The challenge of highly curved monolithic imaging detectors





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ABSTRACT

Current assemblies of image sensors and optics rely on the optics to project a corrected image onto a flat detector surface. In the optical design study of instrumentation for the European Extremely Large Telescope (E-ELT) it was determined that a significant simplification of the optical design - accompanied by an improvement of the image quality - could be achieved through the application of large format (90 mm square) concave curved detectors, with a low radius of curvature (500 - 250 mm). The poster summarizes important developments in the area of curved detectors in the past, their different approaches and ESO's specifications for an on-going feasibility study.

1. NEED A BETTER DETECTOR? **EVOLUTION OF NATURE STILL BEATS TECHNOLOGY**

most of them are routinely used - except the curvature of the retina.

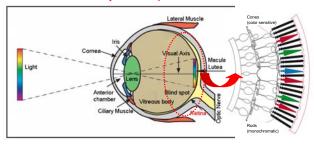


Figure 1: Picture of a human eyeball (left) and detail of its curved retina (right) [1]

2. WHY A CURVED DETECTOR FOR E-ELT?

Figure 2 shows a typical optical design under study for E-ELT instrumentation – comparing a curved and a flat detector. The correction of the field curvature is a major problem for fast cameras with large field of view. The combination of diverging and converging elements leads to very high incident angles on some optical surfaces. Very often vignetting has to be introduced to limit this effect.

A curved monolithic detector with 90 x 90 mm with curvature radius of 310 mm, would enable to:

- Design a very fast camera of F 1.5 with fewer optical elements, herewith increasing the throughput by ~15 %
- Eliminate the vignetting and optimize the image quality through fewer optical elements and fewer air / glass surfaces
- Eliminate field flattening elements, necessitating to introduce other lenses for their correction
- · Introduce cost savings on the optics side

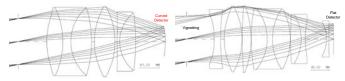


Figure 2: Comparison of optical design with curved detector (left) and flat detector (right) and optical characteristics (below)

Optical characteristics (both cameras): 300 mm F/Number: 1.50 il diameter: 200 mm Entrance pupil lo Angular field of view: 25 ° Detector: up to 100 x 100 mm

3. PUBLISHED TECHNIQUES FOR CURVED DETECTORS FILL FACTOR << 100 %:

- Rogers et al [2] developed a CMOS detector (silicon) on a curved rubber substrate, mainly for applications of artificial seeing (figure 3).
 Several mosaics of CCDs have been assembled on a curved substrate (figure 4).

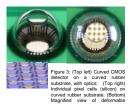




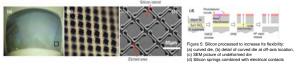
Figure 4: Image of Kepler focal plane, employing a CCD

4. PUBLISHED TECHNIQUES FOR CURVED DETECTORS FILL FACTOR 100 %: Curving silicon, processing silicon

Jin [4] & Buchhoeft [5] describe techniques to first curve the silicon on a spherically curved glass substrate and then deposit the imager structures via soft lithography. To date no results of this approach are known to produce a working test imager with fill factor 100%.

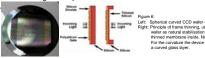
5. PUBLISHED TECHNIQUES FOR CURVED DETECTORS FILL FACTOR = 100 %: Flat silicon processing, thinning, curving

I. Rim & Peumanns [6],[7] (figure 5): The silicon is structured such as to introduce silicon springs between individual pixels islands, increasing its flexibility. Due to these structures this technology is better suitable for backside illuminated CMOS detectors. Curved silicon (without detector) has been produced with size 1cm x 1cm and curvature radius 1cm.



All following techniques deposit first a CCD on flat silicon, then thin it with different backside thinning technologies in order to curve it :

II. Sarnoff process [8]: Figure 6 shows frame thinning at wafer scale without substrate, then bending the center 10..30 µm membrane. Advantages: Handling through monolithic frame, stressfree wet etching. The produced device with curvature radius ~ 500 mm was



III. Lesser process [9]: Figure 7 shows the basic thinning sequence used by M. Lesser A keypoint for curving the device is the optimum thickness of the substrate supported device.



IV. JPL process [10]:

Curved test devices (mainly cylindrical) have been produced:

a.) Standard silicon: Similar to the Lesser process, but: Polishing the thick wafer into using a <u>removable</u> substrate, enabling to handle curved shape from backside, & curve the unsupported detector membrane. applying JPL MBE delta doping process.

b.) Thick fully depleted silicon: JPL MBE delta doping

6. ESO'S SPECIFICATION & FEASIBILITY STUDY

- ESO has a long term interest in curved large monolithic detectors for E-ELT.
- ESO's specification for curved detectors aims at 90 mm x 90 mm size.
- It concentrates currently onto a feasibility study.
- The latter leaves freedom for demonstration samples of smaller size, but focuses onto the final radius of curvature between 500 and 250 mm (figure 8).

Figure 8: Figure 8: Curved model of 90 x 90 mm detector with curvature radius 500 mm (left), respectively 250 mm

7. STATUS / NEXT STEPS OF ESO FEASIBILITY STUDY

- · Simulation of spectral extraction shows a good match between flat & curved detectors.
- August 09: Draft Specification was sent out to a wide variety of companies and research institutions
- Ongoing: Informal discussions with potential partners to define feasibility of study / scope of work and ROM cost per phase

 • Q4/2009 Update of specifications, Q1/2010 Formal call for tender procedure

8. IS IT FEASIBLE ?: OPEN ITEMS...

- Is an existing detector construction feasible for curving ?
- How well will an existing detector perform after bending (fields, shift charge, noise..)? • Will the optical PSF be as before ?
- Which features will the crystal structure exhibit after bending (increased dark) current / defects) ?
- What is the most promising approach to curve thinned silicon (supported / unsupported) ?
- What is the optimum thickness before curving the (thinned) detector?
- Is backside thinning really a requirement for curved silicon?
- How well is the curving process scaleable after testing small samples (at identical radius) of curvature)?

9. CONTACT

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10. REFERENCES