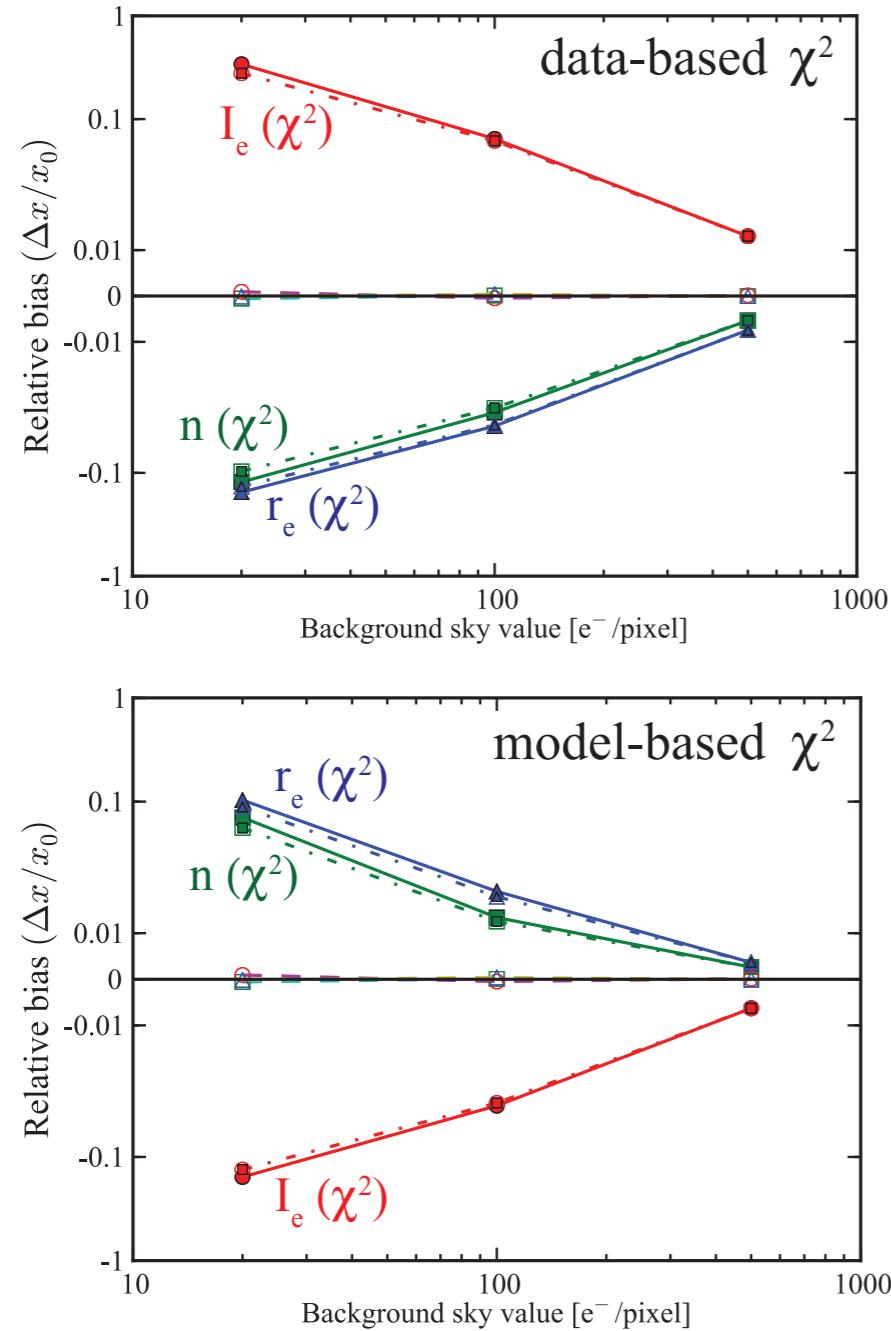
Size & direction of bias as in [Humphrey+2009](#)

Cash-statistic fits are effectively *unbiased!*

# Does This Apply to Real Galaxy Images?

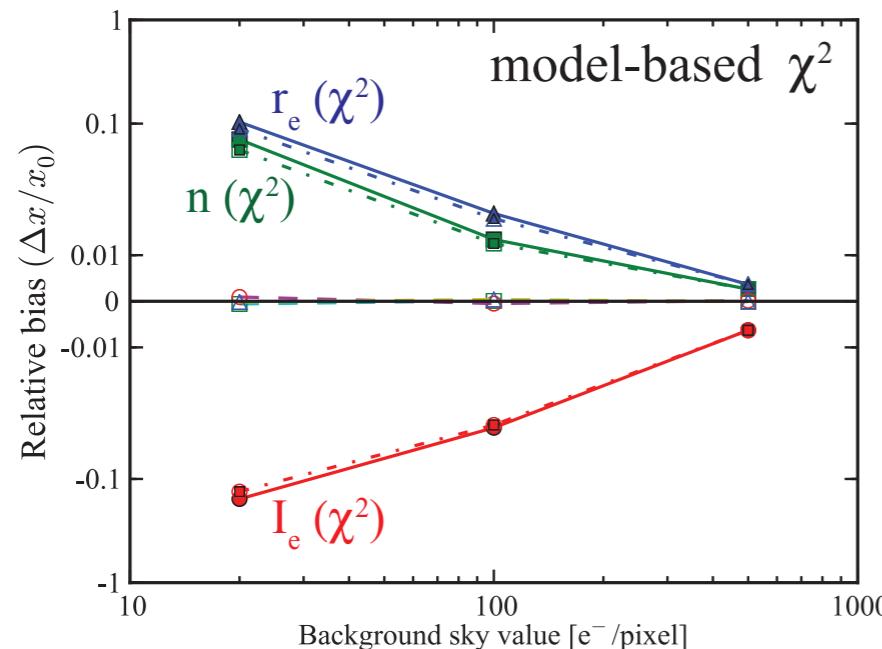
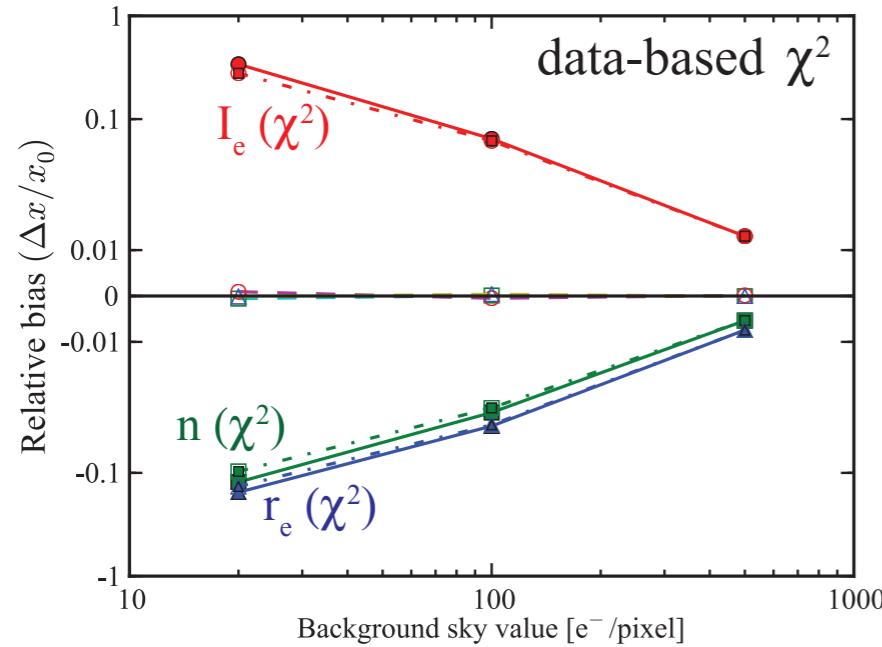
# Does This Apply to Real Galaxy Images?

## Model-Galaxy Images

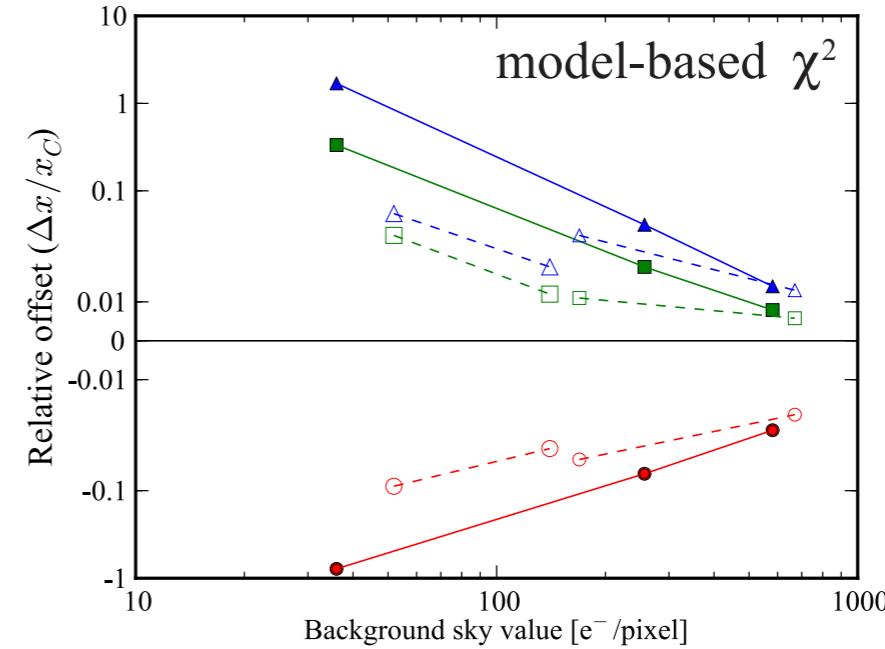
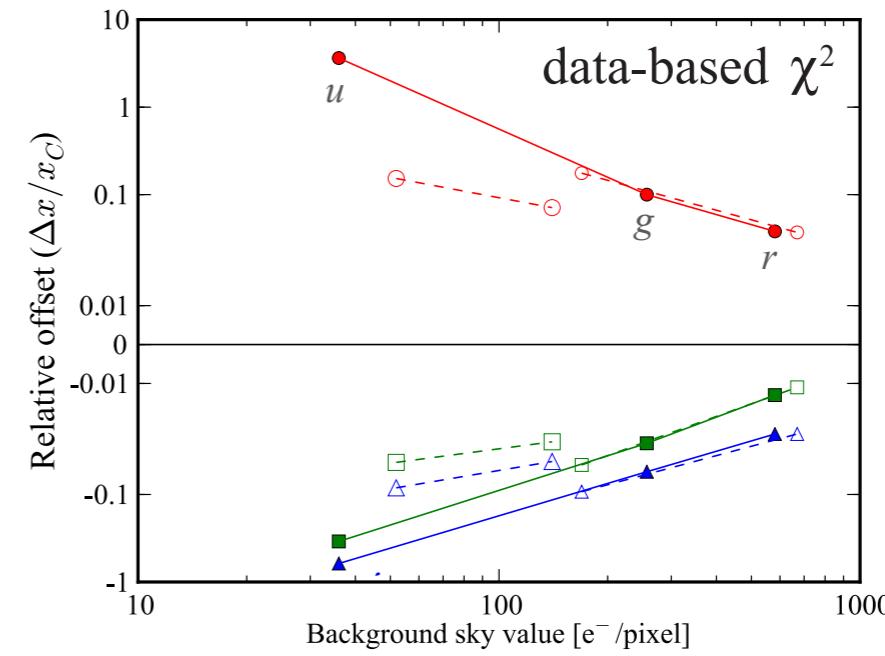


# Does This Apply to Real Galaxy Images?

Model-Galaxy Images



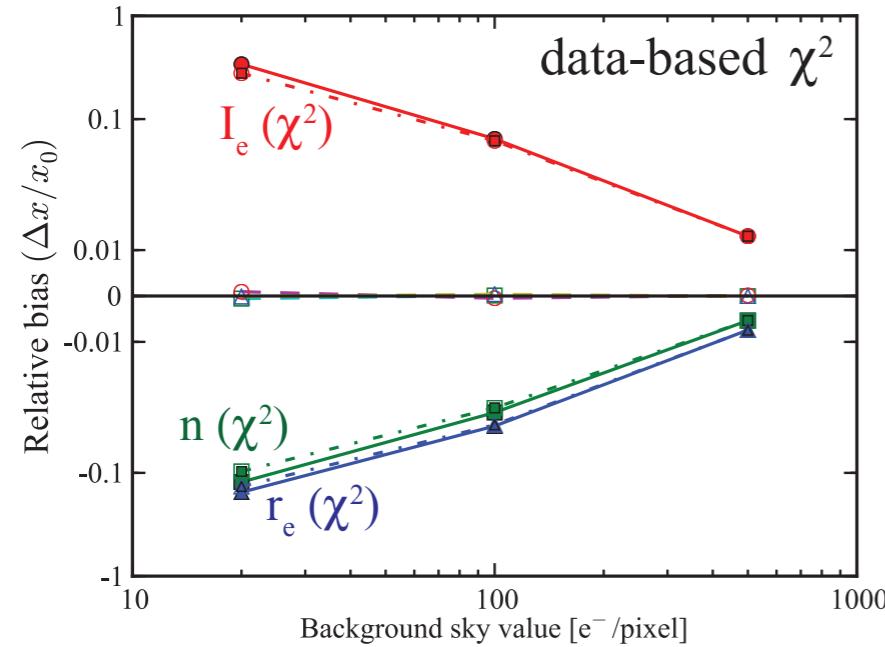
Real-Galaxy Images



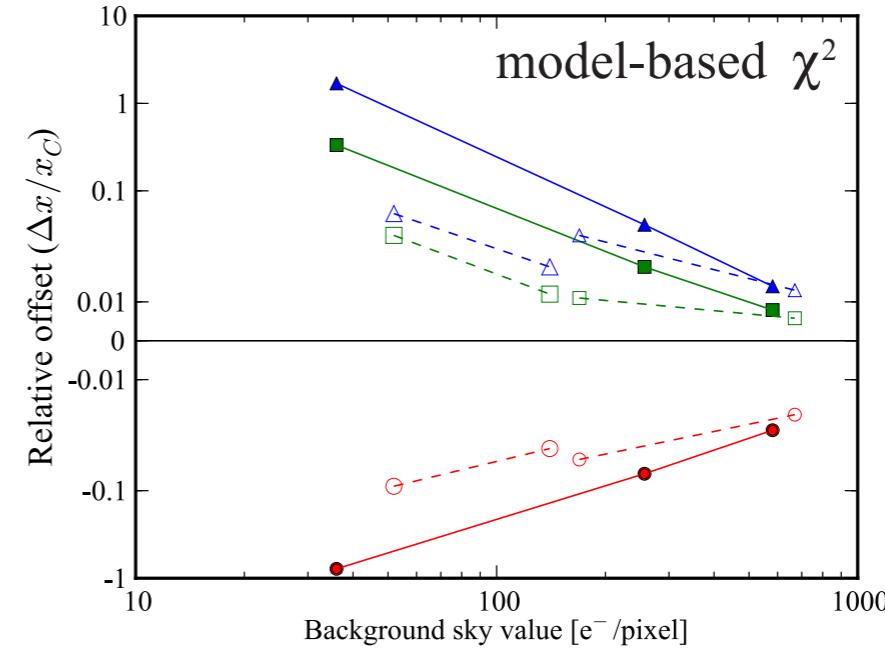
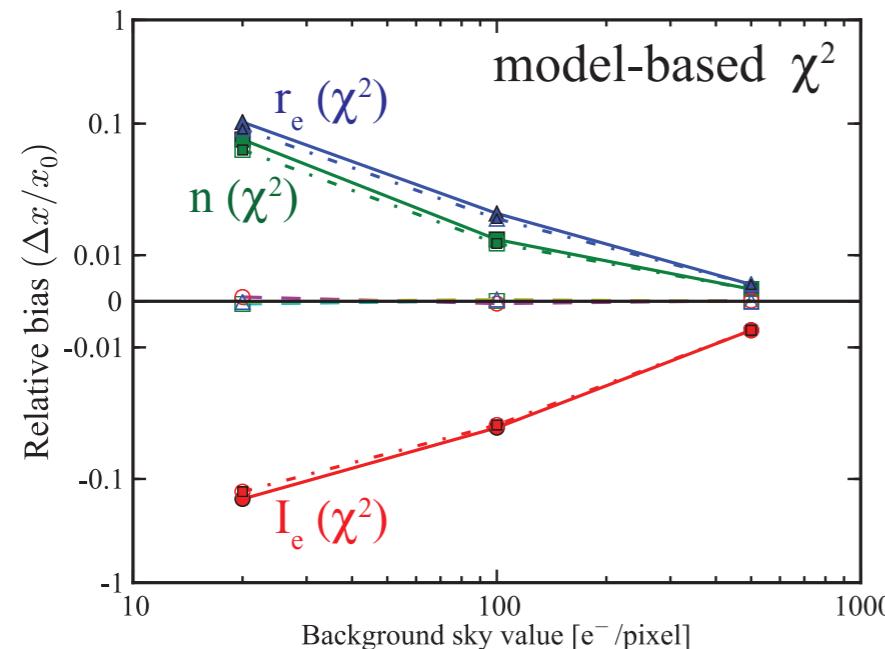
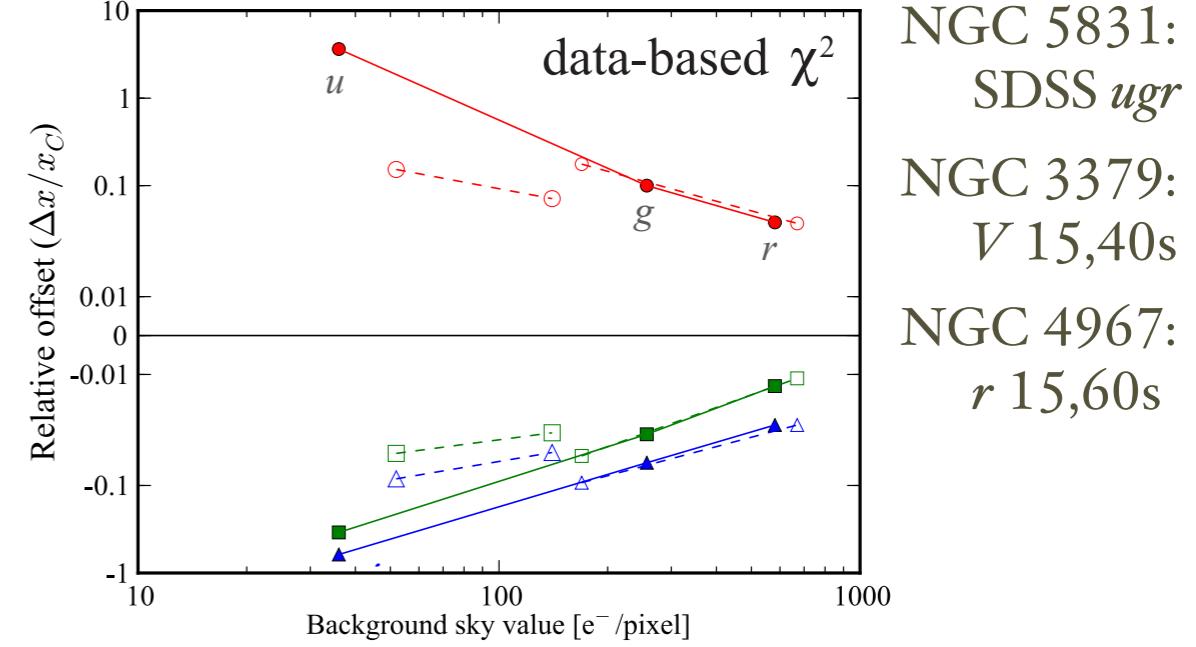
NGC 5831:  
SDSS  $ugr$   
NGC 3379:  
 $V 15,40s$   
NGC 4967:  
 $r 15,60s$

# Does This Apply to Real Galaxy Images?

Model-Galaxy Images



Real-Galaxy Images



YES:  $\chi^2$  Sérsic fits to real elliptical-galaxy images show same pattern of deviations relative to Cash-statistic fits as in model-galaxy images.

# So, should we always use Cash Statistic?

- Cash statistic means lower bias, even when read noise is present
- Probably important whenever background  $< 100$  e-/pixel
- **Drawback:**
  - $C$  is usually  $< 0$ , so can't use least-squares minimization algorithms (like L-M)
  - Can use N-M simplex – but that's **about 5–10 times slower**
  - **Compromise solution when speed is critical: use *model-based*  $\chi^2$  instead of data-based  $\chi^2$**

# Summary

## I. Imfit

- Fast, flexible galaxy image-fitting code
- Easy to add new components
- Multiple minimization options & algorithms

## II. Biases in fitting galaxies:

- Fits using  $\chi^2$  lead to *biased parameters* (as large as 10%)
- Cash-statistic fits are unbiased (but slower)
- When background counts  $< 100 \text{ e}^-/\text{pix}$ , should consider using Cash statistic, or at least model-based  $\chi^2$

Source code, compiled programs (MacOS X,  
Ubuntu Linux), documentation, & sample files  
available here:

[www.mpe.mpg.de/~erwin/code/imfit/](http://www.mpe.mpg.de/~erwin/code/imfit/)

(Or just Google for “Peter Erwin” and “imfit”)