



Reducing the Fractal Iterative Method (FRiM)

to the cost of half an iteration

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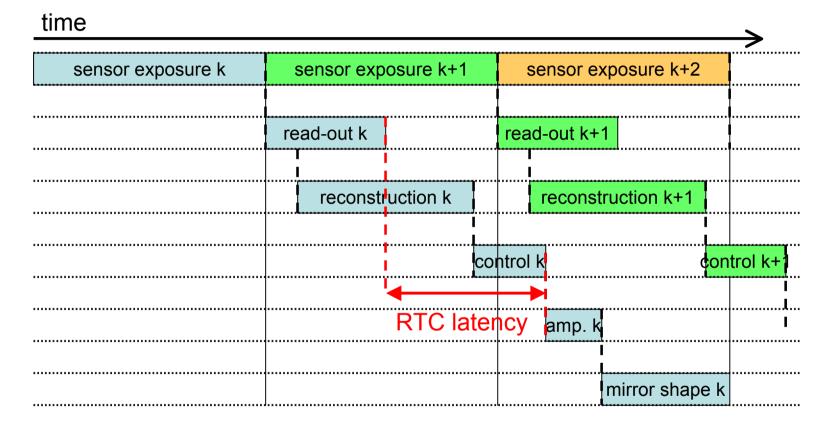




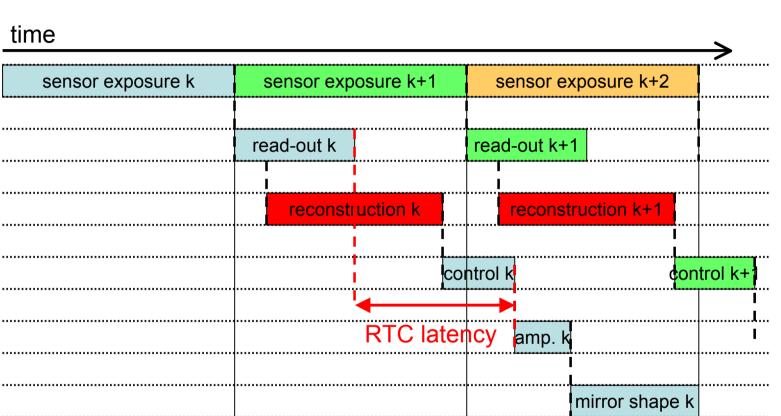
Reminder on the Fractal Iterative Method (FRiM)

- minimum-variance reconstruction algorithm for large Adaptive Optics systems
 Thiébaut & Tallon JOSA A, 2010
- performance assessed on Octopus, ESO end-to-end AO simulator, since 2008
- preconditioned conjugate gradients (PCG), as most of the iterative AO reconstructors
- iterative method PROS
 - no full matrix multiplication
 - neither matrix inversion, nor matrix storage in FRiM
 - sparse/fast operators in FRiM
 - easier to update the model
- iterative method CONS?
 - latency increases with the number of PCG iterations

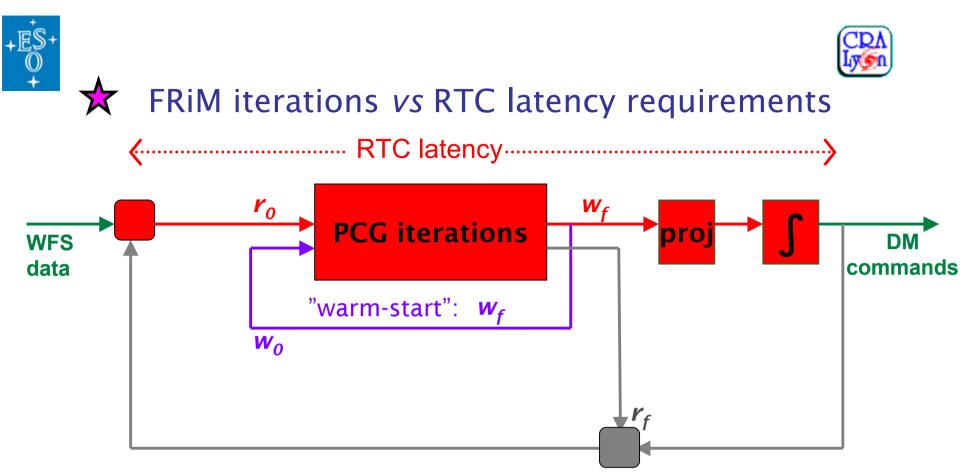




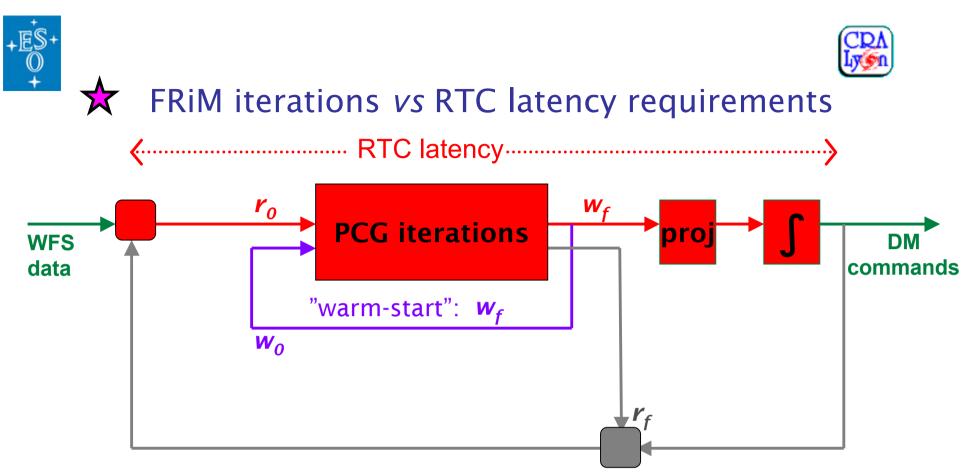




most time spent in the reconstruction, and particularly in the PCG



- projection on DM (proj) and pseudo open-loop control with integrator (\int) (Gilles, 2003)
- r_0 and r_f , PCG residuals (initial and final) for iterations
- *w*₀ and *w*_f, starting guess and final estimate
- "warm-start": w₀ <- w_f (because slow evolution of the turbulent wavefront)



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- "warm-start": W₀ <- W_f (because slow evolution of the turbulent wavefront
- iterations need to be done sequentially
- more iterations means more latency until commands are applicable
- several iterations required to obtain best performance in this classical scheme





Examples of FRiM performance vs #iterations

- E-ELT
 - 42-m telescope (central obs.:0.28)
 - 500 Hz loop frequency
 - Cn2 profile : 9 layers, r_0 = 12.9 cm

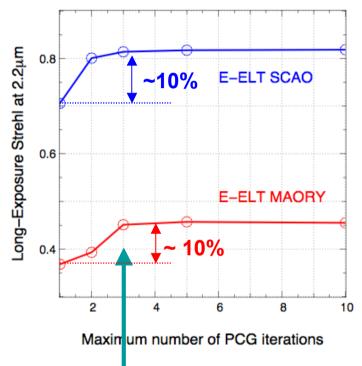
single-conjugate AO:

- DMs: 0 km (85 x 85)
- 1 NGS, 84x84 subap.
- 10⁵ photons/frame/subap.
- $\tau_0 = 2.8 \text{ms}$

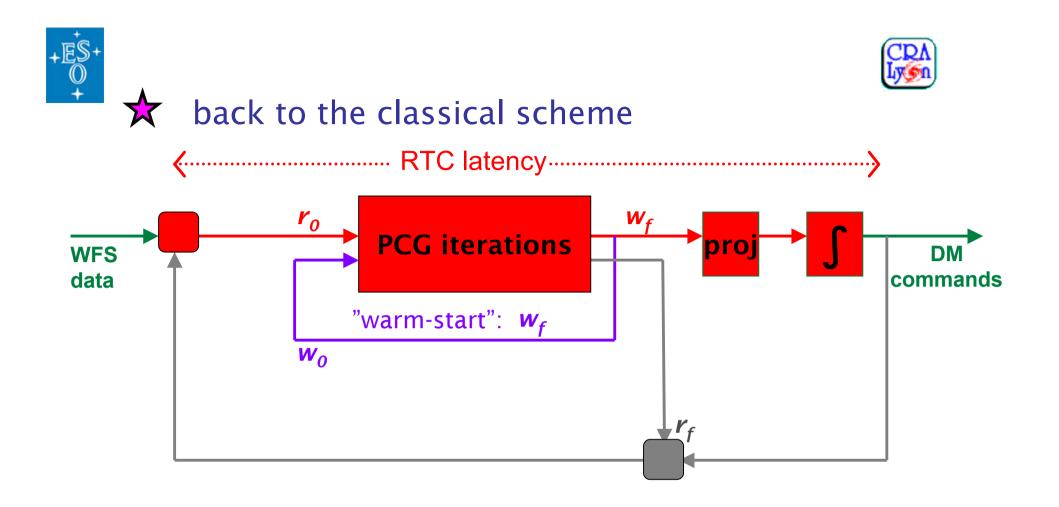
multi-conjugate AO (MAORY):

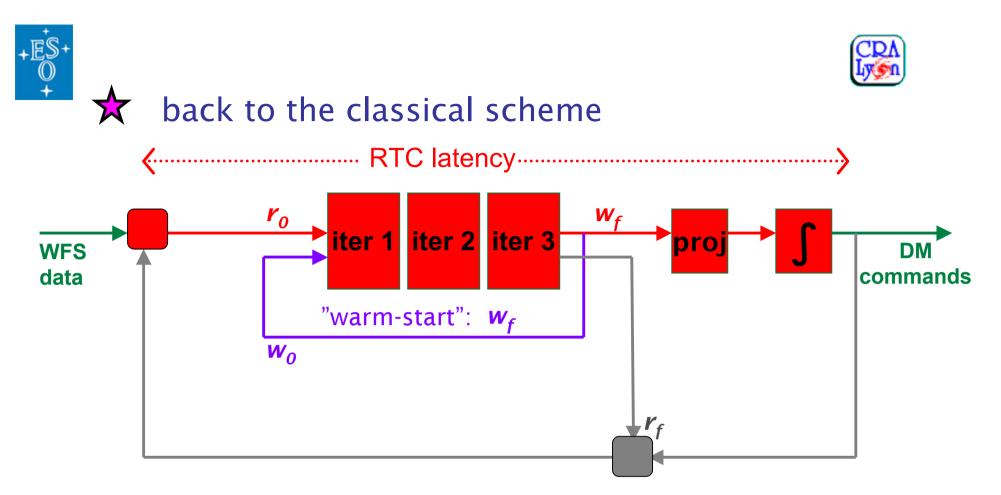
- DMs: 0 km (85 x 85), 4 km (47 x 47), 12.7 km (53 x 53)
- 6 LGS, 84 x 84 subap.
 - > on a Ø 2 arcmin circle
 - > 500 ph/subap.
 - > RON 3e-
- 2 NGS for tip/tilt, 1 NGS for 2 x 2 subap.
 - > on a Ø 2.7 arcmin circle
 - > 500 ph/subap., H band
 - ➢ RON 5e-

Closed–loop simulations FRiM on Octopus

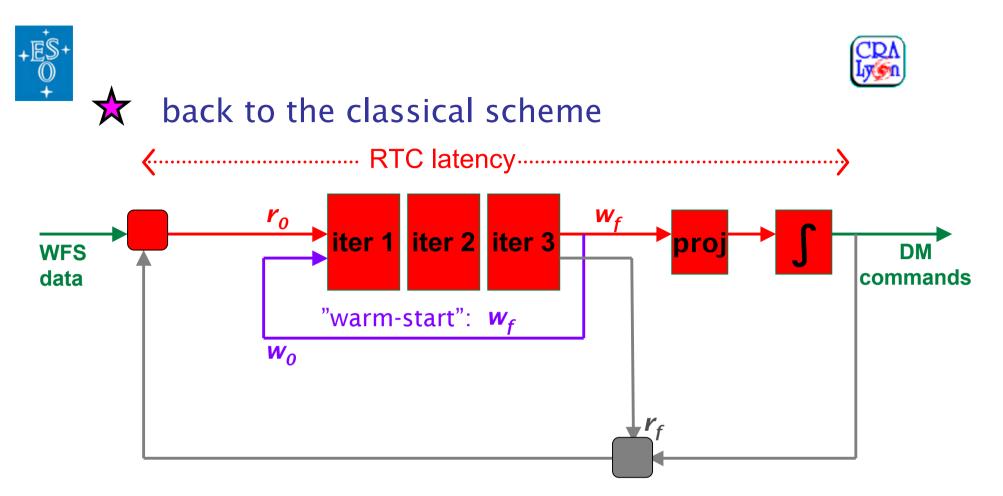


3 PCG iterations required for the best performance

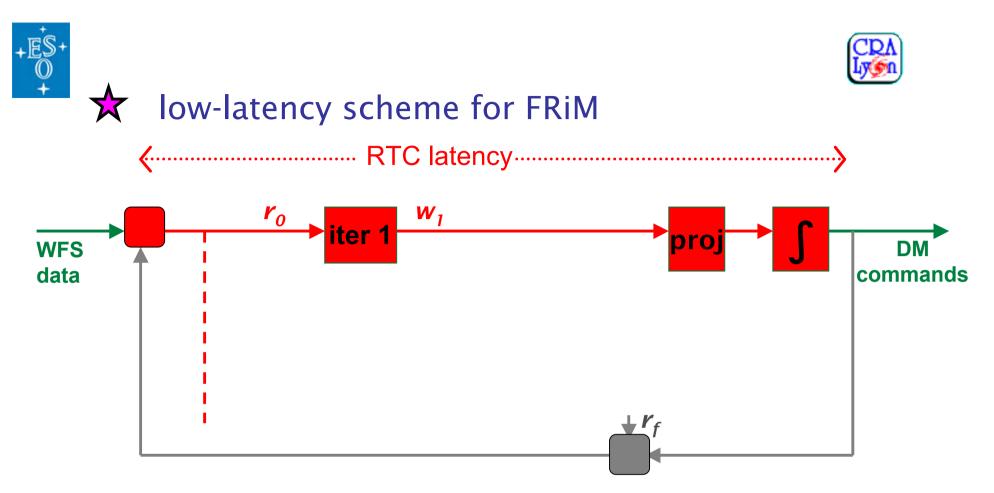




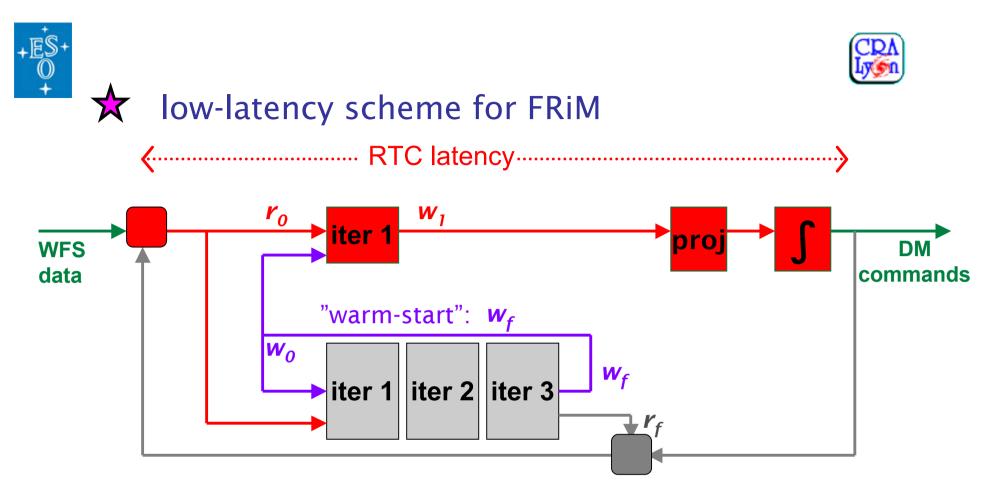
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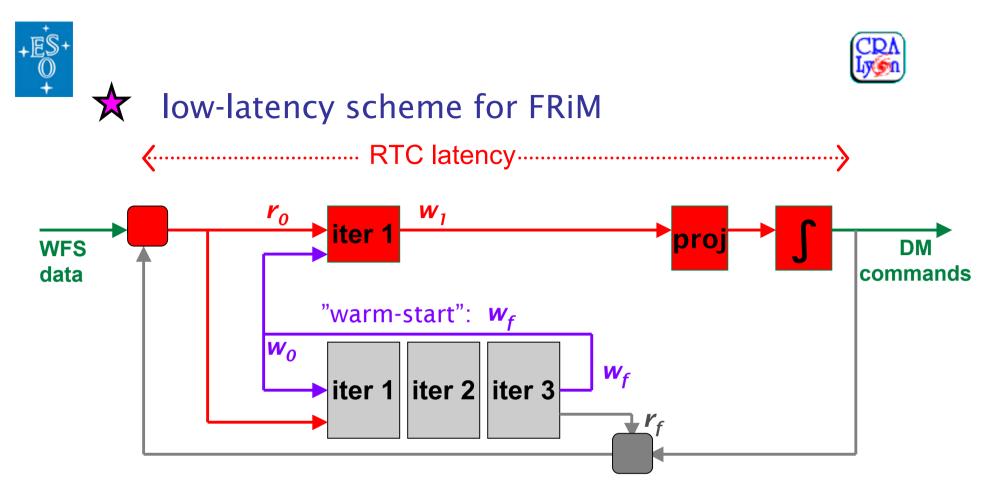
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 - restrict to 1 iteration of FRiM to meet latency requirement and ...

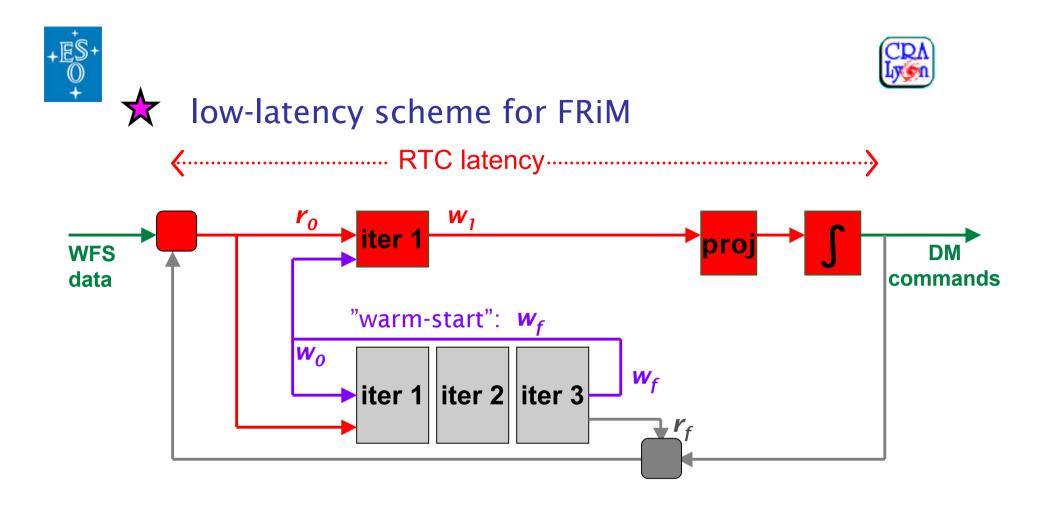


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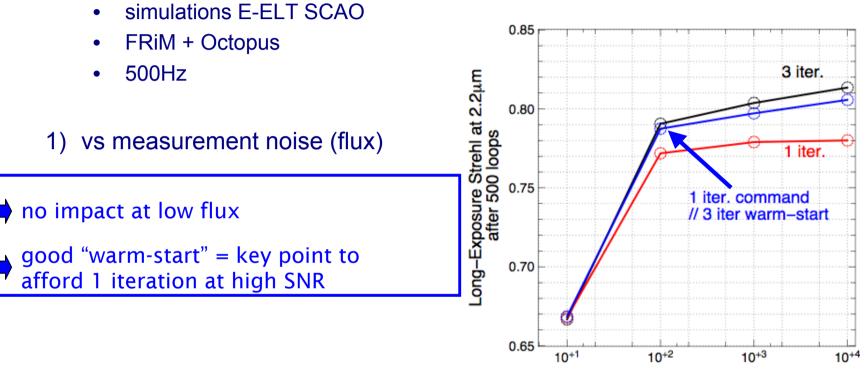


- consequences:
 - ✓ low-latency path is reduced to the cost of 1 iteration
 - ✓ 3 iterations in SCAO < 1 WFS exposure time
 - best performance is maintained thanks to an optimal "warm-start" (preliminary results by simulations)





Results with low-latency scheme



GS flux (photons / frame / subap.)





Results with low-latency scheme

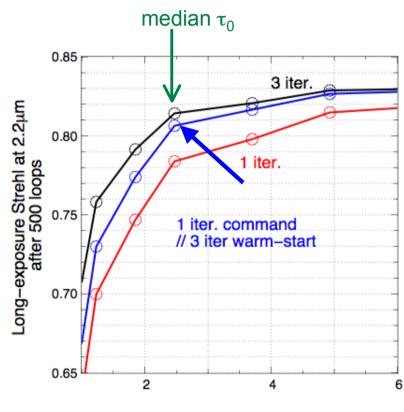
- simulations E-ELT SCAO
- FRiM + Octopus
- 500Hz
- 1) vs measurement noise (flux)

no impact at low flux

good "warm-start" = key point to afford 1 iteration at high SNR

2) vs wind speed (atmosphere coherence time τ_0) high flux conditions

again good "warm-start"= key point
 also helps for high wind speeds



τ₀ (ms)





\bigstar reducing to the cost of half an iteration

- computations for the low-latency branch (only 1 iter.) can be revisited
- only the first iteration to be applied
 - PCG 1rst iteration = steepest descent
 - simplified computations (no need to update the residuals)

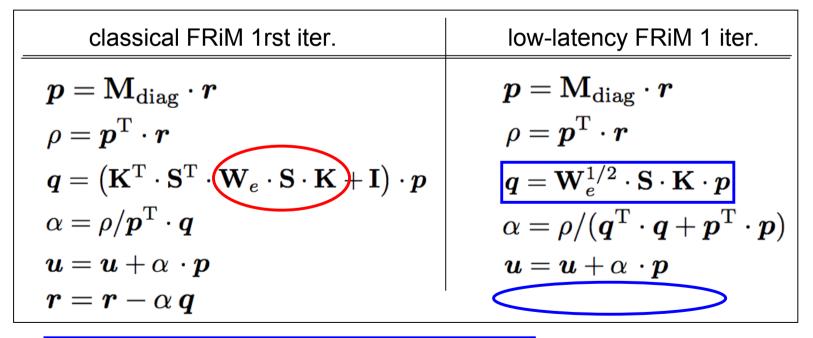
classical FRiM 1rst iter.	low-latency FRiM 1 iter.
$oldsymbol{p} = \mathbf{M}_{ ext{diag}} \cdot oldsymbol{r}$	$oldsymbol{p} = \mathbf{M}_{ ext{diag}} \cdot oldsymbol{r}$
$ ho = oldsymbol{p}^{\mathrm{T}} \cdot oldsymbol{r}$	$ ho = oldsymbol{p}^{\mathrm{T}} \cdot oldsymbol{r}$
$oldsymbol{q} = ig(\mathbf{K}^{ ext{T}} \cdot \mathbf{S}^{ ext{T}} \cdot \mathbf{W}_e \cdot \mathbf{S} \cdot \mathbf{K} + \mathbf{I} ig) \cdot oldsymbol{p}$	$oldsymbol{q} = \mathbf{W}_e^{1/2} \cdot \mathbf{S} \cdot \mathbf{K} \cdot oldsymbol{p}$
$lpha= ho/oldsymbol{p}^{\mathrm{T}}\cdotoldsymbol{q}$	$lpha = ho / (oldsymbol{q}^{\mathrm{T}} \cdot oldsymbol{q} + oldsymbol{p}^{\mathrm{T}} \cdot oldsymbol{p})$
$oldsymbol{u} = oldsymbol{u} + lpha \cdot oldsymbol{p}$	$oldsymbol{u} = oldsymbol{u} + lpha \cdot oldsymbol{p}$
$oldsymbol{r} = oldsymbol{r} - lpha oldsymbol{q}$	





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half of the heavy computations of 1 iteration
 no longer an iterative reconstructor





Conclusions

- For iterative methods, RTC latency is constrained by the # of iterations
 - sequential iterations
 - although only 3 are required for best performance of FRiM
- We developed a new low-latency application of FRiM, based on:
 - 1 iteration for the commands computation
 - 3 iterations to improve the warm-start of the next reconstruction
- First results from simulations demonstrate the efficiency of the improved "warm-start"
- The computational cost of 1 iteration only is half the cost of a classical iteration
- With only 1 iteration, the reconstruction is no longer iterative.
 This may be applied to any iterative method...