

### **DDS on SPARTA**

Stefano Zampieri szampier@eso.org







#### DDS Overview

#### DDS on SPARTA

Network considerations

Conclusions







## **DDS in a nutshell**

DDS is a Real-Time Data-Centric Networking Middleware

#### DDS focuses on

- Performance
  - High-performance data-access APIs (zero copy access)
- Configurability
  - Quality of Service
- Scalability
  - UDP, multicast, reliable multicast
- DDS does not require the presence of intermediate brokers
  - Applications can communicate directly peer-to-peer
- DDS supports advanced features
  - E.g. source filtering (via Content-based and Time-based filters)
- Integration
  - E.g. with Database Management Systems





### **DDS Standards**



- Data Distribution Service for Real-Time Systems (DDS)
  - API specification for Data-Centric Publish-Subscribe communication for distributed real-time systems.
  - Current version 1.2
- DDS Interoperability wire Protocol (DDSI/RTPS)
  - Ensure that applications based on different vendors' implementations of DDS can interoperate.
  - Current version 2.1
- Related Standards
  - > UML Profile for DDS adopted June 2008
  - > DDS for light weight CCM adopted 2008
  - Extensible and Dynamic Topic Types for DDS adopted 2010
- Standards under Development
  - Native Language C++ API for DDS
  - DDS-Java





### **DDS Vendors**

- Real-Time innovations, Inc. (Commercial, Open Community Source)
- PrismTech (Commercial & Open Source)
- Object Computing, Inc. (OpenDDS, Open Source)
- Twin Oaks Computing, Inc. (CoreDX, Commercial)
- Etc.





═▐▋◙┕▖╬┽┿▋▋≡▋▌═╶◙ॼ॒╬╏ᡫ▌▓▕▙



### **QoS: Quality of Service**

	QoS Policy	QoS Policy					
Volatility	DURABILITY	USER DATA					
	HISTORY	TOPIC DATA					
	READER DATA LIFECYCLE	GROUP DATA					
	WRITER DATA LIFECYCLE	PARTITION					
Infrastructure	LIFESPAN	PRESENTATION					
	ENTITY FACTORY	DESTINATION ORDER					
	RESOURCE LIMITS	OWNERSHIP					
	RELIABILITY	OWNERSHIP STRENGTH					
Delivery	TIME BASED FILTER	LIVELINESS					
	DEADLINE	LATENCY BUDGET					
	CONTENT FILTERS	TRANSPORT PRIORITY					

═ ▋▋ 図 ┝╸╬╡┿╸▋▌═╡▋▌═╴▓▌⊆ ╬┇ ᡫ▌ ╣ ╘╸



### **Example QoS**

#### <durability>

<kind>DDS\_TRANSIENT\_LOCAL\_DURABILITY\_QOS</kind>

</durability>

#### <time\_based\_filter>

<minimum\_separation> <sec>1</sec> <nanosec>0</nanosec> </minimum\_separation>

</time\_based\_filter>

<history>

<kind>DDS\_KEEP\_ALL\_HISTORY\_QOS</kind>

</history>

<reliability>

<kind>DDS\_RELIABLE\_RELIABILITY\_QOS</kind> <max\_blocking\_time> <sec>0</sec> <nanosec>0</nanosec> </max\_blocking\_time>

</reliability>

Real Time Control Workshop, 4-5 Dec 2012

═╏╏図┝╸╬╪┿╏╏═╏╏╴═┇┛═╬╏╘╝╬╣╘╸





#### DDS Overview

### DDS on SPARTA

Network considerations

Conclusions







### **SPARTA Real Time Data Flows**



Real Time Control Workshop, 4-5 Dec 2012

· \_ | | ⊙ | ... ;: +- | | = | | ... [9] ... ;: 1: 1: ∭ ...



### **Additional Data Flows**

#### DB Events (n:m)

- Database updates sent to DBGateway and to Main
- Including Alarms
- ~300 events/s (measured on SPHERE)

#### CDMS Events (1:n)

- Upon object updates in the SPARTA Cfg. DB
- Trigger chain of events
- Log Events (n:1)
  - Log messages sent to LogGateway



═╏╏थे⊳ःः + ।।= !। = !। = !! = !! \*



### **Throughput requirements**

#### SAXO

VisLoop: 20KB @ 1.2KHz

VisPixel: 112KB @ 10Hz

≻ Tot: ~25MB/s

### AOF

LGSLoop: 67KB @ 1KHz

LGSPixel: 450KB @ 10 Hz

➤ Tot: ~72MB/s

#### Multicast !





## **SPARTA DDS Model**

### SPARTA DDS Wrapper (spadds)

- Simplified API (DDS-like)
- Publisher (*write*)
- Subscriber + DataListener (onDataAvailable)
- **Topic**: template parameter + string
- QoS defined in XML configuration file
- QoS Profiles, referenced by name when creating Publishers and Subscribers
  - *HighThroughputReliableProfile* (reliable, large send queue)
  - LargePacketsReliableProfile (>64KB, asynchronous publisher)
  - *ReliableEventProfile* (durability)
  - *PixelDisplayProfile* (time based filter)



### **SPARTA Data Task**

- Simplifies development of data tasks
- Simple model: receive N samples then process them in a separate thread
- Developer must implement virtual methods received\_, process\_, and deadlineMissed\_
- Examples: Garbage Collector, Loop Optimiser, Atmospheric Monitor, etc







#### DDS Overview

#### DDS on SPARTA

#### Network considerations









### **Multicast & IGMP**



**Multicast vs Broadcast** 



- IP Multicast
  - > Take advantage of multicast efficiency in network
  - > IP address range: 224.0.0.0 to 239.255.255.255.
- IGMP snooping switches
  - No IGMP snooping
    - Multicast traffic broadcasted to each port
  - IGM Snooping
    - Switch forwards multicast packets to correct ports
      - Monitors IGMP join messages
    - Multicast addresses configured by subscriber

═╏╏図┢╸╬╡┿╏║═┇║═╴║╹═╏╬╶╚



### Wireshark & RTPS2

raal_eth1_err [Wireshark 1.8.1 (SVN Rev 43946 from /trunk-1.8)]																			
Eile	<u>E</u> dit	⊻iew	<u>G</u> o	Capture	e <u>A</u> nal	lyze	Statis	tics	Teleph	on <u>y</u>	<u>T</u> ools	Internals	<u>H</u> elp						
	<b>e</b>	24 6	X G	¥   E	3	×	Z	≞	0	\$	\$	🧼 🐨	⊉   [		⊕ ⊙		R 🖂   🌌	¥	•
Filter												•	Expression.	Clear	Apply	Sav	в		
No.	[]	Time		Sourc	е				Destin	ation			Protocol	Length	Info				
	1	0.000	000	192.	168.1	0.10	)		192.	168.	10.30		RTPS2	110	INFO_DS	sΤ,	HEARTBEAT		
	2 1	0.0000	203	192.	168.1	0.10	)		192.	168.	10.30		RTPSZ	110	INFO_DS	ыт, -т	HEARTBEAT		
	5 - 4 -	0.0120	732	192.	168.1	0.10	,		192.	168.	10.30		RTP52	110	INFO_D:	ы, ст	HEAKIBEAT		
	4	0.0120	200	192.	160.1	0.10	1		192.	160.	10.30		RTP52	110	TNEO_D:	ы, ст	HEARIDEAT		_
	5 ' 6 '	0.025:	799 112	192.	169.1	0.10	, )		192.	160.	10.30		RTP52	110	TNEO_D:	ы, ст	HEARIDEAT		
	7	0.024	123	192.	168 1	0.10	, }		192.	168	10.00 10.10		PTPS2	114	TNEO DS	эт, ат	NACK ERAG		_
	8	0.024	129	192.	168 1	0.30	' 		192.	168	10.10		RTPS2	114	TNEO DS	эт, 5т	NACK_FRAG		_
	9	0.035	956	192.	168.1	0.10	, )		192.	168.	10.30		RTPS2	110	INFO D	ST.	HEARTBEAT		
	10	0.035	968	192.	168.1	0.10	)		192.	168.	10.30		RTPS2	110	INFO DS	5Τ.	HEARTBEAT		
	11	0.047	972	192.	168.1	0.10	)		192.	168.	10.30		RTPS2	110	INFO DS	БΤ.	HEARTBEAT		
	12	0.047	978	192.	168.1	0.10	)		192.	168.	10.30		RTPS2	110	INFO DS	БΤ.	HEARTBEAT		
	13	0.0600	333	192.	168.1	0.10	)		192.	168.	10.30		RTPS2	110	INFO_DS	бΤ,	HEARTBEAT		<b>-</b>
																,			•
	came	1 • 11	n hvi	tes on	wire	1880	) hite	د) .	110 k	vtes	cant	ured (8	80 hits)						
	thern	et TT	s by: Sri	ces on r• Del'	wnc Id3∙e	(000 f•a3	/ Dic. 1 (hc	•30•9	sh•d3	∙ef∙	a3)	Dst• De	00 0709/ 11 d3.92.	f1 (14•	fe•h5•d	3.9	2•f1)		
Thernet Protocol Version 4 Spc: 192 168 10 10 (192 168 10 10) Dst: 192 168 10 30 (192 168 10 30)																			
	ser D	ataor	am Pr	rotoco	l. Src	· Por	·†: 4	6468	(464	68).	Dst	Port: 1	0417 (104	17)		1		.,	
E Re	eal-T	ime P	ubli	sh-Sub	., scribe	Wir	re Pro	otoco	1 2.	× ,									
		<u> </u>	1-			-1	1-							_					
0000	14	te b5	d3 00 -	92 †1 40 00 -	bc 30 40 11	5b 25	d3 e 14 c	n a3 n a8	08 ( 0a (	)0 45 Na c0	00	·a	.0 [ a	.E.					<b></b>
0020	Őa	1e b5	84	28 b1	00 4c	95	d6 5	2 54	50 5	3 0Z	01	(.	LRTPS	5					
0030	01	01 86	ab -	40 65 I 40 67 I	00 00	70	97 0	0 00	00 0	)1 Oe	01	@e	p						
0040	1c	00 80		40 67 1 00 04	80 00	00	03 0	0 00	00 0	)0 51	. 1b	@Q	н. кс						-
0	File:	: "Z:\ora	al eth	1 err" 2	47 KB 0	0:00::	10		P	Profile	: Defau	ılt							
00					-														

Real Time Control Workshop, 4-5 Dec 2012



### Scaling up

### Initial tests on 10 GigE using rtiperftest (no tuning)

	One way Latency (us)	Packets/s	Mb/s	Packet loss
Best effort Small packets	105	130000	104	Very low
Reliable Small packets	510?	35000	28	0
Best effort Large packets	357	11160	5620	About 1%
Reliable Large packets	372	10400	5000	0

### Jumbo frames ?

= || 🖸 🖕 := +- || = || = || = 💷 💷 🖽 🗮 🔛



### Agenda

#### DDS Overview

#### DDS on SPARTA

Network stuff









### Conclusions

DDS works (and saves development)

- > Only 1 serious issue up to now, solved by upgrading
- Reliable (no intermediate brokers), efficient
- Simple programming model, also thank to wrapper API
- > Highly configurable, through external QoS

Future perspectives

DDS/RTPS on Real-Time Box ?







# Thank You !

#### References

http://portals.omg.org/dds/sites/default/files/DDS\_Tutorial\_RT\_Worskshop\_2010.pdf



Real Time Control Workshop, 4-5 Dec 2012